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# Soliton dynamics in optical fibers using the Generalized Traveling Wave Method 

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The Generalized Traveling Wave Method (GTWM) is applied to the non-linear Schrödinger (NLS) equation with general perturbations in order to obtain the equations of motion for an ansatz with 6 collective coordinates, namely the soliton position, the amplitude, the inverse of the soliton width, the velocity, the chirp, and the phase. The advantage of the new ansatz is that it yields three pairs of canonically conjugated coordinates and momenta which all well-behaved. The new ansatz is applied to model the dynamics of a soliton in a dispersion-shifted optical fiber described by the generalized NLS including dissipation, higher-order dispersion, Raman scattering and self-steepening perturbations. It is shown that the GTWM is equivalent to the modifed method of moments, which considers the time variation of the norm, the first and the second moment of the norm, the momentum, the first moment of the momentum and the energy for the perturbed NLS equation.

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## I. INTRODUCTION

The non-linear Schrödinger (NLS) equation is one of the paradigms of soliton physics because it represents a completely integrable system and has numerous applications in practically all fields of physics, which include charge density waves [1], long Josephson junctions [2], optical fibers [3-5], plasmas driven by rf fields [6], and Bose-Einstein condensates $[7,8]$ (see also review articles [9-11]). In particular, in optical fibers, the perturbed NLS equation

$$
\begin{equation*}
i u_{t}+\sigma u_{x x}+\gamma_{0}|u|^{2} u=R[u(x, t) ; x, t] \tag{1}
\end{equation*}
$$

is investigated [12-14], where $\beta_{2}=-2 \sigma$ is the group velocity dispersion and $\gamma_{0}$ is the non-linear parameter responsible for self-phase modulation. The complex function $R$ represents many different kinds of perturbations and may also depend on $u^{\star}$ and the spatial derivatives of $u$ and $u^{\star}$. For sufficiently small perturbations it is usually assumed that the dynamics of a single soliton can be approximately described by an ansatz in the form of the 1 -soliton solution of the unperturbed NLS equation, where the parameters of that solution become time-dependent unknown variables: the so-called collective coordinates (CCs). This ansatz is given by [9]

$$
\begin{equation*}
u(x, t)=2 i \eta \sqrt{\frac{2 \sigma}{\gamma_{0}}} \operatorname{sech}[2 \eta(x-\zeta)] \exp (-i \Theta), \quad \Theta=2 \xi x+\phi \tag{2}
\end{equation*}
$$

with the four CCs $\eta(t), \zeta(t), \xi(t)$, and $\phi(t)$. By specifying perturbation $R=a \exp (i K(t) x)$ without dissipation, and using the Lagrangian approach, then a set of ordinary differential equations (ODEs) for the four CCs was developed [15]. This driving term was already used in the discrete form to model an array of coupled non-linear optical waveguides, in which discrete cavity solitons can be excited [16]. Although in the case of this external driving force, the numerical solution of the CC equations predicted a soliton dynamics which was confirmed by simulations of the perturbed NLS equation [15], the ansatz (2), from the physical point of view, presents certain disadvantages: First, when the ansatz (2) is inserted into the Lagrangian density and an integration over $x$ is performed, the Lagrangian $(L)$ is obtained as a function of the CCs and the time derivatives $\dot{\phi}$ and $\dot{\xi}$. The canonical momentum $d L / d \dot{\phi}$ can be identified with the norm $N=\int d x|u|^{2}$. However, the canonical momentum $d L / d \dot{\xi}$ does not have any obvious physical interpretation. Second, the Hamiltonian as a function of canonically conjugated variables can be obtained only after a complicated transformation. Finally, when the forcing is time-independent, that is, $K(t)=$ constant, then the CCs $\eta(t)$ and $\xi(t)$ perform periodic oscillations, and $\zeta(t)$ has a linear term and oscillations around it. However, $\phi(t)$ exhibits oscillations with a growing amplitude around a linear term.

The above disadvantages can be avoided through the use of a slightly different ansatz [17]: $\Theta$ in Eq. (2) is replaced by $\Theta=2 \xi(x-\zeta)+\Phi$. By using this modified ansatz, the new Lagrangian depends on $\dot{\Phi}$ and $\dot{\zeta}$. The canonical momentum $d L / d \dot{\Phi}$ can again be identified with the norm. The second canonical momentum $d L / d \dot{\zeta}$ now has a physical interpretation: namely, it can be identified with the field momentum. The Hamiltonian is obtained by a simple Legendre transformation and $\Phi(t)$ performs oscillations with constant amplitude, as do the other CCs. Remarkably, this new ansatz allows one to calculate a so-called "phase portrait" in which the soliton dynamics is described by a point moving on a curve in the complex plane. The "phase portrait" makes sense only when this curve is closed, then the point moves on the same orbit in each period. Interestingly, the shape of the orbit allows a prediction about the stability of the soliton, which is indeed confirmed by simulations [17].

