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Predicting transition ranges to turbulent viscous boundary layers in low Prandtl number convection flows

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We discuss two aspects of turbulent Rayleigh-Bénard convection (RBC) on the basis of highresolution direct numerical simulations in a unique setting; a closed cylindrical cell of aspect ratio of one. First, we present a comprehensive comparison of statistical quantities such as energy dissipation rates and boundary layer thickness scales. Data are used from three simulation run series at Prandtl numbers Pr that cover two orders of magnitude. In contrast to most previous studies in RBC the focus of the present work is on convective turbulence at very low Prandtl numbers including Pr = 0.021 for liquid mercury or gallium and Pr = 0.005 for liquid sodium. In this parameter range of RBC, inertial effects cause a dominating turbulent momentum transport that is in line with highly intermittent fluid turbulence both in the bulk and in the boundary layers and thus should be able to trigger a transition to the fully turbulent boundary layers of the ultimate regime of convection for higher Rayleigh number. Secondly, we predict the ranges of Rayleigh numbers for which the viscous boundary layer will transition to turbulence and the flow as a whole will cross over into the ultimate regime. These transition ranges are obtained by extrapolation from our simulation data. The extrapolation methods are based on the large-scale properties of the velocity profile. Two of the three methods predict similar ranges for the transition to ultimate convection when their uncertainties are taken into account. All three extrapolation methods indicate that the range of critical Rayleigh numbers Ra_c is shifted to smaller magnitudes as the Prandtl number becomes smaller.

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I. INTRODUCTION

The structure and dynamics of the viscous and thermal boundary layers near the cooled and heated plates in thermal convection flow is significantly altered by the dimensionless Prandtl number $Pr \equiv \nu/\kappa$ of the working fluid [1, 2]. For very low Prandtl numbers, momentum diffusion, with the kinematic viscosity ν being the diffusion constant, is much smaller than temperature diffusion measured by the constant κ . Thus the thermal boundary layer is much thicker than the viscous one. This regime is of particular interest in geo- and astrophysical convection flows. Around the solid inner core of the Earth, which is mostly an iron-nickel alloy, a liquid outer core exists that is composed of molten metals at high pressure and $Pr \sim 10^{-1}$ [3]. In solar and stellar convection the heat transport is supported by radiative processes resulting in enhanced temperature diffusion and thus Prandtl numbers $Pr \leq 10^{-3}$ in the Sun [4, 5] or $Pr \leq 10^{-8}$ in stars [6–8]. The majority of numerical studies of these convection flows operate at Prandtl (or turbulent Prandtl) numbers $Pr \sim 0.1$ to 1 in order to incorporate further physical processes of strong rotation and compressibility or magnetic fields into the (spherical) models [4, 9]. Direct numerical simulations studies of turbulent convection below $Pr \leq 0.01$ are thus very rare. Low-Prandtl-number convection is also related to new methods of energy harvesting in liquid metal batteries at $Pr \sim 10^{-2}$ [10–12]. In contrast, the thermal boundary layer is well embedded inside the viscous boundary layer for very large Prandtl number where temperature diffusion is much smaller than momentum diffusion.

This large difference in the thicknesses of both interacting boundary layers has implications on the near-wall dynamics and eventually on a transition to turbulence inside these boundary layers as discussed first by Kraichnan [13] in his landmark work. When the Rayleigh numbers are sufficiently large at a given Prandtl number, near-wall coherent structures, such as thermal plumes for the temperature field and streamwise vortices for the velocity field, trigger turbulent fluctuations of both fields and change the character of the boundary layers into a transitional one. Eventually these fluctuations fill the whole boundary layer region and the boundary layers are in a fully developed turbulent state. This transition to turbulence can be expected to proceed in a different way than in a standard isothermal channel flow or flat plate boundary layer [14, 15] for the following two reasons:

(i) In Rayleigh-Bénard convection (RBC) flows a well-defined canonical mean flow is missing, in particular in closed rectangular or cylindrical convection cells as used in all laboratory experiments. The mean flow consists then of a large-scale circulation (LSC) in form of a roll that breaks the symmetry and shows a complicated temporal sloshing and oscillation dynamics [16–18]. The LSC divides the boundary plates at the top and bottom into three regions, an impact region, a high-shear central region and an ejection region at approximately the diametral side of the impact region (see Fig. 1 for this cylindrical geometry). This dynamics can be partly compensated by a rotation of the coordinate frame into the instantaneous direction of this large-scale circulation flow, plane by plane starting from the wall [19]. In this way a classical Reynolds-like decomposition of the turbulent fields is again possible when the analysis is restricted to the central region.

(ii) The temperature field is an active scalar. Therefore thermal plumes (which are unstable fragments of the thermal boundary layer that detach from the wall) will affect the fluid motion and enhance the velocity field fluctuations. Since



FIG. 1: Snapshot of the boundary layer structure for $Ra = 10^7$ and Pr = 0.005. We display the field lines of the skin friction field $s_i = \partial u_i / \partial x_3$ at $x_3 = 0$ with i = 1, 2 in yellow. They provide a two-dimensional blueprint of the velocity field near the plate. Colored contours correspond to the magnitude of the vorticity component $\omega_3 = \epsilon_{3jk} \partial u_k / \partial x_j$ (with j, k = 1, 2) taken in a horizontal plane at z = 0.0034 which corresponds to $2\delta_u$ (see eq. (9)). The magnitude of ω_3 is indicated by the colorbar. The three main regions of the boundary layer are also indicated. View is from above the boundary layer.

these plume ridges have a typical cross section that corresponds to the thermal boundary layer thickness, for $Pr \gg 1$ these structures should have a small impact on the near-wall flow. Low Prandtl number convection is characterized by fast diffusion time scales (since $\tau_d \sim \sqrt{RaPr}$) and much coarser plume structures. These plume structures turn out to be very efficient drivers of fluid turbulence in the convection flow [20] and therefore convective turbulence at very low Prandtl number is dominated by inertial fluid motion. Thus convective turbulence at low Prandtl numbers can be expected to be susceptible to turbulence transitions in the boundary layers at lower Rayleigh numbers than a higher-Prandtl number flow.

With these two points in mind, in this paper we will discuss the boundary layer dynamics for $5 \times 10^{-3} \leq Pr \leq 7 \times 10^{-1}$ with a focus on the much less explored parameter regime of smaller Prandtl numbers. We have a comprehensive set of high-resolution direct numerical simulation (DNS) of three-dimensional turbulent convection flows, all obtained in exactly the same geometry, a closed cylindrical cell at aspect ratio $\Gamma = 1$, i.e., cell diameter D equals cell height H. The data consist of three series of Prandtl numbers Pr = 0.7 for air, Pr = 0.021 for mercury and Pr = 0.005 for liquid sodium, the latter of which corresponds to the smallest value that can be obtained in controlled laboratory experiments. In the case of liquid sodium, our largest Rayleigh number value of $Ra = 10^7$ exceeds those that have been obtained in the experiments [21] for cells with $\Gamma \gtrsim 1$. The situation is different for convection in mercury at Pr = 0.021 where Rayleigh numbers up to $Ra = 10^{11}$ have been obtained in laboratory experiments which are not accessible in DNS. These high Rayleigh numbers correspond to Reynolds numbers of the turbulent flow of $Re \sim 10^6$ [22].

