Efficiency of message transmission using biased random walks in complex networks in the presence of traps

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Abstract

We study the problem of a particle/message that travels as a biased random walk towards a target node in a network in the presence of traps. The bias is represented as the probability p of the particle to travel along the shortest path to the target node. The efficiency of the transmission process is expressed through the fraction f_g of particles that succeed to reach the target without being trapped. By relating f_g with the number S of nodes visited before reaching the target, we firstly show that, for the unbiased random walk, f_g is inversely proportional to both the concentration c of traps and the size N of the network. For the case of biased walks, a simple approximation of S provides an analytical solution that describes well the behavior of f_g, especially for $p > 0.5$. Also, it is shown that for a given value of the bias p, when the concentration of traps is less than a threshold value equal to the inverse of the Mean First Passage Time (MFPT) between two randomly chosen nodes of the network, the efficiency of transmission is unaffected by the presence of traps and almost all the particles arrive at the target. As a consequence, for a given concentration of traps, we can estimate the minimum bias that is needed to have unaffected transmission, especially in the case of Random Regular (RR), Erdős-Rényi (ER) and Scale-Free (SF) networks, where an exact expression (RR and ER) or an upper bound (SF) of the MFPT is known analytically. We also study analytically and numerically, the fraction f_g of particles that reach the target on SF networks, where a single trap is placed on the highest degree node. For the unbiased random walk, we find that $f_g \sim N^{-1/(\gamma-1)}$, where γ is the power law exponent of the SF network.

I. INTRODUCTION

An important process usually associated with random walks is trapping. Trapping reactions have been widely studied as part of the general reaction-diffusion scheme. The trapping reaction can be formulated as: $A + T \rightarrow T$, where T is a static trap and A is a diffusing species that is annihilated irreversibly when it comes in contact with the trap. The problem has been studied in a variety of geometries, such as regular lattices, in fractal spaces [1–5] and recently, in small-world [6], Erdős-Rényi [7, 8], and scale-free networks [7–9].

Such trapping processes can be related to the efficiency of message transmission in networks in the presence of one or more traps. The problem can be regarded of as an analogue for the propagation of information in certain communication networks in the form of packets. This follows since in some cases data packets traverse the network in a random fashion (for example, in wireless sensor networks [10], ad-hoc networks [11] and peer-to-peer networks [12]). A trap acts as a node which is malfunctioning and where information is lost, e.g. like a router which can receive but not transmit data due to a malfunction or an e-mail server unable to forward incoming mails. However, information about the structure of the network might provide an opportunity to send a message with a bias towards the target. In [13], it was shown that using such a bias significantly reduces the time of diffusion from the source to the target. In ER networks there exists a threshold value of the bias parameter delimiting a power law and a logarithmic scaling of the MFPT with the size N of the network. In SF networks, the scaling of the MFPT with network dimensions is always less than a power of $\log N$, i.e the gain of time is very important in SF networks, even for a small value of the bias parameter. When a certain number of nodes or a single important node, such as a hub, lose their functionality and act like traps, since some messages going threw these nodes will never arrive to their target, it is of interest to know the percentage of messages that are lost. It is, therefore, important to see if and how applying a bias towards the target nodes can help in saving messages.

II. MODEL AND METHODS

Our model can be described as follows: Messages start to be transmitted from a source node, with a target node as a destination. Both source and target nodes are chosen randomly

from the total number of network nodes, but always on the giant connected component. Messages may diffuse on the network randomly, or with a bias toward the target node. Traps act as malfunctioning nodes in which information is lost (e.g., a router which cannot transmit data due to some failure). We use Monte Carlo computer simulations. As described in [13], at each step, the particle travels either on a shortest path towards the target, with a probability $0 \leq p \leq 1$, or randomly to one of its node neighbors with a probability $1 - p$. The particle may be trapped before it arrives on the target. The efficiency of transmission from the source to the target node is given by f_g, which is the fraction of particles that arrive from the source to the target. Obviously, the closer this value is to 1, the more efficient the transmission process is.