One of the main goals of our paper is to show that similar disadvantages to those mentioned above appear in collective-coordinate theories for optical solitons and can also be avoided in a similar way as above. Indeed, in the literature on optical solitons the following ansatz with five CCs has been widely used [12-14]:

$$
\begin{equation*}
w(z, T)=\sqrt{\frac{E_{p}}{2 T_{p}}} \operatorname{sech} \frac{T-q_{p}}{T_{p}} \exp \left(-i\left[\phi_{p}+\Omega_{p}\left(T-q_{p}\right)+C_{p} \frac{\left(T-q_{p}\right)^{2}}{2 T_{p}^{2}}\right]\right) \tag{3}
\end{equation*}
$$

Here we use the notation of Refs. [12, 14], where the propagation distance $z$ corresponds to the time $t$ in our NLS equation, and the time $T$ corresponds to our spatial variable $x$. The phase $\phi_{p}$ is assumed to be constant. The CCs depend on $z$ and are the energy $E_{p}$, the temporal shift $q_{p}$, the frequency shift from the original carrier frequency, $\Omega_{p}$, the soliton duration $T_{p}$, and the time-domain chirp $C_{p}$. The chirp term is introduced as a second-order perturbation to the phase of the soliton.

We show that the ansatz (3) also produces problems with the definition of canonical momenta. In particular, $d L / d \dot{T}_{p}$ yields an expression that contains $T_{p}$, which means that $d L / d \dot{T}_{p}$ cannot be a canonical momentum. In contrast to this, an improved new ansatz with a new chirp term and the phase as a sixth CC produces three pairs of canonically conjugated variables. As the Lagrange formalism generally works only for systems without dissipation, and as a dissipative optical fiber is considered, we present the so-called Generalized Traveling Wave Method (GTWM), which
works for arbitrary perturbations $R$. The method was introduced in a general way in Ref. [18]: only the Hamilton equations of the unperturbed system must be known and the unperturbed system need not be integrable. The method was applied to the zero-temperature dynamics [18] and thermal diffusion [19, 20] of magnetic vortices in the two-dimensional anisotropic Heisenberg model, and to the dynamics of topological solitons in non-linear Klein-Gordon equations [21].

In particular for 4 CCs (see Eq. (2)), in [22] it is shown that the GTWM is equivalent to the time-variation: of the norm, of the first moment of the norm, of the momentum and of the energy. This approach has successfully been applied to the nonlinear Schrödinger equation in higher spatial dimension [23]. In the optical interpretation, this technique is known as the Method of Moments (MoM), also termed as the modified conservation laws, which also work for arbitrary perturbations R . This is the method that is mostly used in the literature on optical solitons with five collective variables $[12-14,24]$. Therefore, in order to obtain the equations of motion, five moments (the norm $N$, its first moment $N_{1}$, its second moment $N_{2}$, the momentum $P$, and its first moment $P_{1}$ ) are used [12-14]. Notice that a direct comparison between the ansatze (2) and (3) shows 3 major differences. First, in the ansatz (3) with 5 CCs, the amplitude and the width of the soliton are two independent variables. Second, in the ansatz (3), the phase is no longer an independent variable. Finally, the chirp term is introduced in (3) as the 5 th collective coordinate.

In the current work, we use six independent CCs, namely the soliton position, the amplitude, the inverse of the soliton width, the velocity, the chirp, and the phase. It can be shown that the MoM yields six CC equations, identical to those from GTWM, if the phase in (3) is introduced as a sixth variable and the energy as the sixth moment. In Ref. [25], a different identity instead of a sixth moment was used. However, the resulting CC equations differ from the CC equations obtained by the GTWM.

The presentation of the above results is organized as follows: In the following section, the physical interpretation of canonical momenta is given using an ansatz with six CCs. It is also shown that an inconsistency is obtained when, instead six CCs, five CCs are used In Sec. III, the GTWM is developed for a general perturbation and its equivalence with the modified method of moments is shown. In Sec. IV, we apply the above methods to soliton dynamics in a dispersion-shifted fiber. The dynamics is modeled by a perturbed NLS equation, where the perturbation $R$ consists of several terms [12-14] which account for dissipation, higher-order dispersion, delayed Raman response, energy loss through intra-pulse Raman scattering, and self-steepening. We express $R$ in our notation, calculate the relevant integrals and obtain six CC equations. The sixth ODE is an equation for $\Phi(t)$. The soliton dynamics is studied through the numerical solutions of the equations of motion for the collective coordinates. To conclude the paper, in Sec. V our main findings are summarized.

## II. PHYSICAL INTERPRETATION OF CANONICAL MOMENTA: ANSATZ WITH 6 COLLECTIVE VARIABLES

In this section it is shown that the ansatz that is used in the following sections possesses certain advantages compared to the ansätze that have been widely used in the literature [12-14]. This concerns the form of the chirp term and the introduction of a phase as a sixth collective coordinate (in the above literature only five collective coordinates were used). It is shown that our ansatz allows the definition of three canonical momenta, thereby providing three pairs of canonically conjugated variables.