Our study summarizes global measures of transport of heat and momentum as well as dissipation. We discuss trends of characteristic boundary layer scales with respect to Rayleigh number and compare different spatial intermittency measures of the velocity boundary layer. These measures require the evaluation of velocity and temperature derivatives inside the boundary layers which are not accessible in laboratory experiments, in particular for larger Rayleigh numbers. Their extrapolation to higher Rayleigh numbers allows us to predict a range of Rayleigh numbers beyond which the transition to turbulent boundary layers might be present and convection crosses over into Kraichnan's ultimate regime [13]. This transition is expected to be subcritical just as for isothermal boundary layers and thus a range of Rayleigh numbers for the transition can be expected rather than a sharp threshold [14]. Our ranges of Rayleigh numbers follow, however, from the uncertainty of the extrapolation. We discuss the numerical method in the next section. This is followed by our analysis of global transport and of boundary layer scalings. We then summarize our results and discuss possible future directions.

II. SIMULATIONS

We solve the three-dimensional equations of motion in the Boussinesq approximation. They couple the velocity field $u_i(x_j, t)$ with the temperature $T(x_j, t)$. The indices i, j, k = 1, 2, 3, and the Einstein summation convention will be used in this work. The equations are made dimensionless by using height of the cell H, the free-fall velocity $U_f = \sqrt{g\alpha\Delta TH}$

 10^{-1} 10^{-1} 10^{-2} 10^{-3} 10^{-6} 10^{-8} 10^{10} Ra

FIG. 2: Simulation data record plotted in the parameter plane which is spanned by Ra and Pr. The blue shaded area of the parameter plane for Pr > 0.16 is accessible for gases and/or binary gas mixtures [26]. The red shaded areas indicate the range of Rayleigh numbers which are covered by laboratory experiments in cases of liquid mercury and liquid sodium for cells with $\Gamma \sim 1$. These are the experiments by Glazier et al. [22] up to $Ra = 8 \times 10^{10}$ for mercury and Horanyi et al. [21] up to $Ra = 5 \times 10^6$ for sodium. Three of our simulations are on a line of constant Grashof number Gr = Ra/Pr which has been discussed in [20]. The constant Gr data points are connected by the inclined red line. A summary of further low-Prandtl-number experiments is found in [25].

and the imposed temperature difference ΔT . The equations contain the three control parameters: the Rayleigh number Ra, the Prandtl number Pr and the aspect ratio $\Gamma = D/H = 1$ with the cell diameter D. The equations are given by

$$\frac{\partial u_i}{\partial x_i} = 0, \qquad (1)$$

$$\frac{\partial u_i}{\partial t} + u_j \frac{\partial u_i}{\partial x_j} = -\frac{\partial p}{\partial x_i} + \sqrt{\frac{Pr}{Ra}} \frac{\partial^2 u_i}{\partial x_j^2} + T\delta_{i3}, \qquad (2)$$

$$\frac{\partial T}{\partial t} + u_j \frac{\partial T}{\partial x_j} = \frac{1}{\sqrt{RaPr}} \frac{\partial^2 T}{\partial x_j^2},\tag{3}$$

where

$$Ra = \frac{g\alpha\Delta TH^3}{\nu\kappa}, \qquad Pr = \frac{\nu}{\kappa}.$$
(4)

The variable g stands for the acceleration due to gravity, α is the thermal expansion coefficient, ν is the kinematic viscosity, and κ is thermal diffusivity. No-slip boundary conditions for the fluid are applied at all walls. The side walls are thermally insulated and the top and bottom plates are held at constant dimensionless temperatures T = 0 and 1, respectively.

The equations are numerically solved by the Nek5000 spectral element method package which has been adapted to our problem [23, 24]. The cylindrical cell is composed of spectral elements. On each element, the turbulent fields are expanded in Lagrangian interpolation polynomials of order N in each space direction. This sums up to more than 6 million spectral elements and approximately 10 billion mesh cells (see Tab. I) which require more than half a million Message Passing Interface tasks at the Blue Gene/Q supercomputers JUQUEEN in Jülich (Germany) and Mira at Argonne National Laboratory (USA). As seen in the table, a particular challenge are the largest Rayleigh number runs at the lowest Prandtl number which require small integration time steps due to the high diffusivity of the temperature field. For example, run 19 consumed 22 million processor core hours for runs with 131,072 Message Passing Interface tasks while advancing for 11 free-fall times T_f . It is clear that a longer time series would be desirable.

Fig. 2 summarizes all simulation data sets and relates them to ranges of Rayleigh numbers that have been reached in the laboratory in a comparable geometry and Prandtl number. The figure displays also the range of Prandtl numbers that are accessible to gases and binary gas mixtures and thus to optical imaging technology.

Run	Pr	Ra	N_e	N	N_{bl}	Nu	Re	Re_{τ}	Snapshots	Runtime
1	0.7	3×10^5	3,520	11	27	5.80 ± 0.03	116 ± 1	_	401	695
2	0.7	5×10^5	3,520	11	24	6.90 ± 0.13	151 ± 2	_	401	682
3	0.7	7×10^5	3,520	11	20	7.78 ± 0.05	179 ± 1	_	407	682
4	0.7	10^{6}	30,720	7	25	8.65 ± 0.06	214 ± 6	5	300	542
5	0.7	5×10^6	30,720	7	17	13.79 ± 0.17	483 ± 1	7	340	459
6	0.7	10^{7}	30,720	11	21	16.77 ± 0.01	675 ± 3	8	230	177
7	0.7	5×10^7	30,720	13	18	25.8 ± 0.3	$1,490\pm40$	12	192	93
8	0.7	10^{8}	256,000	11	27	31.4 ± 1.3	$2,070\pm60$	14	84	79
9	0.7	10^{9}	$875,\!520$	11	18	63 ± 4	$6,240\pm140$	24	92	72
10	0.7	10^{10}	$2,\!374,\!400$	9	8	127 ± 6	$19,300\pm900$	48	41	48
11	0.021	3×10^5	256,000	7	54	4.29 ± 0.12	$1,830\pm30$	18	68	92
12	0.021	10^{6}	256,000	9	48	5.43 ± 0.03	$3,030\pm40$	24	150	131
13	0.021	10^{7}	$875,\!520$	11	26	10.11 ± 0.05	$8,450\pm100$	35	206	29
*14	0.021	10^{8}	$2,\!374,\!400$	13	18	19.1 ± 1.3	$22,900\pm300$	48	27	12
*15	0.021	4×10^8	$6,\!272,\!000$	11	42	30.8 ± 1.7	$46,000\pm600$	76	75	6
16	0.005	3×10^5	256,000	9	43	3.26 ± 0.02	$4,620\pm20$	43	29	30
17	0.005	10^{6}	875520	9	39	4.45 ± 0.07	$8,290\pm40$	49	63	39
18	0.005	2.38×10^6	$2,\!374,\!400$	11	30	5.66 ± 0.09	$12,800\pm120$	65	25	8
*19	0.005	10^{7}	$5,\!644,\!800$	9	148	8.0 ± 0.7	$20,800\pm160$	54	19	11

TABLE I: Parameters of the different spectral element simulations. We display the Prandtl number Pr, the Rayleigh number Ra, the number of spectral elements N_e , the polynomial order of the expansion in each of the three space directions, the number of mesh cells inside the thermal boundary layer N_{bl} , the Nusselt number Nu, the Reynolds number Re, the friction Reynolds number Re_{τ} the number of statistically independent snapshots, and the total runtime in units of the free-fall time $T_f = H/U_f$. The runs with one asterisk are either new or have been run for a longer time to gather a better statistics in comparison to [19, 25].



FIG. 3: Global turbulent transport and dissipation laws versus Rayleigh number. Left: Scaling laws of turbulent heat transfer, Nu(Ra), for the three series of DNS. The inset compensates all plots with respect to the scaling exponent for convection in air. Middle: Scaling laws of turbulent momentum transfer, Re(Ra). The inset replots data and compensates the series with respect to the scaling for convection in air. Right: Skin friction coefficient c_{τ} determined over the inner plate section with $r \leq 0.3$ denoted with an index b as a function of the Rayleigh number. Open circles correspond to Pr = 0.7, asterisks to Pr = 0.021 and filled diamonds to Pr = 0.005 in all panels.

