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Autonomic closure for turbulence simulations

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Ryan N. King^{1,2}, Peter E. Hamlington¹,^{*} and Werner J.A. Dahm³ 2 ¹Department of Mechanical Engineering, 3 University of Colorado, Boulder, CO 80309 4 ²National Renewable Energy Laboratory, Golden, Colorado 80401 and 5 ³School for Engineering of Matter. Transport. 6 & Energy, Arizona State University, Tempe, AZ 85287 7 Abstract 8 A new approach to turbulence closure is presented that eliminates the need to specify a prede-9 fined turbulence model and instead provides for fully-adaptive, self-optimizing, autonomic closures. 10 The closure is autonomic in the sense that the simulation itself determines the optimal local, in-11 stantaneous relation between any unclosed term and resolved quantities through the solution of 12 a nonlinear, nonparametric system identification problem. This nonparametric approach allows

the autonomic closure to freely adapt to varying nonlinear, nonlocal, nonequilibrium, and other

turbulence characteristics in the flow. Even a simple implementation of the autonomic closure for

large eddy simulations provides remarkably more accurate results in a priori tests than do dynamic

Autonomic Closure for Turbulence Simulations

versions of traditional prescribed closures.

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Introduction. Turbulence typically involves very wide ranges of length and time scales, which place an enormous computational burden on direct solutions of transport equations for momentum, energy, and scalars in turbulent flows. Coarse-graining [e.g., large eddy simulation (LES)] reduces this burden by solving equations for only intermediate and large scales, but nonlinearity in the original equations then introduces unclosed terms that must be modeled to achieve closure. For instance, with tildes denoting coarse-grained quantities, the incompressible momentum equation after low-pass filtering at scale $\tilde{\Delta}$ is

$$\frac{\partial}{\partial t}\widetilde{u}_i + \widetilde{u}_j \frac{\partial}{\partial x_j} \widetilde{u}_i = -\frac{\partial}{\partial x_i} \widetilde{p} + \nu \frac{\partial^2}{\partial x_j^2} \widetilde{u}_i - \frac{\partial}{\partial x_j} \tau_{ij} , \qquad (1)$$

where $\widetilde{u}_i(\mathbf{x}, t)$ and $\widetilde{p}(\mathbf{x}, t)$ are the "resolved" velocity and pressure, with the density absorbed in \widetilde{p} , and where $\tau_{ij} \equiv \widetilde{u_i u_j} - \widetilde{u}_i \widetilde{u}_j$ is the unclosed stress that accounts for local, instantaneous momentum exchange between resolved and unresolved scales. Coarse-graining of other transport equations introduces similar unclosed terms.

A central challenge in turbulence simulations is to achieve closure of coarse-grained equa-29 tions by relating unclosed terms such as τ_{ij} to resolved quantities via turbulence models. 30 Many such models have been proposed, particularly for use in LES, with the most common 31 [1–4] prescribing τ_{ij} relations that depend only on the resolved strain rate tensor, as re-32 viewed in [5]. However since coarse graining was introduced, more than 50 years of research 33 has failed to provide universal models for τ_{ij} or other unclosed terms that reliably account 34 for nonlinear, nonlocal, nonequilibrium, and other turbulence effects [6–8] with fidelity ap-35 proaching that of direct simulation in the resolved scales at all local flow conditions. 36