In order to achieve our goal, we focus on the perturbed NLS Eq. (1) with the driving term $R=a \exp (i K(t) x)$ [15], which is obtained from the Euler-Lagrange equation

$$
\frac{d}{d t} \frac{\partial \mathcal{L}_{t o t}}{\partial u_{t}^{\star}}+\frac{d}{d x} \frac{\partial \mathcal{L}_{t o t}}{\partial u_{x}^{\star}}-\frac{\partial \mathcal{L}_{t o t}}{\partial u^{\star}}=0
$$

with the Lagrangian density $\mathcal{L}_{\text {tot }}=\mathcal{L}_{\text {kin }}-\mathcal{L}_{p o t}+\mathcal{L}_{\text {pert }}$

$$
\mathcal{L}_{k i n}=\frac{i}{2}\left(u_{t} u^{\star}-u_{t}^{\star} u\right), \quad \mathcal{L}_{\text {pot }}=\sigma\left|u_{x}\right|^{2}-\frac{\gamma_{0}}{2}|u|^{4}, \quad \mathcal{L}_{\text {pert }}=-a\left(\exp (i K(t) x) u^{\star}+\exp (-i K(t) x) u\right)
$$

Our ansatz

$$
\begin{equation*}
u(x, t)=2 i A \operatorname{sech}[2 \eta(x-\zeta)] \exp (-i \Theta), \quad \Theta=\Phi+2 \xi(x-\zeta)+C(x-\zeta)^{2} \tag{4}
\end{equation*}
$$

contains six collective variables: soliton position $\zeta(t)$, amplitude $A(t)$, inverse width $2 \eta(t)$, velocity $\xi(t)$, chirp $C(t)$, and phase $\Phi(t)$ [25].

By inserting the ansatz into $\mathcal{L}_{k i n}$ and integrating over $x$, the kinetic part of the Lagrangian is obtained

$$
\begin{equation*}
L_{k i n}=4 \frac{A^{2}}{\eta} \dot{\Phi}-8 \frac{A^{2}}{\eta} \xi \dot{\zeta}+\frac{\pi^{2}}{12} \frac{A^{2}}{\eta^{3}} \dot{C} . \tag{5}
\end{equation*}
$$

From this, we obtain

$$
\frac{\partial L_{k i n}}{\partial \dot{\Phi}}=4 \frac{A^{2}}{\eta}=N
$$

where the canonical momentum $N$ is conjugated to the phase $\Phi$ and is identified as the norm $N=\int d x|u|^{2}$. Furthermore,

$$
\frac{\partial L_{k i n}}{\partial \dot{\zeta}}=-8 \frac{A^{2}}{\eta} \xi=P
$$

where the canonical momentum $P$ (field momentum)

$$
\begin{equation*}
P=\frac{i}{2} \int_{-\infty}^{+\infty} d x\left(u u_{x}^{\star}-u^{\star} u_{x}\right) \tag{6}
\end{equation*}
$$

is conjugated to the soliton position $\zeta$. Moreover, $P=M V$, where $M=N / 2$ is the mass and $V=-4 \xi$ is the soliton velocity. Finally, we obtain

$$
\frac{\partial L_{k i n}}{\partial \dot{C}}=\frac{\pi^{2}}{12} \frac{A^{2}}{\eta^{3}}=D
$$

where the canonical momentum $D$ is conjugated to the chirp $C$ and can be written in the form $D=\pi^{2} N B^{2} / 12$, with $B=1 /(2 \eta)$ as the soliton width.

Now we want to show that the ansatz (3) that has often been used in the literature on optical solitons [12-14] does not allow the definition of three canonical momenta.

The CCs in Eq. (3) for $\omega(z, T)$ have the following relations to the CCs in Eq. (4)

$$
\begin{equation*}
q_{p} \equiv \zeta, \quad \frac{1}{T_{p}} \equiv 2 \eta, \quad \sqrt{\frac{E_{p}}{2 T_{p}}} \equiv 2 A, \Omega_{p} \equiv 2 \xi, \quad \frac{C_{p}}{2 T_{p}^{2}} \equiv C \tag{7}
\end{equation*}
$$

and constant phase $\phi_{p}$. The factor $i$ in our ansatz is equivalent to a constant phase $\phi_{0}=\pi / 2$, because $i=\exp \left(-i \phi_{0}\right)$.
Using the above variables, we obtain

$$
L_{k i n}=-E_{p} \Omega_{p} \dot{q}_{p}+\frac{\pi^{2}}{24} E_{p} \dot{C}_{p}-\frac{\pi^{2}}{12} \frac{E_{p} C_{p}}{T_{p}} \dot{T}_{p}
$$

For the first canonical momentum we get

$$
\frac{\partial L_{k i n}}{\partial \dot{C}_{p}}=\frac{\pi^{2}}{24} E_{p}
$$

where the energy $E_{p}=\int d \tau|w|^{2}$ is conjugated to the chirp. For the second canonical momentum, we obtain

$$
\begin{equation*}
\frac{\partial L_{k i n}}{\partial \dot{q}_{p}}=-E_{p} \Omega_{p} \tag{8}
\end{equation*}
$$

and this is conjugated to the temporal shift $q_{p}$, where $\Omega_{p}=\left(i / 2 E_{p}\right) \int d \tau\left(w w_{T}^{\star}-w^{\star} w_{T}\right)$ is identified as the frequency shift. The r.h.s. of Eq. (8) is equivalent to the canonical momentum $P$ in Eq. (6). Finally, we obtain

$$
\begin{equation*}
\frac{\partial L_{k i n}}{\partial \dot{T}_{p}}=-\frac{\pi^{2}}{12} \frac{E_{p} C_{p}}{T_{p}} \tag{9}
\end{equation*}
$$

Here the chirp should be conjugated to the soliton duration $T_{p}$. However, $T_{p}$ also appears on the r.h.s. of Eq. (9) which must not be the case. Thus the r.h.s. of Eq. (9) cannot be interpreted as a canonical momentum.