The algorithm of the model may be described as follows:

1. A pair of random nodes is selected as source and target nodes. A particle begins moving on the network from the source node.

2. At each time step the particle hops to an adjacent node along the shortest path (between source and target) with probability p, or to a random node (including these on the shortest path) with probability $1 - p$

3. If the particle is trapped or arrives on target go to step 1, else go to step 2 (i.e. perform another time step)

We consider the process only on the largest cluster of the network. We perform a total of 10^5 realizations using 100 different networks, while performing walks between 1000 pairs of random source-target nodes on each network.

III. RESULTS FOR CONCENTRATION OF TRAPS

A key quantity for solving the problem of trapping is the number of distinct nodes S visited before reaching the target. Indeed, f_g is in reality the survival probability of the particles until meeting the target. If we denote by $q_{S=m}$ the probability that the number of distinct nodes visited before reaching the target is equal to m, then the fraction f_g of particles that succeed to reach the target without being trapped can be expressed exactly

as the following sum:

$$f_g = \sum_{m=1}^{m=N} q_{S=m}(1-c)^{m-1}. \tag{1}$$

For the unbiased random walk, since each node of the network (except the source) has the same probability of being the target, f_g can be easily estimated:

$$f_g = \sum_{m=1}^{m=N} q_{S=m}(1-c)^{m-1} \approx \frac{1}{N-1} \int_{m=1}^{m=N} e^{-c(m-1)} dm \approx \frac{1}{Nc}. \tag{2}$$

Firstly, we plot the transmission efficiency of the biased random walk in the presence of a concentration c of traps in ER networks obtained by simulations. In Fig. 1(a), we plot the fraction of particles that arrive on targets f_g, as a function of the concentration of traps c for different values of the bias parameters in ER networks. Eq. (1) is tested in Fig. 1(c) by plotting both the results from simulations with traps (full symbols) and the evaluation of Eq. (1) (continuous lines) where $q_{S=m}$ is obtained from simulations without traps, see Fig. 1(d). As expected from Eq. (2), we see in Figs. 1(a) and 1(b) that the probability that the unbiased particle will arrive at the target before meeting a trap is inversely proportional to both the size of the system and the concentration of traps. However, the situation is different for biased random walks. Indeed, in Fig. 1 we see that, for low values of c, the particle may not hit the traps even with a relatively very small bias, and practically all particles arrive their target. For higher concentration of traps one needs stronger bias to survive and reach the target. This follows, because a stronger bias towards the target makes the path length shorter which helps to encounter less possible traps. Note that for small bias p, and for intermediate range of c, f_g is almost parallel to f_g at $p = 0$. This suggests that in this range also the survival, f_g, of biased particles is inversely proportional to c. We hypothesize that this crossover is due to two competing time scales. One is the typical time a walker does not encounter traps, $1/c$, and the second is the mean first passage time (MFPT) from source to target without the presence of traps. We test this hypothesis in the scaling of Fig. 2.

In Fig.2, we plot the same data as in Fig. 1 but instead of c on the x axes we use cT_D, where T_D is the MFPT from the source to the target in the case with no traps calculated from Eqs. (4) and (5). Indeed, except from very high concentration of traps (order 1) the curves collapse into a single curve. This collapse clearly suggests the above discussed two distinct time scales and a crossover point corresponding to a threshold concentration

$$c_{th} \cong T_D^{-1}. \tag{3}$$

For $c < c_{th}$ the concentration of traps does not affect at all the transmission efficiency and practically $f_g \approx 1$. This seems reasonable since $1/c$ can be considered as the mean time spent between traps and if the time to reach the target is less than the time to diffuse from one trap to the other then the particle practically will not meet the traps. This result gives us a relation that connects directly the concentration of traps in a network of size N with the value of the minimum bias parameter p_m that is needed to have completely full efficiency. In [13], the MFPT was found analytically for RR and ER networks for every value of the bias parameter, see Eqs. (4) and (5). Thus, in both RR and ER networks with a concentration c of traps, p_m can be found easily by solving the following equation:

$$T_D = \frac{D}{2p'_m - 1} + \frac{1 - p'_m}{(2p'_m - 1)^2} \left[\left(\frac{1 - p'_m}{p'_m} \right)^D - 1 \right] = \frac{1}{c}, \tag{4}$$

where $p'_m = p_m + (1 - p_m)/\langle k \rangle$ and

$$D = \frac{\ln\left(1 + (\langle k \rangle - 2)(N - 1)/\langle k \rangle\right)}{\ln(\langle k \rangle - 1)} \approx \frac{\ln\left((\langle k \rangle - 2)N/\langle k \rangle\right)}{\ln(\langle k \rangle - 1)}. \tag{5}$$

Furthermore, in Figs. 1 and 2 we see that for $c > c_{th}(p)$ the transmission efficiency is strongly affected by traps and all the curves follow the unbiased one that has a slope of -1 in the log-log plot except for very large c of order 1.

We also study f_g for scale free networks with degree distribution $p(k) \sim k^{-\gamma}$ [14–16]. We find in SF networks similar behavior, see Fig. 3, and there is a similar abrupt decay of f_g above c_{th}. However, in this case the MFPT is not known analytically for every value of p. Instead, it is possible to use the upper bound value of the MFPT [13]. It will not give the minimum value p_m, but a certainly secured value with applicability to real networks. Our results on SF suggest that it is possible to secure almost all the messages by only applying a minimum, often very small, bias. What is needed for this is a minimal knowledge of the structure of the network or a strategy to increase the probability to get closer to the target at each step. In comparison with ER networks, we see that in SF networks a smaller bias is needed to have a significant improvement in f_g. This is mainly due to the MFPT, which is significantly smaller in a SF networks compared to ER networks when a bias towards the target is applied [13]. This is since, due to hubs, the distances between sources and targets

are smaller on the order of $\log(\log N)$ [17] compared to ER for which the distances scale as $\log N$ [18].

According to Eq. (1), the key quantity is the distribution q_S of the number of distinct nodes S visited before meeting the target. Even if it is difficult to find an analytic expression of the function q_S for all cases, we can still approximate q_S in two regimes. For a sufficiently large value of the bias parameter, p, and low concentration of traps, $c < c_{th}$, the distribution of S is not so broad. In this case, we can find an approximation for the mean value of S by considering the typically tree-like structure of ER networks (see Fig. 4). When the particle deviates from the shortest path, we assume that it passes twice the same nodes and the mean number of distinct nodes visited can then be approximated by:

$$S \simeq D + \frac{1}{2}(T_D - D) = \frac{1}{2}(T_D + D), \tag{6}$$

where T_D and D are the known MFPT and mean shortest distance in the network, respectively. Thus, using Eq. (1), f_g can be approximated by the following expression

$$f_g \simeq (1 - c)^{\frac{1}{2}(T_D + D)} \qquad (c < c_{th}). \tag{7}$$

For $c > c_{th}$, the probability to hit the target before any other trap is proportional to $1/c$,

$$f_g \simeq \frac{A(p)}{c}, \qquad (c > c_{th}) \tag{8}$$

where $A(p)$ can be calculated for each p by solving:

$$\frac{A(p)}{c_{th}} = (1 - c_{th})^{\frac{1}{2}(T_D + D)}. \tag{9}$$

Since we know analytically both D and T_D for ER networks, it is possible to test the validity of this approximation. In Fig. 5, we compare simulation results (symbols) and the corresponding approximated curves obtained by using Eqs. (7) and (8). We see that very simple arguments give a surprisingly good analytic approximation, even for relatively small bias.