Autonomic Closure Approach. Here we take a completely different approach to turbulence closure that circumvents the need to prescribe a fixed relation between unclosed terms and resolved variables. Rather than specifying a prescribed model for the unclosed stress τ_{ij} or other unclosed terms, we instead use a fully general nonparametric relation \mathcal{F} that represents the true unclosed quantity in terms of all resolved variables at all points and all prior times. For example, to model τ_{ij} in incompressible turbulence this fully general nonparametric relation for the stress can be expressed as

$$\tau_{ij}^{\mathcal{F}}(\mathbf{x},t) \equiv \mathcal{F}_{ij}\left[\widetilde{\mathbf{u}}(\mathbf{x}+\mathbf{x}',t-t'), \ \widetilde{p}(\mathbf{x}+\mathbf{x}',t-t') \ \forall \ \mathbf{x}',t' \ge 0\right],$$
(2)

where (\mathbf{x}', t') is a stencil with center point (\mathbf{x}, t) on which the resolved variables in \mathcal{F}_{ij} are defined and $\tau_{ij}^{\mathcal{F}}$ represents the true stress τ_{ij} . Due to its generality, \mathcal{F}_{ij} will typically ⁴⁶ have a very large number of degrees of freedom, and is thereby free to adapt to the local,
⁴⁷ instantaneous turbulence state in the flow.

The particular form of the general relation \mathcal{F}_{ij} is determined at each point and time using system identification based on test filtering. Resolved variables are filtered at a test scale $\widehat{\Delta} > \widetilde{\Delta}$ to yield test-filtered resolved variables, such as $\widehat{\widetilde{u}}(\mathbf{x},t)$ and $\widehat{\widetilde{p}}(\mathbf{x},t)$, which are then used to obtain a test field for the unclosed quantity; e.g., for $\tau_{ij} \equiv \widetilde{u_i u_j} - \widetilde{u}_i \widetilde{u}_j$ the test field is $T_{ij} \equiv \widehat{\widetilde{u}_i \widetilde{u}_j} - \widehat{\widetilde{u}_i} \widehat{\widetilde{u}_j}$. The same nonparametric relation \mathcal{F}_{ij} introduced in Eq. (2) is used to relate the known test field to known test-filtered variables. Thus, for instance, analogous to Eq. (2)

$$T_{ij}^{\mathcal{F}}(\mathbf{x},t) \equiv \mathcal{F}_{ij}\left[\widehat{\widetilde{\mathbf{u}}}(\mathbf{x}+\mathbf{x}',t-t'),\widehat{\widetilde{p}}(\mathbf{x}+\mathbf{x}',t-t') \,\forall \,\mathbf{x}',t' \ge 0\right].$$
(3)

Values for the degrees of freedom in \mathcal{F}_{ij} are determined by optimizing the local, instantaneous agreement of $T_{ij}^{\mathcal{F}}$ with T_{ij} via minimization of a suitably defined objective function

$$\mathcal{J}_{ij}\left(\mathbf{x},t\right) = E\left[T_{ij}\left(\mathbf{x},t\right), T_{ij}^{\mathcal{F}}(\mathbf{x},t)\right]$$
(4)

that measures the error in representing $T_{ij}(\mathbf{x},t)$ with $T_{ij}^{\mathcal{F}}(\mathbf{x},t)$ and which may include regu-57 larization. For example, E could be based on the ℓ_2 norm of local instantaneous differences 58 between $T_{ij}(\mathbf{x},t)$ and $T_{ij}^{\mathcal{F}}(\mathbf{x},t)$ over P distinct stencil center points sampled from a region 59 in which the turbulence state – and thus the relation \mathcal{F}_{ij} – is taken to be uniform. This is 60 typically a local region centered on (\mathbf{x}, t) , but could extend in homogeneous directions or 61 along Lagrangian paths. The sample region could in some cases span the full computational 62 domain, but is typically much smaller to allow \mathcal{F}_{ij} to adapt to local, instantaneous changes 63 in the turbulence state, with the sampling being repeated over the full domain. Regular-64 ization in Eq. (4) ensures that \mathcal{F}_{ij} stably generalizes to points in the same turbulence state 65 that were not included in the set of P stencil center points. Once the degrees of freedom in 66 \mathcal{F}_{ij} have been determined in this way, the resulting locally optimal form of \mathcal{F}_{ij} is then used 67 in Eq. (2) to obtain the local, instantaneous value of $\tau_{ij}^{\mathcal{F}}$. 68

The same procedure can be implemented for any other unclosed quantity. In effect, we solve a local nonlinear system identification problem at the test scale to determine the optimal local instantaneous degrees of freedom in the nonparameteric relation \mathcal{F} . This can be repeated at every point and every time in the simulation, so that a new locally optimal relation between the unclosed quantity and all resolved variables is determined at each point and time. This approach is therefore a fully-adaptive, self-optimizing autonomic closure for
 coarse-grained equations.