Going back to our ansatz Eq. (4), $\mathcal{L}_{p o t}$ is integrated over $x$ and we obtain for the potential part of the Lagrangian

$$
L_{p o t}=\frac{16 \sigma}{3} A^{2} \eta+16 \sigma \frac{A^{2} \xi^{2}}{\eta}+\frac{\pi^{2} \sigma}{3} \frac{A^{2} C^{2}}{\eta^{3}}-\frac{16 \gamma_{0}}{3} \frac{A^{4}}{\eta}
$$

and for the perturbative part $L_{\text {pert }}=\int d x \mathcal{L}_{\text {pert }}$. By denoting the non-perturbative part as $L=L_{k i n}-L_{p o t}$, the six Lagrange equations become

$$
\frac{d}{d t} \frac{\partial L}{\partial \psi_{t}}-\frac{\partial L}{\partial \psi}=\frac{\partial L_{p e r t}}{\partial \psi}
$$

where $\psi$ stands for the $6 \mathrm{CCs} \Phi(t), \zeta(t), \eta(t), \xi(t), A(t)$, and $C(t)$.
However, the Lagrange formalism only works for Hamiltonian systems, that is, the perturbation $R$ does not contain dissipative terms. If the damping is very simple, for example, $R=-i \beta u(x, t)$ with $\beta>0$, then the Euler-Lagrange equation can be generalized through the introduction of a dissipation function; for the above example see Ref. [15, 17].

For this reason, in the next section, two methods are used which both work for arbitrary perturbation $R$ : For the Generalized Traveling Wave Method only the Hamiltonian of the unperturbed system must be known. Using our ansatz (4), six equations of motion are obtained. The same CC equations are derived by using the Method of Moments, if a sixth moment is introduced.

## III. GENERALIZED TRAVELING WAVE METHOD AND METHOD OF MOMENTS WITH SIX CC

The perturbed NLS Eq. (1) actually consists of two equations for the real and imaginary parts, for $u(x, t)$ and $u^{*}(x, t)$. For our purpose, these equations can be rewritten as

$$
\begin{align*}
i u_{t} & =\frac{\delta H_{0}}{\delta u^{*}}+R[u(x, t) ; x, t]  \tag{10}\\
-i u_{t}^{*} & =\frac{\delta H_{0}}{\delta u}+R^{*}[u(x, t) ; x, t] \tag{11}
\end{align*}
$$

where

$$
\begin{equation*}
H_{0}=\int_{-\infty}^{+\infty} d x \mathcal{H}_{0}=\int_{-\infty}^{+\infty} d x\left(\sigma u_{x} u_{x}^{*}-\frac{\gamma_{0}}{2} u^{2} u^{* 2}\right) \tag{12}
\end{equation*}
$$

For the following, only this Hamiltonian of the unperturbed system must be known. We now assume that the time dependence of $u(x, t)$ and $u^{*}(x, t)$ in Eqs. (10)-(11) only appears via a set of $m$ real collective coordinates $\left\{Y_{1}(t), Y_{2}(t), \ldots Y_{m}(t)\right\}:=\vec{Y}(t)$, that is, $u(x, t)=u(x, \vec{Y}(t))$ and $u^{*}(x, t)=u^{*}(x, \vec{Y}(t))$. It is then necessary to multiply (10) by $\partial u^{*} / \partial Y_{n}$, and (11) by $\partial u / \partial Y_{n}$, add the resulting equations and integrate over the system, which yields

$$
\begin{equation*}
\sum_{j=1}^{m} I_{Y_{n} Y_{j}} \dot{Y}_{j}=F_{n}(\vec{Y})+R_{n}(\vec{Y}), \quad n=1,2, \ldots m \tag{13}
\end{equation*}
$$

with

$$
\begin{align*}
& I_{Y_{n} Y_{j}}=\int_{-\infty}^{+\infty} d x i\left[\frac{\partial u}{\partial Y_{n}} \frac{\partial u^{*}}{\partial Y_{j}}-\frac{\partial u^{*}}{\partial Y_{n}} \frac{\partial u}{\partial Y_{j}}\right]  \tag{14}\\
& F_{n}(\vec{Y})=-\int_{-\infty}^{+\infty} d x\left[\frac{\delta H_{0}}{\delta u^{*}} \frac{\partial u^{*}}{\partial Y_{n}}+\frac{\delta H_{0}}{\delta u} \frac{\partial u}{\partial Y_{n}}\right]=-\int_{-\infty}^{+\infty} d x \frac{\partial \mathcal{H}_{0}}{\partial Y_{n}}=-\frac{\partial H_{0}}{\partial Y_{n}}  \tag{15}\\
& R_{Y_{n}}(\vec{Y})=-\int_{-\infty}^{+\infty} d x\left(R \frac{\partial u^{*}}{\partial Y_{n}}+R^{*} \frac{\partial u}{\partial Y_{n}}\right) \tag{16}
\end{align*}
$$

where the overdot in Eq. (13) denotes the derivative with respect to time. Equations (13)-(16) represent a set of $m$ first-order ODEs for our $m$ CCs.