It is also useful to investigate the dependence of the average time of the survived particles to reach the target, $\langle t_{target} \rangle$, on p in the presence of traps. In Fig. 6 we analyze $\langle t_{target} \rangle$ and find that the bias p has a significant effect on the average time, decreasing it, only for values of p above a certain threshold, which depends on the concentration of traps (higher values for higher concentrations). When the bias is low, since only very few walks reach the

target, representing the case where the target is very close to the source, we get a MFPT which is constant in p and N and depends only on c (as $1/c$, which is the average time between traps). This contains only the case in which we hit the target by chance, with no bias towards it, and thus the time is independent of p and N. Thus, when the bias is low, the process is controlled by the presence of traps and the distance between the traps is the important parameter controlling the diffusion time, $\langle t_{target} \rangle \sim 1/c$, see dotted lines in Fig. 6. On the other hand, when the bias becomes important the average time to diffuse to the target becomes less than $1/c$ and the process is controlled by the dependence of the MFPT on the bias parameter p (red bold curve in Fig. 6).

IV.   SINGLE TRAP - SF NETWORKS

We are now interested in a scenario where a central hub of the network fails, as may be the case with real world networks since this kind of nodes is very prone to attacks. In this case, we assume that a single trap is placed on the highest degree node, k_{max} of the network. When only one trap is present on the highest connected node of the network, we can use the following simple argument to evaluate f_g. We consider that all the k_{max} nodes that are connected with the hub act like traps since they drive the particle to the trap. Thus, for the unbiased case, we can use k_{max}/N instead of c in equation (2). Thus, we assume,

$$f_g \sim \frac{1}{k_{max}}. \tag{10}$$

The scaling of k_{max} with the size of the network is known for all γ values to be $k_{max} \sim N^{\frac{1}{\gamma-1}}$ [19]. Thus, for the random walk case, without bias, we have

$$f_g \sim N^{-\frac{1}{\gamma-1}}. \tag{11}$$

In Figs. 7(a) and 7(b) we see the results for the scaling of f_g with system size N for various p values in SF networks with $\gamma = 2.2$ and 3, respectively, when a single trap is present on the most connected node. For the unbiased walk the dependance of the slope on γ is in very good agreement with Eq. (11) (see also Fig. 8). This relation shows the increasing role of the hub when γ is decreased. For small γ, most particles traversing the network need to pass through the hub and are subsequently trapped while for higher γ values, the particle is more likely to find the target without passing from through the hub. When considering a

biased random walk, the general picture from figures 7(a) and 7(b) is that when the size of the network becomes sufficiently large, f_g remains almost unaffected by system size for every value of p. This means that in a SF network with failure of the most connected node, even a small bias can vastly improve the transmission process in comparison with the unbiased case, and the effect is more pronounced the larger the network. In SF network with large γ values, the effect is less pronounced, however, a small bias still offers a significant improvement in the fraction of particles that successfully arrive on target.

V. CONCLUSIONS

We propose a model to study the efficiency of biased random walks in ER and SF networks to reach their targets in the presence of traps. We find that in the presence of a concentration c of randomly distributed traps, for the unbiased random walk, the dependence of the fraction of particles that arrive on target f_g on c is $f_g \sim c^{-1}$ in both ER and SF networks. For biased walks, there exists a threshold value of the concentration c_{th} which depends on the bias p. For $c < c_{th}$ almost all the particles arrive on target without being trapped i.e $f_g \approx 1$. For $c > c_{th}$, f_g decreases significantly approximately as $1/c$. This threshold value, c_{th}, corresponds to the inverse of the MFPT of the biased diffusion process without traps, and thus it is possible for any concentration of traps to find the needed minimum bias parameter p in order to have unaffected transmission. Also, by a simple approximation of the mean numbers of distinct nodes visited, we obtain an analytic expression that adequately describes the function f_g for a broad range of values of p. We have also investigated the efficiency of the process in SF networks after failure of the most connected node which behave as a trap. In the case of the unbiased random walk, we find that $f_g \sim 1/k_{max}$ and thus $f_g \sim N^{-1/(\gamma-1)}$. In the case of biased walks, even a small bias can vastly improve the efficiency of the transmission process in comparison with the unbiased case. The improvement is more pronounced the larger is the size of the network, since the effective concentration of traps, k_{max}/N, decreases with N.