The closure is "autonomic" in the sense that the simulation itself determines the opti-76 mal local, instantaneous relation between the unclosed quantity and resolved variables. In 77 particular, \mathcal{F} is free at each point and time to adapt as needed to the relative degree of non-78 linear, nonlocal, nonequilibrium, and other turbulence effects in the flow. In a sense, this 79 new closure approach can be regarded as a nonparametric generalization of the dynamic 80 approach used with various prescribed closure models, such as the dynamic Smagorinsky 81 model [3, 4]. Computational costs associated with this autonomic closure can be controlled 82 by limiting the degrees of freedom in \mathcal{F} and reducing the size of the spatio-temporal stencil 83 (\mathbf{x}', t') associated with its inputs. 84

It will be shown here through *a priori* tests involving τ_{ij} that even simple implementations of this autonomic approach can provide far more accurate closures for unclosed terms than do dynamic versions of traditional prescribed closure models.

Example of a General Nonparametric Relation \mathcal{F} . Although any sufficiently general form could be used, here we show an example of a fully general nonparametric relation that may be used for autonomic closure of τ_{ij} . In this example, we choose \mathcal{F}_{ij} in Eqs. (2) and (3) to be a Volterra series [9], namely a sum of multidimensional convolutions over all possible linear and nonlinear combinations of all resolved variables at all points and times. For instance, the Nth-order Volterra series for an *M*-dimensional multivariate input vector $\mathbf{v}(t)$ and scalar output y(t), namely $y(t) = \mathcal{F}[\mathbf{v}(t)]$, is given by

$$y(t) = h^{(0)} + \sum_{n=1}^{N} \left[\sum_{m_1=1}^{M} \cdots \sum_{m_n=1}^{M} \right] \int_{\mathbb{R}^n} h^{(n)}_{m_1 \cdots m_n} (\tau_1, \cdots, \tau_n) \prod_{p=1}^n v_{m_p} (t - \tau_p) \, \mathrm{d}\tau_p \,, \tag{5}$$

⁹⁵ where $h_{m_1\cdots m_n}^{(n)}$ are Volterra coefficients that are formally related to partial derivatives of ⁹⁶ \mathcal{F} . For systems with fading memory and bounded inputs, the Stone-Weierstrass theorem ⁹⁷ guarantees that any continuous function can be represented to within arbitrary precision by ⁹⁸ a Volterra series of sufficient but finite order [10].

⁹⁹ The continuous Volterra series in Eq. (2) can be written in discrete form for implemen-¹⁰⁰ tation in turbulence simulations. For N_v resolved variables on a discrete spatio-temporal ¹⁰¹ stencil with $[N_x, N_y, N_z]$ spatial points and N_t times, the number of variables in the input vector is $M = N_v N_x N_y N_z N_t$. The resulting Nth-order discrete Volterra series for \mathcal{F}_{ij} is then

$$\mathcal{F}_{ij} = h_{ij}^{(0)} + \sum_{n=1}^{N} \left[\sum_{m_1=1}^{M} \cdots \sum_{m_n=m_{n-1}}^{M} \right] h_{ij,m_1\cdots m_n}^{(n)} \prod_{p=1}^{n} \widetilde{v}_{m_p} , \qquad (6)$$