In order to evaluate the integrals (14) which appear in the ODEs (13), we now take the one-soliton solution of the unperturbed NLS equation [9] and make the specific ansatz (4) for $u(x, \vec{Y}(t))$ [25]. The soliton energy (12) is obtained

$$
\begin{equation*}
H_{0}=\frac{16 \sigma}{3} A^{2} \eta+16 \sigma \frac{A^{2} \xi^{2}}{\eta}+\frac{\pi^{2} \sigma}{3} \frac{A^{2} C^{2}}{\eta^{3}}-\frac{16 \gamma_{0}}{3} \frac{A^{4}}{\eta} \tag{17}
\end{equation*}
$$

Setting $Y_{1}=\zeta, Y_{2}=\Phi, Y_{3}=\eta, Y_{4}=\xi, Y_{5}=A$, and $Y_{6}=C$, in (13)-(16), we obtain for $n=1, \cdots, 6$

$$
\begin{align*}
8 \frac{A^{2} \xi}{\eta^{2}} \dot{\eta}-8 \frac{A^{2}}{\eta} \dot{\xi}-16 \frac{A \xi}{\eta} \dot{A} & =-R_{\zeta}  \tag{18}\\
-4 \frac{A^{2}}{\eta^{2}} \dot{\eta}+8 \frac{A}{\eta} \dot{A} & =-R_{\Phi}  \tag{19}\\
-8 \frac{A^{2} \xi}{\eta^{2}} \dot{\zeta}+4 \frac{A^{2}}{\eta^{2}} \dot{\Phi}+\frac{\pi^{2}}{4} \frac{A^{2}}{\eta^{4}} \dot{C} & =-\frac{16 \sigma}{3} A^{2}+16 \sigma \frac{A^{2} \xi^{2}}{\eta^{2}}+\pi^{2} \sigma \frac{A^{2} C^{2}}{\eta^{4}}-\frac{16 \gamma_{0}}{3} \frac{A^{4}}{\eta^{2}}-R_{\eta},  \tag{20}\\
8 \frac{A^{2}}{\eta} \dot{\zeta} & =-32 \sigma \frac{A^{2}}{\eta} \xi-R_{\xi}  \tag{21}\\
16 \frac{A \xi}{\eta} \dot{\zeta}-8 \frac{A}{\eta} \dot{\Phi}-\frac{\pi^{2}}{6} \frac{A}{\eta^{3}} \dot{C} & =-\frac{32 \sigma}{3} A \eta-32 \sigma \frac{A \xi^{2}}{\eta}-\frac{2 \pi^{2} \sigma}{3} \frac{A C^{2}}{\eta^{3}}+\frac{64 \sigma}{3} \frac{A^{3}}{\eta}-R_{A}  \tag{22}\\
-\frac{\pi^{2}}{4} \frac{A^{2}}{\eta^{4}} \dot{\eta}+\frac{\pi^{2}}{6} \frac{A}{\eta^{3}} \dot{A} & =-\frac{2 \pi^{2} \sigma}{3} \frac{A^{2} C}{\eta^{3}}-R_{C} \tag{23}
\end{align*}
$$

respectively. By setting $A=\eta$ and $C=0$, Eqs. (18)-(23) reduce to the equations of motions for $\zeta, \Phi, \eta$ and $\xi$ obtained in [22] for a 4 -CC ansatz (see Eqs. (11)-(14) of [22]).

A very particular property of GTWM is related to its relationship with the so-called modified conservation laws, also called method of moments (the time evolution of the quantities which are conserved for the unperturbed system) [25, 26].

We define the following moments in a similar way to that in [25]. For the ansatz (4) they read

$$
\begin{align*}
N & =\int_{-\infty}^{+\infty} d x|u|^{2}=\frac{4 A^{2}}{\eta}  \tag{24}\\
N_{1} & =\int_{-\infty}^{+\infty} d x x|u|^{2}=\frac{4 A^{2}}{\eta} \zeta  \tag{25}\\
N_{2} & =\int_{-\infty}^{+\infty} d x(x-\zeta)^{2}|u|^{2}=\frac{\pi^{2}}{12} \frac{A^{2}}{\eta^{3}}  \tag{26}\\
P & =\int_{-\infty}^{+\infty} d x \frac{i}{2}\left[u u_{x}^{*}-u^{*} u_{x}\right]=-8 \frac{A^{2} \xi}{\eta}  \tag{27}\\
P_{1} & =\int_{-\infty}^{+\infty} d x \frac{i}{2}(x-\zeta)\left[u u_{x}^{*}-u^{*} u_{x}\right]=-\frac{\pi^{2}}{6} \frac{A^{2} C}{\eta^{3}} \tag{28}
\end{align*}
$$

where $N$ is the norm, $N_{1}$ is the first moment of the norm, $N_{2}$ is the second moment of the norm, $P$ is the momentum, and $P_{1}$ is the first moment of the momentum. In addition, the energy $H_{0}$ is used as the sixth moment given by Eq. (12). Notice that in [25] only 5 moments, that is, $P, N, P_{1}, N_{1}$, and $N_{2}$ were defined. These moments yield 5 equations of motion for 5 CCs. In order to obtain the sixth equation of motion, Ref. [25] used a certain identity. However, we is show that if the ansatz (4) is used, then the correct sixth equation of motion can be obtained from the time variation of the energy $H_{0}$ defined by Eq. (12) and given by Eq. (17).