III. GLOBAL TURBULENT TRANSPORT AND DISSIPATION

In response to the three input parameters Ra, Pr and Γ , turbulent heat and momentum fluxes are established in an RBC flow. The turbulent heat transport is determined by the dimensionless Nusselt number which is given by

$$Nu = 1 + \sqrt{RaPr} \langle u_3 T \rangle_{V,t} \,. \tag{5}$$

Expression $\langle \cdot \rangle_{V,t}$ stands for a combined volume and time average. The mean thickness of the thermal boundary layer is given by

$$\delta_T = \frac{1}{2Nu} \,. \tag{6}$$

The left panel of Fig. 3 summarizes the global turbulent transport laws of heat obtained for the three series of DNS. We fit the data to the following scaling laws:

$$Nu = \begin{cases} (0.13 \pm 0.02) Ra^{0.26 \pm 0.01} : Pr = 0.005\\ (0.13 \pm 0.04) Ra^{0.27 \pm 0.01} : Pr = 0.021\\ (0.15 \pm 0.01) Ra^{0.29 \pm 0.01} : Pr = 0.700 \end{cases}$$
(7)

A decrease of the scaling exponent from 0.29 for convection in air to 0.26 in sodium is observed. Theoretical predictions for the scaling exponents at different Prandtl numbers are found in the range between 1/3 and 1/4. The exponent of 1/3 would follow from a model that describes thermal boundary layers as being marginally stable, an idea which goes back to Malkus [27]. The scaling theory of Shraiman and Siggia [28] builds on a turbulent boundary layer and gives an exponent of 2/7 for Pr > 1. Our exponent of 0.29 for Pr = 0.7 is consistent with the Grossmann-Lohse theory that however predicts no pure algebraic scaling [1, 29]. An exponent of 1/4 follows from a joint balancing of inertial and buoyancy term in the momentum balance together with a balance of advection and diffusion terms in the advectiondiffusion equation for temperature [30]. It is also the result of an asymptotic model for steady inertial convection in two dimensions by Busse and Clever which is formulated for the limit of very small Prandtl numbers [31]. In both models [30, 31] of low-Prandtl convection, it is assumed that the fluid turbulence is highly inertial. The compensated plots in the insets of both panels show that this scaling is not perfect, as it has been found in many other studies of thermal convection. When the data of run 19 are excluded from the fit, the exponent for the sodium series becomes 0.265 \pm 0.01 as given in [25]. The exponents are found in the same range as laboratory experiments in air [2] and in mercury or gallium [22, 32, 33] as well as in sodium [21].

The turbulent momentum transport is expressed by the Reynolds number Re which is defined as

$$Re = u_{rms} \sqrt{\frac{Ra}{Pr}}$$
 with $u_{rms} = \sqrt{\langle u_i^2 \rangle_{V,t}}$, (8)

The mean thickness of the viscous boundary layer is frequently given by Blasius-type relation

$$\delta_u = \frac{a}{\sqrt{Re}} \,, \tag{9}$$

where a < 1 is a free parameter (here a = 1/4 as in [34]). The following scaling laws can be derived from our data (see mid panel of Fig. 3):

$$Re = \begin{cases} (21 \pm 9)Ra^{0.43 \pm 0.03} & : Pr = 0.005\\ (6.5 \pm 0.6)Ra^{0.45 \pm 0.01} & : Pr = 0.021\\ (0.24 \pm 0.01)Ra^{0.49 \pm 0.01} & : Pr = 0.700 \end{cases}$$
(10)

Again, the trend is very systematic with an exponent that decreases for decreasing Prandtl number and with a prefactor that is systematically enhanced confirming the high level of developed fluid turbulence in the cell. If we exclude run 19 from the fit to the data for the series of convection in sodium, an exponent of 0.49 ± 0.01 would follow [25]. For the turbulent momentum transfer fewer (direct) measurements are available. In nearly all cases the temperature signal is used to determine a Reynolds number on the basis of a characteristic frequency, e.g. in Ref. [35]. Our scaling exponent for mercury agrees with the experiments [35] as does that for air [36].

Finally it is worth noting that we observe fairly constant slopes for all Reynolds versus Rayleigh data the mid panel of Fig. 3, and particularly for Pr=0.7 which covers Reynolds numbers that span two orders of magnitude. For all Re the bulk flow is turbulent, and the boundary layer that can be characterized by an increasing level of turbulent fluctuations as Ra increases, but is still always below the transition to a fully turbulent boundary layer.

Most of the kinetic energy is dissipated in the boundary layers. A global measure of the dissipative losses in shear flows is the skin-friction coefficient (see e.g. [37]) which is given in the present flow [25] in dimensionless form by

$$c_{\tau} = \frac{2\langle \tau_w \rangle_{b,t}}{u_{rms}^2} \,. \tag{11}$$

Here, $\langle \tau_w \rangle_{b,t}$ is the mean wall shear stress. This stress field is connected with the friction velocity u_{τ} via $\langle \tau_w \rangle_{b,t} = u_{\tau}^2$. Following [19], the friction velocity is given by

$$u_{\tau}(x_3 = 0) = \sqrt[4]{\frac{Pr}{Ra}} \left\langle \left(\left\langle \frac{\partial u_i}{\partial x_3} \right\rangle_b^2 \right)^{\frac{1}{4}} \right\rangle_t,$$
(12)



FIG. 4: Snapshots of the temperature field in the top row and of the wall shear stress field in the bottom row. (a,d) Run 19 at $Ra = 10^7$ and Pr = 0.005. (b,e) Run 14 at $Ra = 10^8$ and Pr = 0.021. (c,f) Run 10 at $Ra = 10^{10}$ and Pr = 0.7. All three runs have a comparable Reynolds number $Re \approx 2 \times 10^4$ as seen in Tab. I. The interior plate section is always highlighted. The corresponding color scales are the same in the three cases. The cross section planes for T are taken at $z = \delta_T/2$ with $\delta_T = 1/(2Nu)$ being the thermal boundary layer thickness. The ratio of the thicknesses is approximately 1 : 7 : 16 when convection in sodium, mercury, and air are compared. The instantaneous wall shear stress field can be derived from Eqns. (11) and (12) as $\tau_w(x_1, x_2) = Gr^{-1/2}|\partial_3 u_i|$ with Grashof number Gr = Ra/Pr and summation over i = 1, 2. View is from below in all figures.

with i = 1, 2. Fig. 3 (right) summarizes the results for c_{τ} for all simulation data. The following algebraic power laws have been fitted to the recent data sets.

$$c_{\tau} = \begin{cases} (0.2 \pm 0.1)Ra^{-0.12 \pm 0.05} : Pr = 0.005\\ (0.7 \pm 0.2)Ra^{-0.18 \pm 0.02} : Pr = 0.021\\ (10 \pm 1)Ra^{-0.26 \pm 0.01} : Pr = 0.700 \end{cases}$$
(13)

Note that this calculation method differs from the one in [25] which alters the scaling laws slightly. Without run 19 the power law fit for the series at Pr = 0.005 is $c_{\tau} = (0.78 \pm 0.01)Ra^{-0.23\pm0.01}$. We have chosen the present method in order to conduct the analysis consistently with the subsequent sections where the logarithmic law of the wall will be discussed. While a laminar isothermal flat plate boundary layer would approximately scale as $c_{\tau} \sim Ra^{-1/4}$, a turbulent boundary layer would follow $c_{\tau} \sim Ra^{-1/10}$ for larger Reynolds numbers if we simply translate $Re \sim \sqrt{Ra}$ [37]. We observe that the magnitude of the scaling exponent for air coincides with the one for a laminar boundary layer and that this exponent increases for sodium to almost a fully turbulent boundary layer scaling. This crossover is caused by the increasing discrepancy between the thicknesses of thermal and viscous boundary layers as Pr falls and the fact that the temperature is an active scalar that affects the fluid motion near the walls. In Fig. 4, we plot three horizontal cuts well inside the corresponding thermal boundary layer for runs 10, 14 and 19. All three simulations result in a comparable $Re \approx 20,000$. Bright contours stand for the detachment zones of thermal plumes. Coarse temperature field contours (see left panel for sodium) are then in line with regions across which wall shear stress filaments vary only moderately. This can be seen in the bottom row of the same figure. The region containing detaching plumes is largest in the sodium case and results in a reduced drop in the friction coefficient with respect to Ra.