where the lower bounds on the summations span only unique variable combinations while still allowing for variable repetition in the products. In this example, the input vector \tilde{v} in Eq. (6) consists of \tilde{u} and \tilde{p} at all points and times (\mathbf{x}', t') in the spatio-temporal stencil, namely

$$\widetilde{\boldsymbol{v}}(\mathbf{x},t) = \{ \operatorname{vec} \left[\widetilde{u}_1(\mathbf{x} + \mathbf{x}', t - t') \forall \mathbf{x}', t' \ge 0 \right], \operatorname{vec} \left[\widetilde{u}_2(\mathbf{x} + \mathbf{x}', t - t') \forall \mathbf{x}', t' \ge 0 \right],$$
(7)
$$\operatorname{vec} \left[\widetilde{u}_3(\mathbf{x} + \mathbf{x}', t - t') \forall \mathbf{x}', t' \ge 0 \right], \operatorname{vec} \left[\widetilde{p}(\mathbf{x} + \mathbf{x}', t - t') \forall \mathbf{x}', t' \ge 0 \right] \}^{\mathsf{T}}.$$

Each (ij) in Eq. (6) has a set of coefficients $\mathbf{h}_{ij} \equiv h_{m_1\cdots m_n}^{(n)}$ which, once determined, allows the stress $\tau_{ij}^{\mathcal{F}}$ in Eq. (2) to be obtained from resolved variables $\tilde{\boldsymbol{v}}$ on the stencil.

Since Eq. (6) is a sum of all possible multi-point products of all orders among all resolved variables at all locations and times on the stencil, this general relation can represent many mathematical operations among the resolved variables, including multi-point differences and products, spatial and temporal derivatives, filters, and others depending on the coefficients \mathbf{h}_{ij} . Thus, in addition to many other fluid dynamically recognizable quantities, the autonomic closure allows τ_{ij} to locally depend on the resolved strain rate but, as previously recommended [11], does not require or impose any such dependence.

For each (ij) in Eq. (6) the total number of coefficients in \mathbf{h}_{ij} is $N_c = (M+N)!/(N!M!)$, so N_c becomes very large as the series order N and stencil size M become large. However, truncation of the series and limitation of the stencil size allows determination of \mathbf{h}_{ij} in the autonomic closure to become sufficiently manageable for implementation in practical turbulence simulations.

Implementation of Autonomic Closure. For example, the objective function in Eq. (4) may be represented using a mean squared error for E with Tikhonov regularization. With $T_{ij}^{\mathcal{F}}(\mathbf{x},t)$ given by \mathcal{F}_{ij} in Eq. (6), this is equivalent to a damped least squares minimization, namely

min
$$\mathcal{J}_{ij}(\mathbf{x},t) = \|\mathbf{T}_{ij} - \mathbf{V}\mathbf{h}_{ij}\|^2 + \lambda \|\mathbf{h}_{ij}\|^2,$$
 (8)

where $\|\cdot\|$ is the ℓ_2 norm, \mathbf{T}_{ij} is a $P \times 1$ column vector composed of the known test stresses $T_{ij}(\mathbf{x}, t)$ at the P stencil center points (\mathbf{x}, t) , \mathbf{h}_{ij} is the $N_c \times 1$ column vector of unknown ¹²⁷ coefficients, and **V** represents the $P \times N_c$ array of all linear and nonlinear combinations of ¹²⁸ the input vector $\hat{\widetilde{v}}(\mathbf{x},t)$, each row of which corresponds to a different stencil center point ¹²⁹ (\mathbf{x},t) . Here $\hat{\widetilde{v}}$ is composed of $\hat{\widetilde{u}}_i$ and $\hat{\widetilde{p}}$ and is the test-scale analog of \widetilde{v} in Eq. (7). Since ¹³⁰ \mathbf{T}_{ij} and **V** are known at the test scale, Eq. (8) can be solved for \mathbf{h}_{ij} . For $\lambda > 0$, the least ¹³¹ squares problem is full rank and can be solved as

$$\mathbf{h}_{ij} = \left(\mathbf{V}^{\mathsf{T}}\mathbf{V} + \lambda \mathbf{I}\right)^{-1} \mathbf{V}^{\mathsf{T}}\mathbf{T}_{ij} \,. \tag{9}$$

This smoothly damps small singular values of $\mathbf{V}^{\mathsf{T}}\mathbf{V}$ that would otherwise generate instabilities, and also ensures that the solution is full rank even in the event that $P < N_c$.