From Eqs. (18) and (27), Eqs. (19) and (24), and Eqs. (23) and (26), it can be shown that Eqs. (18), (19), (21) and (23) can be rewritten in the following way

$$
\begin{align*}
\frac{d P}{d t} & =-R_{\zeta}  \tag{29}\\
\frac{d N}{d t} & =-R_{\Phi}  \tag{30}\\
\frac{d \tilde{N}_{1}}{d t} & =\dot{\zeta}=-4 \sigma \xi-\frac{\eta}{8 A^{2}} R_{\xi}  \tag{31}\\
\frac{d N_{2}}{d t} & =-\frac{2 \pi^{2} \sigma}{3} \frac{A^{2} C}{\eta^{3}}-R_{C} \tag{32}
\end{align*}
$$

where $\tilde{N}_{1}=N_{1} / N$. In other words, four of the six equation of motions are directly related with the time variation of the momentum, the norm, and the first and second moments of the norm. In [22] for an arbitrary number of CCs and arbitrary ansatz it was shown that the time variation of the energy reads

$$
\begin{equation*}
\frac{d H_{0}}{d t}=-R_{t} \tag{33}
\end{equation*}
$$

Finally, by multiplying Eq. (20) by $-\eta$, Eq. (22) by $-A / 2$, and Eq. (23) by $-2 C$, and by adding the resulting equations, we obtain

$$
\begin{equation*}
\frac{d P_{1}}{d t}=\frac{32}{3} \frac{A^{2}}{\eta}\left(\sigma \eta^{2}-\frac{\gamma_{0}}{2} A^{2}\right)+\frac{2 \pi^{2} \sigma}{3} \frac{A^{2} C^{2}}{\eta^{3}}+\frac{A}{2} R_{A}+\eta R_{\eta}+2 C R_{C} \tag{34}
\end{equation*}
$$

Hence, it is shown that, for a general perturbation and assuming the ansatz (4), the GTWM is equivalent to the time variation of the norm, the momentum, the energy, the first and second moments of the norm and the first moment of the momentum.

Clearly, the equation of motion for $\zeta$ is precisely Eq. (31). By multiplying (19) by $2 \xi$ and adding it to (18),

$$
\begin{equation*}
\dot{\xi}=\frac{\eta}{8 A^{2}} R_{\zeta}+\frac{\eta \xi}{4 A^{2}} R_{\Phi} \tag{35}
\end{equation*}
$$

By multiplying (23) by $-48 \eta^{2} / \pi^{2}$ and adding it to (19),

$$
\begin{equation*}
\dot{\eta}=4 \sigma \eta C+\frac{6}{\pi^{2}} \frac{\eta^{4}}{A^{2}} R_{C}-\frac{\eta^{2}}{8 A^{2}} R_{\Phi} \tag{36}
\end{equation*}
$$

Subsequent insertion of this expression for $\dot{\eta}$ in (19) gives

$$
\begin{equation*}
\dot{A}=2 \sigma A C+\frac{3}{\pi^{2}} \frac{\eta^{3}}{A} R_{C}-\frac{3 \eta}{16 A} R_{\Phi} \tag{37}
\end{equation*}
$$

Multiplying (22) by $A /(2 \eta)$ and adding Eq. (20), yields

$$
\begin{equation*}
\dot{C}=4 \sigma C^{2}-\frac{64}{\pi^{2}} \eta^{2}\left(\sigma \eta^{2}-\frac{\gamma_{0}}{2} A^{2}\right)-\frac{3 \eta^{3}}{\pi^{2} A} R_{A}-\frac{6 \eta^{4}}{\pi^{2} A^{2}} R_{\eta} \tag{38}
\end{equation*}
$$

The Eqs. (32), (35)-(38) agree with those obtained in [25]. However, we now show that the equation for the phase $\Phi$ can be directly obtained from the GTWM or equivalently for the time derivative of the energy. From (20) we obtain

$$
\begin{equation*}
\dot{\Phi}=2 \xi \dot{\zeta}-\frac{\pi^{2} \dot{C}}{16 \eta^{2}}-\frac{4 \sigma}{3} \eta^{2}-\frac{4 \gamma_{0}}{3} A^{2}+4 \sigma \xi^{2}+\frac{\pi^{2} C^{2}}{4 \eta^{2}}-\frac{\eta^{2}}{4 A^{2}} R_{\eta} \tag{39}
\end{equation*}
$$

It is interesting to note that this equation does not agree with that obtained in [25]. Notice that, in [25], the equation for $\Phi$ was obtained from a certain identity, which is not related with the time variation of modified conserved quantities.