Another global dissipation measure is the volume mean of the kinetic energy dissipation rate. The corresponding



FIG. 5: Mean kinetic energy dissipation rate as a function of the Rayleigh and Prandtl numbers. Left: Mean kinetic energy dissipation rate $\langle \epsilon \rangle_{V,t}$ obtained in the full cylinder volume V. The scaling laws that were fitted to the data results in the following scaling exponents: -0.20 ± 0.01 for Pr = 0.7 (open circles), -0.20 ± 0.01 for Pr = 0.021 (asterisks) and -0.21 ± 0.03 for Pr = 0.005 (diamonds). Middle: Mean dissipation rates in a subvolume V_b centered in the bulk away from all walls, $\langle \epsilon \rangle_{V_b,t}$. This results in the following scaling exponents: -0.19 ± 0.01 for Pr = 0.7 (open circles), -0.15 ± 0.05 for Pr = 0.021 (asterisks) and -0.03 ± 0.08 for Pr = 0.005 (diamonds). Without run 19 the exponent is -0.19 ± 0.02 for Pr = 0.005. The subvolume in the bulk takes 22% of the total cell volume. Right: Replot of the mean kinetic energy dissipation rates in the bulk in versus Reynolds number to demonstrate ansatz (16).



FIG. 6: Ratio of mean boundary layer thicknesses δ_u/δ_T versus Rayleigh number Ra. Symbols are given in the legend.

field is defined as

$$\epsilon(x_k, t) = \frac{1}{2} \sqrt{\frac{Pr}{Ra}} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)^2 \,. \tag{14}$$

The kinetic energy balance in a statistically stationary regime gives rise to an exact relation for the mean kinetic energy dissipation rate [24]

$$\langle \epsilon \rangle_{V,t} = \frac{Nu - 1}{\sqrt{RaPr}} \,. \tag{15}$$

In Fig. 5(a), we plot the mean kinetic energy dissipation rate for the three DNS data series obtained from a full volume and time average of Eqn. (14). It is observed that the power law exponent of the scaling of the dissipation rate with respect to Rayleigh number is about the same for all series and varies between 0.20 and 0.21. At a given Ra, the magnitude of mean kinetic energy energy dissipation is enhanced as Pr decreases which is in line with a growing relevance of the inertial effects of the fluid turbulence. Following Grossmann and Lohse [38], we decompose the mean kinetic energy dissipation rate into a boundary layer (bl) and bulk (bu) contribution. Dimensional analysis gives the following Reynolds number dependencies of both contributions of the mean dissipation rate with a physical dimension that is indicated here with a tilde

$$\langle \tilde{\epsilon} \rangle_{V,t} = \langle \tilde{\epsilon}_{bl} \rangle_{V,t} + \langle \tilde{\epsilon}_{bu} \rangle_{V,t} = c_1 \frac{\nu^3}{H^4} R e^{\frac{5}{2}} + c_2 \frac{\nu^3}{H^4} R e^3.$$
(16)

In Fig. 5(b) the mean kinetic energy dissipation rate in the bulk of the cell is displayed. The combined volume-time average is taken in a cylindrical subvolume V_b in the center of cell that occupies about 22% of the total volume V and

is sufficiently far away from all boundary layers for all Ra and Pr, including those at the sidewalls. It is seen that the dissipation rate magnitude is significantly smaller in the bulk, by a factor of two or larger. The magnitude of the power law exponents that were fitted to the data are slightly smaller and decrease with decreasing Pr. If we take the Reynolds number based on the free-fall velocity, $Re_f = U_f H/\nu = \sqrt{Ra/Pr}$, eq. (16) translates to

$$\frac{\langle \epsilon \rangle_{V,t}}{\sqrt{(Pr/Ra)^3}} = c_1 R e^{\frac{5}{2}} + c_2 R e^3.$$
(17)

Figure 5(c) replots the mean dissipation rates in the bulk in correspondence with eq. (17) and reproduces a cubic scaling with the Reynolds number that is taken from Tab. I.

Following from Tab. II of Ahlers et al. [1], our data correspond to regime II_{ℓ} for which kinetic energy dissipation in the bulk and thermal dissipation in the boundary layer dominate, respectively. In this regime, pure scaling laws $Nu \sim Ra^{1/5}Pr^{1/5}$ and $Re \sim Ra^{-2/5}Pr^{-3/5}$ would follow. Our series for the lower Pr trends towards this scaling.

Is is also interesting to plot the ratio of the viscous and thermal boundary layer thicknesses here, which is displayed in Fig. 6. The ratio is smaller than one for all runs displayed. There is, however, a fairly significant decrease in the ratio as Prandtl number decreases. The resulting scaling with respect to Rayleigh number is a consequence of the obtained scaling laws Nu(Ra, Pr) and Re(Ra, Pr) in combination with the definitions (6) and (9). The scaling exponent of the thickness ratio remains thus nearly unchanged for decreasing Prandtl number. This is a consequence of the fact that the Nusselt and Reynolds scaling exponents both decrease in magnitude as Prandtl number decreases (see also eqns. (7) and (10)). For other definitions of thermal and viscous boundary layer thicknesses, and a more systematic comparison for Rayleigh and Prandtl numbers, see also refs. [25, 49].

IV. TRANSITION TO TURBULENCE IN THE VISCOUS BOUNDARY LAYER

A. Method I: Friction Reynolds number from logarithmic law of wall

In ref. [19], we showed that the viscous boundary layer is characterized by a favorable pressure gradient which is connected with the LSC flow in the cell. Since this LSC is twisted and obeys a complicated three-dimensional dynamics, in particular an ongoing change of the orientation, a rotation of the frame of reference into the mean orientation of the LSC at each plane of constant x_3 was suggested. This plane-by-plane rotation, which is done for each snapshot separately, removes the interior twist of the roll, by compensating for the orientation changes and allows us to define streamwise and spanwise directions similar to plane wall-bounded shear flows. Details of the transformation can be found in the appendix. Together with the transformation $\hat{x}_i = R_{ij}x_j$, a corresponding transformation for the velocity components is given as $\hat{u}_i = R_{ij}u_j$.