Once the local coefficients \mathbf{h}_{ij} are determined at the test scale from Eq. (8), they are 134 projected to the original coarse-grain scale where \mathcal{F} can be used to evaluate the local un-135 closed quantity, as in Eq. (2). In effect, the local, instantaneous coefficients \mathbf{h}_{ij} characterize 136 the local, instantaneous state of the turbulence, including the extent of nonlinear, nonlocal, 137 nonequilibrium, and other characteristics of the turbulence at that point and time. When 138 the coarse-grain and test-filter scales are sufficiently close, the relative effect of these char-139 acteristics should locally be the same in the coarse-grain fields as in the test fields, and thus 140 \mathbf{h}_{ij} should also be the same. 141

Demonstration and Tests of Autonomic Closure. We now show a simple demonstration 142 of autonomic closure and use it in *a priori* tests to assess the accuracy and utility of this 143 new turbulence closure approach. Specifically, we represent τ_{ij} with the Volterra series form 144 in Eq. (6) and use Eq. (7) to write the input vector $\tilde{\boldsymbol{v}}$ in terms of \tilde{u}_i and \tilde{p} $(N_v = 4)$, but we 145 truncate the series after second order (N = 2) and use only time-local variables $(N_t = 1)$ on 146 a $3 \times 3 \times 3$ spatial stencil, giving M = 108 and $N_c = 5995$. The large number of coefficients 147 \mathbf{h}_{ij} is due to the many multipoint second-order products that can be formed from \widetilde{u}_i and \widetilde{p} 148 on even this small stencil. 149

Using spectrally sharp filters applied to data from a 1024^3 pseudo-spectral direct numerical simulation (DNS) of homogeneous isotropic turbulence at $\text{Re}_{\lambda} = 433$ in the Johns Hopkins Turbulence Database [12], the velocity and pressure fields are coarse-grained and test-filtered to, respectively, retain 30 and 15 Fourier modes. The sample region here spans the entire domain, although smaller regions could be used instead to reveal local variations in the turbulence state via \mathbf{h}_{ij} . Across the sample region we sample at 25 equally-spaced increments along each direction, giving P = 15,625 total points and providing an overdetermined system for \mathbf{h}_{ij} , which is solved using Eq. (9).

Figure 1 shows typical examples of test stress fields $T_{ij}(\mathbf{x},t)$ and corresponding $T_{ij}^{\mathcal{F}}(\mathbf{x},t)$ 158 fields resulting from the least-squares minimization for \mathbf{h}_{ij} . It is apparent that even this 159 relatively simple \mathcal{F}_{ij} is sufficient to represent most of the features in the test stresses $T_{ij}(\mathbf{x}, t)$. 160 Also shown for comparison is the corresponding representation of the test stresses from the 161 dynamic Smagorinsky (DS) model of Lilly [4] with no additional averaging or clipping, 162 denoted $T_{ij}^{DS}(\mathbf{x},t)$. The DS model is chosen for comparison due to its widespread use and 163 because, similar to the current approach, it effectively requires the solution of an optimization 164 problem to determine a variable model coefficient. It is apparent from Fig. 1 that the highly 165 prescriptive relation in the DS model between the test stresses and the test-filtered variables 166 is far less able to represent features in $T_{ij}(\mathbf{x},t)$ than the autonomic closure. 167