## IV. PROPAGATION OF SOLITONS IN OPTICAL FIBERS

The non-linear propagation of a Raman soliton in an optical fiber can be modeled by using the generalized NLS [27]. Under certain approximations this equation becomes the perturbed NLS Eq. (1) with

$$
\begin{equation*}
R=-i \beta u+i \beta_{1} u_{x x x}-i \gamma_{1} \frac{\partial}{\partial x}\left(u|u|^{2}\right)+\gamma_{0} T_{R} u \frac{\partial|u|^{2}}{\partial x}+i \gamma_{1} T_{R} \frac{\partial}{\partial x}\left(u \frac{\partial|u|^{2}}{\partial x}\right) \tag{40}
\end{equation*}
$$

where the first term on the r.h.s. is the dissipation, the second term accounts for the third-order dispersion, the third describes the influence of self-steepening. Moreover, the term proportional to $\gamma_{0} T_{R}$ represents the intra-pulse Raman scattering, while the last term is related with the energy loss through intra-pulse Raman scattering [14]. By using the
ansatz (4) with six CCs, from Eqs. (31) and (35)-(39), and after a number of straightforward calculations, we obtain:

$$
\begin{align*}
\dot{\zeta} & =-4 \sigma \xi+4 \beta_{1} \eta^{2}+12 \beta_{1} \xi^{2}+\frac{\pi^{2}}{4} \beta_{1} \frac{C^{2}}{\eta^{2}}+4 \gamma_{1} A^{2}  \tag{41}\\
\dot{\xi} & =-\frac{64}{15} \gamma_{0} T_{R} A^{2} \eta^{2}+\frac{8}{3} \gamma_{1} A^{2} C-\frac{128}{15} \gamma_{1} T_{R} \eta^{2} A^{2} \xi  \tag{42}\\
\dot{\eta} & =4 \sigma \eta C-24 \beta_{1} \eta \xi C-\frac{128}{\pi^{2}} \gamma_{1} T_{R} A^{2} \eta^{3}  \tag{43}\\
\dot{A} & =-8 \beta A+2 \sigma A C-12 \beta_{1} A C \xi-\gamma_{1} T_{R} A^{3} \eta^{2}\left(\frac{64}{\pi^{2}}+\frac{64}{15}\right)  \tag{44}\\
\dot{C} & =4 C^{2}\left(\sigma-6 \beta_{1} \xi\right)+\frac{64}{\pi^{2}} \eta^{2}\left(\frac{\gamma_{0}}{2} A^{2}-\sigma \eta^{2}+\gamma_{1} A^{2} \xi+6 \beta_{1} \xi \eta^{2}\right)+  \tag{45}\\
& +\left(\frac{64}{\pi^{2}}-\frac{128}{15}\right) \gamma_{1} T_{R} A^{2} \eta^{2} C \\
\dot{\Phi} & =2 \xi \dot{\zeta}+4 \sigma \xi^{2}+\frac{8 \sigma}{3} \eta^{2}-\frac{10 \gamma_{0}}{3} A^{2}-8 \beta_{1} \xi^{3}-16 \beta_{1} \eta^{2} \xi-  \tag{46}\\
& -\frac{20}{3} \gamma_{1} A^{2} \xi+\gamma_{1} T_{R} A^{2} C\left(\frac{8 \pi^{2}}{45}-4\right) .
\end{align*}
$$

It is interesting to note that an ansatz with 5 CCs [12] was used in [14], which is essentially the ansatz (4) with $\Phi=\pi / 2$. Using this 5 CC ansatz, the chirp term displays oscillations which grow in amplitude. In contrast, the ansatz with 6 collective coordinates, which includes the new chirp term and the time-dependent phase has, at least, two advantages: first, the oscillations of the chirp do not grow and second, the extra equation for the phase is obtained, which is crucial for a correct physical interpretation of the canonical momentum associated to certain problems.

We now define

$$
\begin{equation*}
\sigma=-\beta_{2} / 2, \quad \beta=\alpha / 2, \quad \beta_{1}=\beta_{3} / 6 \tag{47}
\end{equation*}
$$

using the parameters of the optical fiber $\alpha, \beta_{1}$ and $\beta_{2}$. The values for the required fiber parameters are given in Table I. By using the initial conditions shown in Table II, the equations of motion are numerically solved for the six collective coordinates, Eqs. (41)-(45) and $A(t), \zeta(t), \xi(t), \eta(t), C(t)$, and $\Phi(t)$ are obtained (see Fig. 1). In Fig. 1, the soliton amplitude $A(t)$ and the inverse of the soliton width $1 / \eta(t)$ decay with a propagation distance while the soliton is accelerated. The chirp $C(t)$ oscillates with a spatial period approximately equal to 0.09 m , which is much smaller than the fiber length. Interestingly, the phase $\Phi(t)$ no longer has linear behavior as a function of the propagation distance $t$ and, due to the perturbations, non-linear terms appear in $t$.