Based on the friction velocity (12), we define an inner viscous scale by

$$\ell_{\tau} = \sqrt{\frac{Pr}{Ra}} u_{\tau}^{-1} \,. \tag{18}$$

Thus $\hat{u}_i^+ = \hat{u}_i/u_{\tau}$ and $\hat{x}_i^+ = \hat{x}_i/\ell_{\tau}$. Note that for Figs. 7 and 10, the instantaneous profiles for \hat{u}_i^+ versus \hat{x}_i^+ are first found by dividing \hat{u}_i by the instantaneous u_{τ} and \hat{x}_i by the instantaneous ℓ_{τ} . Then these profiles are time averaged (see [19] for more details). We can now define a friction Reynolds number as $Re_{\tau} = \tilde{u}_{\tau} \tilde{\delta}_* / \tilde{\nu}$. In dimensionless form this translates to

$$Re_{\tau} = u_{\tau}\delta_* \sqrt{\frac{Ra}{Pr}}.$$
(19)

The relevant length scale used here is the x_3 coordinate of the maximum of the time-averaged velocity profile which is denoted as δ_* . Thus Re_{τ} differs from the typical definition in a turbulent channel flow (CF) where the half width of the channel is taken as the characteristic scale. Fig. 7 shows the mean streamwise velocity profile obtained for the interior plate sections at the top and bottom. The linear relation and the von Kármán law are also indicated together with a CF Benchmark case for a turbulent boundary layer at $Re_{\tau} = 180$ [39]. The RBC flow results in a friction Reynolds number of $Re_{\tau} = 48$. The bottom figure replots data on doubly linear axes. For all RBC data sets, the shape of the mean profile is qualitatively the same. In contrast to a pressure-driven CF, the profile passes through a maximum at $\hat{x}_3 = \delta_*$ and decreases to a bulk plateau afterwards. The behavior is thus closer to a turbulent plane wall jet as discussed for example by George et al. [40].

This calls for a closer inspection. Figure 8 shows typical vertical cuts through the near-wall flow region where we display the velocity field in a plane along the y-axis (run 19 at the top and run 14 at the bottom of the figure). In both instances the flow direction is from left to right in the interior section which is indicated by the red double-headed arrow. The thickness of the BL varies significantly along the downstream direction, and this is caused by detaching plumes and downwelling from the vigorous bulk turbulence. These processes will prohibit any self-similar downstream evolution as it is known from evolving turbulent plane wall jets [40]. We have tried without success to collapse the data after re-scaling by δ_* and the mean streamwise velocity maximum.



FIG. 7: Mean streamwise velocity profile for a turbulent RBC flow (run 14). Top: Plot of the data in inner wall units for comparison with the logarithmic law of the wall for a turbulent channel flow [39] at $Re_{\tau} = 180$. Profiles have to intersect $(\hat{x}_3^+, \hat{u}_1^+) = (1, 1)$ which is indicated by solid gray lines. The dashed vertical line at $\hat{x}_3^+ = 5$ separates viscous sublayer and buffer layer, the dashed line at $\hat{x}_3^+ = 30$ separates the buffer and logarithmic layer. The linear law $\hat{u}_1^+ = \hat{x}_3^+$ and the von Kármán law $\hat{u}_1^+ = k^{-1} \log \hat{x}_3^+ + B$ with the constant k = 0.4 and B = 5.5 are indicated as solid red lines. Bottom: Replot of the data in a double linear plot, but with the x-axis as \hat{x}_3 . The dashed vertical line indicates now the thermal boundary layer thickness which is given by $\delta_T = 1/(2Nu)$.



FIG. 8: Velocity field snapshots inside the thermal boundary layer for runs 14 (bottom) and 19 (top). Vertical cuts are taken along the x-axis in the top panel and along the y-axis in the bottom panel. All arrows are normalized to one such that only the flow direction is indicated. The background color stands for the three-dimensional velocity magnitude $u = (u_i^2)^{1/2}$. Colors range from u = 0 (white) to u = 0.5 (deep blue). Note the real aspect ratio of this cut is 167:1 and that the viscous boundary layer thickness is about 1/3 of the displayed height in both cases. We also indicate the interior section b that is taken for most of the present boundary layer analysis.

Fig. 9 shows the resulting friction Reynolds numbers versus Rayleigh number. The series for Pr = 0.021 and Pr = 0.7 follow a power law scaling. By means of an extrapolation one can now determine the range of critical Rayleigh numbers, $Ra_c^{(I)}$ for which $Re_\tau \approx 200$, i.e., the friction Reynolds number for which the boundary layers in a channel flow are fully turbulent [41, 42] and for which we would expect a transition into the ultimate convection regime in the present setup. This friction Reynolds number is reached in the series for convection in air for an intersection point of $Ra_c^{(I)}(Pr = 0.7) = 5 \times 10^{12}$, and a range of $10^{12} \leq Ra_c \leq 2 \times 10^{13}$ when the error bars of the power law fit to $Re_\tau(Ra)$ are incorporated. The upper boundary of this uncertainty range is consistent with the convection experiments of He *et al.* [43, 44]. In case of mercury, one obtains an intersection point of $Ra_c^{(I)}(Pr = 0.021) = 10^{11}$ and a range of $5 \times 10^9 \leq Ra_c \leq 4 \times 10^{12}$. Note that runs 14 and 15 have been run longer for the present analysis which caused a slightly modified range in comparison to Ref. [19]. The case of liquid sodium is more uncertain. If one includes only the first three data points in the least squares fit, an intersection point of $Ra_c^{(I)}(Pr = 0.005) = 10^9$ and a range of $10^{17} \leq Ra_c \leq 5 \times 10^{11}$ results. The scatter becomes even larger when the fourth data point of run 19 is incorporated.



FIG. 9: Friction Reynolds numbers versus Rayleigh number for three different Prandtl numbers. The horizontal dashed line marks $Re_{\tau} = 200$.



FIG. 10: Mean streamwise velocity profiles for different Prandtl and Rayleigh numbers (see Tab. I). The maxima $(\delta_*/\ell_\tau, \hat{u}_3^+(\delta_*/\ell_\tau))$ are indicated as stars. A power law fit to the successive maxima in each series is used to predict the intersection point of the logarithmic profiles with the von Kármán law. This intersection point is at $\hat{u}_1^+ = 134, 129, 83$ for Pr = 0.7, 0.021, 0.005, respectively. In all cases, the profiles taken from the top and bottom plates are included.

The extrapolations show that the crossover range is shifted towards smaller Rayleigh numbers as the Prandtl number decreases.

B. Method II: Extrapolation of velocity profile maximum

An alternative method is based on the maxima at $x_3 = \delta_*$ of the streamwise velocity profiles. In Fig. 10 we display all mean streamwise velocity profiles and indicate the maxima of the velocity profiles for each data set. A curve fit through the data is also drawn that intersects the law of the wall at a certain point. The curve fit is obtained as follows: We fit a power law to the maxima position, $\delta_*/\ell_\tau = C_1 \times Ra^{c_1}$. The procedure is repeated for $\hat{u}_3^+(\delta_*/\ell_\tau) = C_2 \times Ra^{c_2}$. The result is the parametric dashed curve that connects the maxima and can be extrapolated to higher Rayleigh numbers such that the intersection point with the von Kármán law and thus the corresponding Rayleigh number can be determined. With this procedure we obtain $Ra_c^{(II)}(Pr = 0.005) = 6 \times 10^8$ and an uncertainty range of $3 \times 10^6 \leq Ra_c \leq 10^{12}$ for convection in liquid sodium. In case of mercury, $Ra_c^{(II)}(Pr = 0.021) = 10^{10}$ and an uncertainty range of $5 \times 10^9 \leq Ra_c \leq 5 \times 10^{10}$ follows. For convection in air one obtains $Ra_c^{(II)}(Pr = 0.7) = 9 \times 10^{11}$ and an uncertainty range of $1 \times 10^{11} \leq Ra_c \leq 4 \times 10^{12}$. This method underestimates $Ra_c^{(II)}$ as is assumed that for this intersection point, the boundary layer is fully turbulent. However, it may be that the profile needs to overlap with the von Kármán law for a more substantial region for the boundary layer to be considered fully turbulent. It is seen, however, that the transition ranges of method II overlap significantly with those from method I. Again the uncertainty of the series with lowest Prandtl number is largest. The error bars of the power law fits results in the ranges for Ra_c . Nevertheless, method II is an appropriate complementary way to obtain transition ranges based on large-scale quantities such as mean profiles. For completeness we plot $\delta_*(Ra, Pr)$ in Fig. 11. While the data for Pr = 0.7 and 0.021 follow



FIG. 11: Distance of the mean streamwise velocity maximum from the wall, δ_* , as a function of Rayleigh and Prandtl number. Line styles agree with those from Fig. 9. The vertical lines (same linestyle as data) correspond to the critical Rayleigh numbers from Tab. II, method II.

be more of an outlier. More data at higher Ra and lower Pr would enable us to better understand this behavior.