Figure 2 shows corresponding results for the turbulent stress field $\tau_{ij}(\mathbf{x}, t)$ to allow comparison with the autonomic closure representation $\tau_{ij}^{\mathcal{F}}(\mathbf{x}, t)$, which uses the same \mathbf{h}_{ij} determined at the test filter scale in Fig. 1. Also shown for comparison are corresponding results $\tau_{ij}^{DS}(\mathbf{x}, t)$ from the DS model. It is apparent that $\tau_{ij}^{\mathcal{F}}(\mathbf{x}, t)$ from the autonomic closure provides a remarkably accurate representation of the true stress $\tau_{ij}(\mathbf{x}, t)$, especially in view of the global optimization used here, while $\tau_{ij}^{DS}(\mathbf{x}, t)$ has nearly no correlation with features in $\tau_{ij}(\mathbf{x}, t)$.

Figure 3 uses probability densities to compare test stress values T_{ij} with $T_{ij}^{\mathcal{F}}$ and T_{ij}^{DS} , and turbulent stress values τ_{ij} with $\tau_{ij}^{\mathcal{F}}$ and τ_{ij}^{DS} . The distributions $T_{ij}^{\mathcal{F}}$ and $\tau_{ij}^{\mathcal{F}}$ from the autonomic closure agree remarkably well with the true stress distributions T_{ij} and τ_{ij} , while those from the DS model greatly overpredict the occurrence of large positive and negative stress values.

Figure 4 similarly compares the kinetic energy flux between resolved and unresolved 180 scales, $\widetilde{P}(\mathbf{x},t) = \tau_{ij}\widetilde{S}_{ij}$, with corresponding results $\widetilde{P}^{\mathcal{F}}(\mathbf{x},t)$ from the autonomic closure and 181 $\tilde{P}^{DS}(\mathbf{x},t)$ from the DS model, each obtained from their corresponding stress fields. It is 182 apparent that the autonomic closure provides remarkably accurate results for $\widetilde{P}(\mathbf{x},t)$ and 183 its distribution, while the DS model essentially matches only the average energy flux and has 184 nearly no correlation with the actual energy transfer field. This is verified in the probability 185 densities in Fig. 5, where even this simple autonomic closure is seen to provide accurate 186 results for the distribution of energy flux values, while the prescribed (DS) closure greatly 187 overpredicts large positive and negative energy flux values. 188

Summary and Conclusions. The autonomic approach to turbulence closure presented 189 here provides a fully-adaptive, self-optimizing way to treat unclosed terms in coarse-grained 190 equations, based on a locally optimal relation between the unclosed quantity and all re-191 solved variables at each point and time. The nonparametric nature of the approach allows 192 the closure relation to freely adapt to varying nonlinear, nonlocal, nonequilibrium, and other 193 turbulence characteristics throughout the flow. By limiting the degrees of freedom in the 194 general relation and reducing the size of the stencil on which it is implemented, the com-195 putational cost associated with the autonomic closure can be managed. Even the simple 196 implementation of the autonomic closure demonstrated here gives remarkably more accurate 197 results than dynamic versions of traditional prescribed turbulence models. 198

¹⁹⁹ The autonomic approach also provides a means for "model discovery" by finding optimal ²⁰⁰ coefficients \mathbf{h}_{ij} at a test scale that give effective representations for unclosed terms. These ²⁰¹ coefficients and the associated stencil then provide an autonomically-discovered static model ²⁰² that can be broadly implemented. Furthermore, the resulting \mathbf{h}_{ij} can be decomposed into ²⁰³ any desired set of fluid dynamically recognizable quantities that can be formed from the ²⁰⁴ resolved variables on the chosen stencil, thereby providing autonomically-enabled insights ²⁰⁵ into local turbulence physics; e.g., in near-wall turbulence.