| Parameter | Values |
| :---: | :---: |
| speed of light | $c=2.99792458 \times 10^{8} \mathrm{~m} / \mathrm{s}$ |
| center wavelength | $\lambda_{0}=1.55 \times 10^{-6} \mathrm{~m}$ |
| fiber length | 200 m |
| fiber linear loss | $\alpha=4.6 \times 10^{-5} \mathrm{~m}^{-1}$ |
| group velocity dispersion (GVD) | $\beta_{2}=-5.1 \times 10^{-27} \mathrm{~s}^{2} / \mathrm{m}$ |
| 3rd-order dispersion | $\beta_{3}=10^{-40} \mathrm{~s}^{3} / \mathrm{m}$ |
| non-linearity | $\gamma_{0}=2 \times 10^{-3} \mathrm{~W}^{-1} \mathrm{~m}^{-1}$ |
| self-steepening | $\gamma_{1}=\gamma_{0} \lambda_{0} /(2 \pi c) \mathrm{s} /(\mathrm{m} \mathrm{W})$ |
| Raman parameter | $T_{R}=2.5 \times 10^{-15} \mathrm{~s}$ |

TABLE I. Parameters of the optical fiber

By using the change of variables given by Eqs. (7), the energy $E_{p}$, the temporal shift $q_{p}$, the frequency $\Omega_{p}$, the soliton duration $T_{p}$, and the chirp $C_{p}$ are obtained as functions of the propagation distance $t$ (see Fig. 2). As $q_{p}=\zeta$, then $q_{p}$ is not plotted in Fig. 2.

In Fig. 2, the dynamics of the soliton show the expected behavior in energy $E_{p}$, frequency shift $\Omega_{p}$, and soliton duration $T_{p}$ as a function of propagation distance. In particular, the energy is decreasing due to fiber loss and intrapulse Raman scattering. The Raman scattering also leads to continuous downshift in soliton center frequency. This effect is rather strong for femtosecond solitons. As the soliton downshifts, it experiences increasing dispersion which

| Collective coordinates at $t=0$ | Values |
| :---: | :---: |
| $\mathrm{A}(0)$ | $15.97 \sqrt{J / s}$ |
| $\zeta(0)$ | 0 m |
| $\xi(0)$ | $0 \mathrm{~s}^{-1}$ |
| $\eta(0)$ | $10^{13} \mathrm{~s}^{-1}$ |
| $\mathrm{C}(0)$ | $0 \mathrm{~s}^{-2}$ |
| $\Phi(0)$ | $\pi / 2$ |

TABLE II. Initial conditions
leads to increasing duration. In Fig. 2, the normalized new chirp $C / N$ (black curve) is shown together with the normalized old chirp $C_{p} / N_{p}$ (blue curve), where the factors $N=10^{24} \mathrm{~s}^{-2}$ and $N_{p}=10^{-2}$ are used to display the curves on comparable vertical scales. Clearly, the old chirp oscillations grow as a function of propagation distance, whereas the new chirp term oscillates with a decreasing amplitude.

## V. CONCLUSIONS

For the description of NLS solitons, in particular in the application to optical solitons, we have introduced a new ansatz with six collective coordinates (CCs) which avoids certain disadvantages of the 5-CC ansatz that is widely used in the literature. The six independent CCs (the soliton position, the amplitude, the inverse of the soliton width, the velocity, the chirp, and the phase) are unknown functions of time. In optical notation, these collective coordinates correspond to the following magnitudes: the temporal shift, the energy, the soliton duration, the carrier frequency, the chirp, and phase. In contrast to a 5 -CC ansatz, with six independent CCs, we obtain three pairs of canonically conjugated variables, and hence three canonical momenta can be defined and can have physical interpretations. To this end we have given a new form to the chirp term in the $6-\mathrm{CC}$ ansatz.

As the NLS equations that describe optical solitons have several complicated perturbation terms, such as higherorder dispersion, delayed Raman response, energy loss through intra-pulse Raman scattering, and self-steepening, we apply two methods which both work for arbitrary perturbations: The Generalized Traveling Wave Method (GTWM) and the Method of Moments (MoM). Indeed, it is shown that in the case of the perturbed NLS Eq. (1), the GTWM with the ansatz (4) yields six modified conservation laws, namely the time variation of the norm, the first and second moment of the norm, the momentum, the first moment of the momentum and the energy. Therefore, both methods yield 6 identical ODEs, which are the equations of motion for the collective coordinates.

We numerically solve the resulting ODEs for the six CCs, using the parameters for a femtosecond soliton propagating in a typical dispersion-shifted fiber. We also show that the 6 - CC ansatz results in a better-behaved chirp with reduced oscillations.

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FIG. 1. $A, \zeta, \xi, \eta, C$ and $\Phi$ vs propagation distance $t$ for a large propagation distance.


FIG. 2. $E_{p}, \Omega_{p}, T_{p}$, and the normalized chirp parameter vs propagation distance $t$ for a larger fiber length. For the normalized chirp (lower right panel) an old definition $C_{p} / N_{p}$ (blue curve) displays growing oscillations, while the new definition $C / N$ (black curve) results in more subdued oscillations. Factors $N_{p}=10^{-2}$ and $N=10^{24} \mathrm{~s}^{-2}$ are used to display the curves on comparable vertical scales.
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