C. Method III: Shape Factors

In refs. [45, 46], we obtained the temperature shape factors for Pr = 0.7 and Pr = 0.021. We refine this method and include the results for Pr = 0.005 here. Following Schlichting [37], we can define a displacement thickness as

$$d_u = \int_0^{\delta_{u_h}^*} \left(1 - \frac{\langle u_h(x_3) \rangle_{b,t}}{[\langle u_h \rangle_{b,t}]_{\max}} \right) dx_3 \tag{20}$$

where $\delta_{u_h}^*$ is the x₃-location of $[\langle u_h(x_3) \rangle_{b,t}]_{\text{max}}$. The variable $u_h = \sqrt{u_1^2 + u_2^2}$ is the rms horizontal velocity. Likewise we can define a displacement thickness for temperature as

$$d_T = \int_0^\infty \left(1 - \frac{\langle T(x_3) \rangle_{b,t}}{[\langle T \rangle_{b,t}]_{\text{mean}}} \right) dx_3 \tag{21}$$

where $[\langle T \rangle_{b,t}]_{\text{mean}}$ is the mean temperature in the bulk. Since the mean temperature profiles are typically not perfectly constant in the bulk (i.e. there tends to be a temperature gradient, which changes with Rayleigh and Prandtl number), we only integrate in practice out to 2.5 times the thermal boundary layer thickness, found here by the slope method. This is the same method used in [45]. In Fig. 12 these displacement thicknesses are plotted as a function of Rayleigh and Prandtl numbers. In the left panel, one sees that the thermal displacement thickness increases in magnitude as Prandtl number decreases, and that the scaling exponents systematically decrease, also as Prandtl number decreases. The opposite is found for the velocity displacement thickness: the magnitude is smaller and the exponent is larger as Prandtl number decreases. This trend is similar to what was found for the local method of finding boundary layer thicknesses as presented in Scheel and Schumacher [25], although the exact exponent values differ.

For a laminar boundary layer [47], it is expected that the displacement thickness falls off with Rayleigh number with an exponent of 1/4, but for a turbulent boundary layer this exponent decreases to 1/10. This displacement thickness analysis suggests that all of our boundary layers are closer to a laminar BL, with possibly a slight increase in intermittency as Prandtl number increases for the velocity boundary layer and the opposite trend for the thermal boundary layer.

A momentum thickness can also be defined for velocity

$$m_u = \int_0^{\delta_{u_h}^*} \left(1 - \frac{\langle u_h(x_3) \rangle_{b,t}}{\left[\langle u_h \rangle_{b,t} \right]_{\max}} \right) \left(\frac{\langle u_h(x_3) \rangle_{b,t}}{\left[\langle u_h \rangle_{b,t} \right]_{\max}} \right) dx_3$$
(22)

and temperature

$$m_T = \int_0^\infty \left(1 - \frac{\langle T(x_3) \rangle_{b,t}}{\left[\langle T \rangle_{b,t} \right]_{\text{mean}}} \right) \left(\frac{\langle T(x_3) \rangle_{b,t}}{\left[\langle T \rangle_{b,t} \right]_{\text{mean}}} \right) dx_3$$
(23)



FIG. 12: Displacement thicknesses d_T and d_u (found from Eqns. (21) and (20), respectively) as a function of Rayleigh and Prandtl number.



FIG. 13: Shape factors, H_T (left) and H_u (right) as defined in Eqn. (24) as a function of Rayleigh and Prandtl numbers. All horizontal lines are the shape factors for the Prandtl-Blasius case. For temperature, the shape factor H_T depends on Prandtl number: the dashed line is for Pr = 0.7, the solid line is for Pr = 0.021 and the dashed-dotted line is for Pr = 0.005. For velocity, the shape factor H_u is independent of Prandtl number.

From these quantities, we can define the shape factors H as

$$H_T = \frac{d_T}{m_T}$$
 and $H_u = \frac{d_u}{m_u}$. (24)

The shape factor for the laminar Prandtl-Blasius profile is 2.59 for H_u , independent of Prandtl number. The computed quantity for H_T is Prandtl number dependent and is 2.58, 2.47, and 2.44 for Pr = 0.7, 0.021 and 0.005, respectively (see Fig. 13). A shape factor that is larger than the laminar value tends to indicate an overshoot of the Prandtl-Blasius profile and a smaller shape factor indicates an undershoot. The latter is caused by rising (or falling) plumes and resulting recirculations due to flow incompressibility. In almost all cases, the shape factors are fairly close, but tend to fall below the Prandtl-Blasius values. The results for H_u demonstrate a systematic decrease in shape factor as Prandtl number decreases. The results for H_T show similar shape factor values for Pr = 0.7 and Pr = 0.021 as was also presented in [46]. However, the temperature shape factor for Pr = 0.005 is an outlier. And the shape of the temperature profile does look different for $Ra < 1 \times 10^7$, with a distinct rounded peak at the end of the boundary layer as is evidenced by the larger shape factors. For $Ra = 1 \times 10^7$, the thermal boundary layer more closely resembles the Prandtl-Blasius profile.

Finally, we can use our results for the velocity shape factor, H_u to predict a transition to a turbulent boundary layer. The shape factor H_u should be 1.28 for a turbulent boundary layer [47]. In Fig. 14 we fit lines to the data and find the intersection of these fits with the horizontal line at $H_u = 1.28$. This value will be $Ra_c^{(III)}$. For Pr = 0.7 a fit to



FIG. 14: Extrapolation of functional dependence of the velocity shape factor to determine $Ra_c^{(III)}$, the critical Rayleigh number for the transition to a turbulent boundary layer. Note for Pr = 0.7, the fit is only to the last four data points. The horizontal black line at 2.59 is the shape factor for a laminar boundary layer and the horizontal red line at 1.28 is the value of the shape factor for a turbulent boundary layer.

Extrapolation Met	hod Pr	Ra_c	Uncertainty Range
Ι	0.7	$Ra_c = 5 \times 10^{12}$	$1 \times 10^{12} < Ra_c < 2 \times 10^{13}$
Ι	0.021	$Ra_c = 1 \times 10^{11}$	$5 \times 10^9 < Ra_c < 4 \times 10^{12}$
Ι	0.005	$Ra_c = 1 \times 10^9$	$1 \times 10^7 < Ra_c < 5 \times 10^{11}$
II	0.7	$Ra_c = 9 \times 10^{11}$	$1 \times 10^{11} < Ra_c < 4 \times 10^{12}$
II	0.021	$Ra_c = 1 \times 10^{10}$	$5 \times 10^9 < Ra_c < 5 \times 10^{10}$
II	0.005	$Ra_c = 6 \times 10^8$	$3 \times 10^6 < Ra_c < 1 \times 10^{12}$
III	0.7	$Ra_c = 4 \times 10^{16}$	$6 \times 10^{12} < Ra_c < 1 \times 10^{22}$
III	0.021	$Ra_c = 7 \times 10^{14}$	$2 \times 10^{12} < Ra_c < 1 \times 10^{18}$
IV	0.7	$Ra_c = 3 \times 10^{13}$	$1 \times 10^{13} < Ra_c < 5 \times 10^{13}$
IV	0.021	$Ra_c = 2 \times 10^{13}$	$1 \times 10^{12} < Ra_c < 1 \times 10^{14}$