This new closure is broadly related to recent applications of machine-learning approaches to turbulence simulations (e.g., [13–16]). A key distinction is that the autonomic closure does not require external training data. In effect, the test fields here provide internal training data and the scale-invariance of local turbulence characteristics between the test-filter and coarse-grain scales allows the local degrees of freedom in the general nonparametric relation \mathcal{F} to be projected from one scale to the other.

We have shown results from a priori tests of autonomic closure for LES, but full assess-212 ment of the performance and accuracy of this new approach also requires a posteriori tests 213 to investigate matters such as numerical stability, computational cost, and closure accuracy 214 for non-spectrally sharp filters. In particular, accurate predictions of forward and backward 215 scatter of kinetic energy, as well as the duration of backward scatter events, are critical 216 for ensuring that the closure is both realistic and stable in simulations. The present results 217 show that both forward and backward scatter of kinetic energy in $\widetilde{P}(\mathbf{x},t)$ flux fields from the 218 autonomic closure agree well with corresponding DNS fields, in contrast to the largely un-219 physical fluxes predicted by the dynamic Smagorinsky model. Although some prior models 220

showing improved agreement in *a priori* tests, such as the similarity model [17], are known to be insufficiently dissipative, it is anticipated that the large number of degrees of freedom in the autonomic closure may enable accurate predictions of backscatter and dissipation across a wide range of local turbulence states. Ongoing work is also exploring whether test filtering can be similarly applied to ensemble-averaged fields in order to allow the approach presented here to extend to autonomic closure of ensemble (Reynolds) averaged turbulence simulations.

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FIG. 1. Test stress fields $T_{11}(\mathbf{x}, t)$ (top row), $T_{12}(\mathbf{x}, t)$ (middle row), and $T_{13}(\mathbf{x}, t)$ (bottom row), showing results for (left column) the true stress $T_{ij}(\mathbf{x}, t)$, (middle column) the autonomic stress $T_{ij}^{\mathcal{F}}(\mathbf{x}, t)$, and (right column) the stress $T_{ij}^{DS}(\mathbf{x}, t)$ from the dynamic Smagorinsky model. (color online)



FIG. 2. Coarse-grained turbulent stress fields $\tau_{11}(\mathbf{x}, t)$ (top row), $\tau_{12}(\mathbf{x}, t)$ (middle row), and $\tau_{13}(\mathbf{x}, t)$ (bottom row), showing results for (left column) the true stress $\tau_{ij}(\mathbf{x}, t)$, (middle column) the autonomic closure $\tau_{ij}^{\mathcal{F}}(\mathbf{x}, t)$, and (right column) the dynamic Smagorinsky model $\tau_{ij}^{DS}(\mathbf{x}, t)$. (color online)



FIG. 3. Probability densities of turbulent stress components at the test-filter scale (top row) and coarse-grain scale (bottom row), showing results for T_{11} and τ_{11} (left column), T_{12} and τ_{12} (middle column), and T_{13} and τ_{13} (right column), showing densities for the true stresses from DNS (black lines), stresses from the autonomic closure (red lines), and stresses from the dynamic Smagorinsky model (blue lines). (color online)



FIG. 4. Kinetic energy flux fields at the test-filter scale (top row) and coarse-grain scale (bottom row), showing results for the true flux fields $\tilde{P}(\mathbf{x},t)$ (left), the fields $\tilde{P}^{\mathcal{F}}(\mathbf{x},t)$ resulting from the autonomic closure (center), and the fields $\tilde{P}^{DS}(\mathbf{x},t)$ from the dynamic Smagorinsky model. Even this simple implementation of autonomic closure is far more accurate than the prescribed closure in the dynamic Smagorinsky model. (color online)



FIG. 5. Probability densities of kinetic energy fluxes (a) \hat{P} at the test-filter scale and (b) \tilde{P} at the coarse-grain scale, showing distributions of the true fluxes from DNS (black lines), fluxes from the autonomic closure (red lines), and fluxes from the dynamic Smagorinsky model (blue lines). (color online)