TABLE II: A comparison of different methods to predict the range of critical Rayleigh numbers, Ra_c , at which the viscous boundary layer becomes turbulent for three different Prandtl numbers. Methods I-III are described in this paper. Method IV was discussed in [25].

the last four data points gives $Ra_c^{(III)}(Pr = 0.7) = 4 \times 10^{16}$, for Pr = 0.021 the $Ra_c^{(III)}(Pr = 0.021) = 7 \times 10^{14}$. The data for Pr = 0.005 is very scattered with no clear trend. The resulting uncertainty ranges vary quite widely, when the error associated with the least squares fit is taken into account. These ranges are $6 \times 10^{12} < Ra_c < 1 \times 10^{22}$ for Pr = 0.7 and $2 \times 10^{12} < Ra_c < 1 \times 10^{18}$ for Pr = 0.021. While the predictions for $Ra_c^{(III)}$ are larger for the other methods, the values of $Ra_c^{(III)}$ do overlap when the uncertainty is taken into account. It is not surprising that method III overestimates the value for Ra_c since the boundary layer profile would be fully turbulent if $H_u = 1.28$, whereas for method II, we extrapolate to where the boundary layer just reaches the log-law, or when it just starts to become turbulent. Furthermore, as summarized in Ref. [48], the shape factor H_u of turbulent flat plate boundary layers is often found rather at values of 1.4, i.e., larger than 1.28. This would additionally decrease the critical Rayleigh numbers in our extrapolation. The results for all three methods are summarized in Tab. II. In addition, the results from a fourth method that we discussed in [25] are given for completeness. This method is based on a shear Reynolds number Re_{sh} which can be determined by means of a root mean square velocity taken at the distance from the plate that corresponds to the mean of a locally fluctuating viscous boundary layer thickness. The local boundary layer thickness is determined for the vertical derivatives of the horizontal velocity components which correspond to the two components of the skin friction vector field. A turbulent fraction is defined as the percentage of BL area for which $Re_{sh} \gtrsim 350$. The transition follows for those Ra that would have a turbulent fraction of 100%.



FIG. 15: Semilogarithmic plot of mean temperature profiles scaled by inner wall units. These profiles are given for the three indicated Prandtl numbers as a function of Rayleigh number (and increasing Rayleigh number is indicated by an arrow). The dashed lines are fits to the theoretically predicted law by Yaglom and Kader [50, 51] $\langle \theta^+(x_3^+) \rangle = \alpha \ln x_3^+ + \beta(Pr)$ with $\alpha \approx 2.12$, $\beta(Pr) = (3.8Pr^{1/3} - 1)^2 - 1 + 2.12 \ln Pr$. In all cases, the profiles taken from the top and bottom plates are included.

V. TEMPERATURE FIELD STATISTICS

A. Mean profiles

In ref. [19], we also examined the profiles of the mean temperature inner wall units and we extend this analysis here. We define the friction temperature as

$$T_{\tau} = -\left\langle \frac{u_{\tau}^{-1}(t)}{\sqrt{RaPr}} \left\langle \frac{\partial T}{\partial x_3} \right\rangle_b \bigg|_{x_3=0} \right\rangle_t.$$
(25)

Thus $\theta^+ = T/T_{\tau}$ and we plot these profiles as a function of Rayleigh and Prandtl number in Fig. 15. Note that for Figs. 15, the instantaneous profiles for θ^+ versus x_3^+ are first found by dividing $\theta = \{T/\Delta T \text{ for } x_3 = 1, 1 - T/\Delta T \text{ for } x_3 = 0\}$ by the instantaneous T_{τ} and x_3 by the instantaneous ℓ_{τ} . Then these profiles are time averaged (see [19] for more details). We see that the profiles follow a similar trend of rising as Rayleigh increases, with a portion of the profile following a logarithmic law. The region of the profile that is logarithmic tends to increase as Rayleigh number increases. The dashed lines are a plot of the theoretically predicted turbulent temperature profile by Yaglom and Kader [50, 51] for each Prandtl number: $\langle \theta^+(x_3^+) \rangle = \alpha \ln x_3^+ + \beta(Pr)$ with $\alpha \approx 2.12$, $\beta(Pr) = (3.8Pr^{1/3} - 1)^2 - 1 + 2.12 \ln Pr$. While the profiles for Pr = 0.021 and Pr = 0.005 have slopes that are smaller than the slope of theoretical log law, the slope for Pr = 0.7 is quite similar, with an agreement of 10% for the three highest Rayleigh numbers (although the intercept does not match). Finally one sees that as Prandtl number decreases, the temperature profiles tend to decrease in size in these inner wall units, but they reach their peak at larger x_3^+ values.

The slopes $\langle \alpha_f \rangle_t$ of the linear portion of the semilog plots are found by fitting each instantaneous temperature profile to the equation $\langle \theta^+(x_3^+) \rangle_b = \alpha_f \ln x_3^+ + \beta_f$. The $\langle \alpha_f \rangle_t$ values are then the time averages. The error bars are given by the standard deviation in the α_f values found from the instantaneous profiles. Then these values are converted to units of unscaled T versus x_3 by multiplying by the friction temperature T_{τ} . These slopes, $\langle \alpha_f \rangle_t T_{\tau}$ are plotted in Fig. 16 for all available Rayleigh and Prandtl numbers. The universality in these slopes for the three Prandtl numbers is quite remarkable. In addition the results from Ahlers et. al. [52] are also plotted, which were for Pr = 0.8, $\Gamma = 0.5$ and $5 \times 10^{11} < Ra < 5 \times 10^{12}$. However, their results were for an aspect ratio of 1/2 and they measured the profiles close to the sidewall of the container, and either of these could account for the discrepancy. In their paper, they also predicted a theoretical scaling exponent between -0.005 and -0.106, which does agree with our exponent. In addition, Wei and Ahlers [53] found, for Pr = 12.3, $\Gamma = 1$ and $2 \times 10^{10} < Ra < 2 \times 10^{11}$, a scaling exponent of -0.011 ± 0.025 (no prefactor given) which is in agreement with our results. More work needs to be done experimentally, numerically and theoretically to better understand the dependence of $\langle \alpha_f \rangle_t T_{\tau}$ on Rayleigh and Prandtl number.



FIG. 16: Slopes $\langle \alpha_f \rangle_t$ found by fitting a line to the linear portion of Fig. 15 for each Rayleigh and Prandtl number. Then each slope $\langle \alpha_f \rangle_t$ is multiplied by its respective friction temperature T_{τ} . Fits to the data are $\langle \alpha_f \rangle_t T_{\tau} = (1.0 \pm 0.1) Ra^{-0.03 \pm 0.01}$ for Pr = 0.7 (black dashed line), $\langle \alpha_f \rangle_t T_{\tau} = (0.15 \pm 0.06) Ra^{-0.03 \pm 0.001}$ for Pr = 0.021 (blue solid line) and $\langle \alpha_f \rangle_t T_{\tau} = (0.06 \pm 0.03) Ra^{-0.02 \pm 0.01}$ for Pr = 0.021 (blue solid line) and $\langle \alpha_f \rangle_t T_{\tau} = (0.06 \pm 0.03) Ra^{-0.02 \pm 0.01}$ for Pr = 0.005 (yellow dashed-dotted line). The purple dashed line is the equation by Ahlers et al. (ABH)[52]: $\langle \alpha_f \rangle_t T_{\tau} = (0.66 \pm 0.06) Ra^{-0.123 \pm 0.01}$.

B. Probability density functions

Finally we summarize the statistics of the temperature field for the three series of simulation runs. The probability density functions (PDFs) of $T(\boldsymbol{x},t)$ for different Rayleigh and Prandtl numbers are shown in Fig. 17. While the panels to the left evaluate the distribution of T in the full volume V, the data to the right are obtained in the subvolume V_b (see section III). All PDFs are centered around their global $\langle T \rangle_{V,t}$ or bulk mean $\langle T \rangle_{V_b,t}$, respectively. We find that the temperature PDFs at a fixed Pr become systematically more narrow about the mean as the Rayleigh number increases, both, in the bulk and the full volume. This trend agrees with what is seen in ref. [22] in the bulk for the high-Rayleigh number experiments in mercury. However for Pr = 0.005 and the highest Rayleigh number (run 19), we see that PDF $_{V_b,t}$, the distribution taken over the bulk of the container, has widened. The reason for this observation could be that the Reynolds number is large enough to generate sharper plume structures of the temperature field.

The trend is confirmed in Fig. 18(a), where we plot the width for the bulk temperature PDFs. We see that the widths decrease systematically as Rayleigh increases except for run 19 which is an outlier. In Fig. 18, we also plot the skewness and kurtosis for the bulk temperature pdfs as defined by the following equations:

Skewness =
$$\frac{\langle (T - \langle T \rangle_{V_b,t})^3 \rangle_{V_b,t}}{\langle (T - \langle T \rangle_{V_b,t})^2 \rangle_{V_b,t}^{3/2}},$$
(26)

$$\operatorname{Kurtosis} = \frac{\langle (T - \langle T \rangle_{V_b,t}) \rangle_{V_b,t}^4}{\langle (T - \langle T \rangle_{V_b,t})^2 \rangle_{V_b,t}^2}.$$
(27)

The skewness, or asymmetry of the PDF is fairly randomly scattered about zero, and the larger values for the higher Rayleigh numbers are most likely a result of the shorter simulation times. The kurtosis, on the other hand, tends to grow systematically from sub-Gaussian values (smaller than 3) at the lowest Rayleigh numbers to values larger than 3 for all Prandtl numbers and sufficiently large Ra. This indicates a increasing intermittency of temperature statistics. The kurtosis is found to level off for the series at Pr = 0.7 for $Ra \gtrsim 10^8$.

VI. SUMMARY AND DISCUSSION

The main purpose of the present work was summarize our DNS results for all Rayleigh and Prandtl numbers and then to use these results to predict a possible transition to turbulence in the viscous boundary layer of a turbulent Rayleigh-Bénard convection flow by different analysis methods. We used our existing and further extended direct numerical simulation data basis for three-dimensional turbulent convection in a closed cylindrical cell at an aspect ratio of 1. Most of the data are obtained in the regime of very low Prandtl numbers, i.e., in a regime of convection where the thermal and viscous boundary layers are partly decoupled from each other. It is the thin viscous boundary layer which shows a transitional behavior that is accompanied by intermittent fluctuations of local thickness, wall stress or



FIG. 17: Temperature probability density functions (PDFs) for Pr = 0.7 (top row), Pr = 0.021, (middle row) and Pr = 0.005 (bottom row). The horizontal axis is the temperature minus the global, $\langle T \rangle_{V,t}$, or bulk mean temperature, $\langle T \rangle_{V_b,t}$. The left column (PDF_{V,t}) gives the PDFs taken over the entire container, and the right column (PDF_{V_b,t}) gives the PDFs taken over the bulk (see caption for Fig. 5 for a definition of the bulk).

velocity amplitudes. In the focus of the present work was the analysis of "standard" quantities of turbulent boundary layer analysis, such as the existence of logarithmic profiles, displacement and momentum displacement thicknesses and the resulting shape factors. Based on such quantities, we suggest three methods that predict a range of critical Rayleigh numbers for a transition to boundary layer turbulence by extrapolation. Furthermore, a fourth method which we discussed in [25] is added for completeness.

One point that did not receive much attention in the past is related to the specific shape of the velocity profile. Theoretical models such as [54] assume a logarithmic profile that extends all the way to the mid plane of the convection layer or cell. The mean streamwise velocity profiles in our simulations are however found to be closer (although not equal) to a planar wall-jet with a pronounced local mean velocity maximum and an offset (see fig. 7). Similarly to channels, this class of flows obeys a logarithmic law of the wall as reported in refs. [55, 56]. It would thus be interesting to verify whether the decreasing mean velocity towards the bulk has consequences for the scaling predictions. Which theoretical model best describes the viscous BL profiles near the plates and how this effects the global transport across the boundary layers is still an open question that requires closer inspection.

The predicted transition ranges in all methods are shifted to lower Rayleigh number values as the Prandtl number decreases which is consistent with the results of the scaling theory by Grossmann and Lohse (see e.g. Fig. 3(a) in ref.[1]). For convection in air, the predictions of methods I and IV are consistent with experimental results [44]. The four methods that are independent of each other predict partly overlapping ranges of critical Rayleigh numbers. We note again that the extrapolations in all cases have large error bars. For the smallest Prandtl number, namely run 19, longer time series would be needed to resolve the slow transformation of the large-scale flow in the cell. The intention of this work is to suggest several analysis tools that can be applied in future simulations and partly even in experiments. At this stage, it is hard to say which of our methods is most reliable, although it is seen that method III has the largest uncertainty ranges and method II provides only a lower bound as it predicts just when the boundary layer reaches the



FIG. 18: Width $\langle (T - \langle T \rangle_{V_b,t})^2 \rangle_{V_b,t}$, skewness and kurtosis calculated from the bulk temperature PDFs in the right column of Fig. 17. See Eqns. (26) and (27) for our definitions of skewness and kurtosis.

log-law.

We also wish to note that our predictions do not imply that such a transition must occur. Our study should therefore be understood as an encouragement to conduct a new series of high-Rayleigh number laboratory experiments, in particular in the low Prandtl number regime. This is to our view one of the most interesting sectors of the Ra - Prparameter plane, since the turbulence is highly inertial as we discussed here and in our subsequent works [19, 20, 25]. Specifically, liquid sodium, the lowest Prandtl number that can be obtained in a laboratory, seems to occupy a special role. It is still not well-understood if the turbulent convection flow switches into a different regime as Rayleigh number increases, as a result of the very diffusive temperature field. Our trends for the Nusselt number in Fig. 3 might suggest such a behavior. Further longer-term numerical simulations are currently underway to understand these observations better and will be reported elsewhere.

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VII. APPENDIX: TRANSFORMATION INTO LSC FRAME

We summarize the rotations of coordinates and fields that have been used in Ref. [19] to determine a streamwise and spanwise in a closed cylindrical convection cell. The mean orientation angle of the LSC is calculated in each plane at fixed height $x_3 > 0$ by

$$\langle \phi(x_3,t) \rangle_b = \arctan\left[\frac{\langle u_2(x_3,t) \rangle_b}{\langle u_1(x_3,t) \rangle_b}\right].$$
 (28)

At each plane of constant x_3 we apply afterwards

$$\begin{pmatrix} \hat{x}_1\\ \hat{x}_2\\ \hat{x}_3 \end{pmatrix} = \begin{pmatrix} \cos\langle\phi\rangle_b & \sin\langle\phi\rangle_b & 0\\ -\sin\langle\phi\rangle_b & \cos\langle\phi\rangle_b & 0\\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1\\ x_2\\ x_3 \end{pmatrix} .$$
(29)

and thus the velocity components transform correspondingly as

$$\begin{pmatrix} \hat{u}_1\\ \hat{u}_2\\ \hat{u}_3 \end{pmatrix} = \begin{pmatrix} \cos\langle\phi\rangle_b & \sin\langle\phi\rangle_b & 0\\ -\sin\langle\phi\rangle_b & \cos\langle\phi\rangle_b & 0\\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} u_1\\ u_2\\ u_3 \end{pmatrix} .$$
(30)

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