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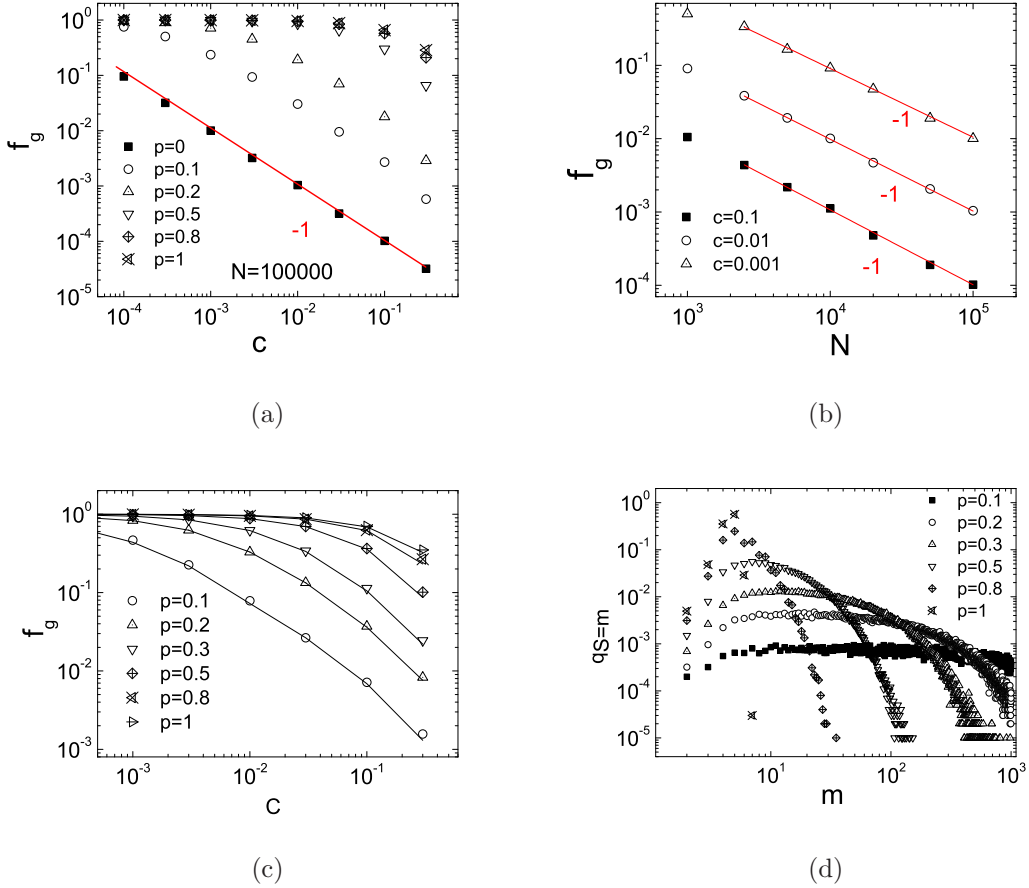[19] R. Cohen, K. Erez, D. ben Avraham, and S. Havlin, Phys. Rev. Lett. **85**, 4626 (2000).

FIG. 1: (Color online) (a) Log-log plot of f_g vs c for various values of p in ER networks with $\langle k \rangle = 10$, $N = 100000$. (b) For $p = 0$, f_g scales as $1/N$. (c) Comparison of results for $N = 20000$ (full symbols) with results from Eq. (1) (continuous lines) where (d) the probability $q_{S=m}$ for having m distinct nodes visited for different p values is obtained from simulations without traps on similar networks.
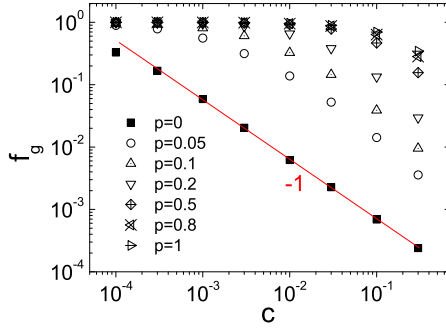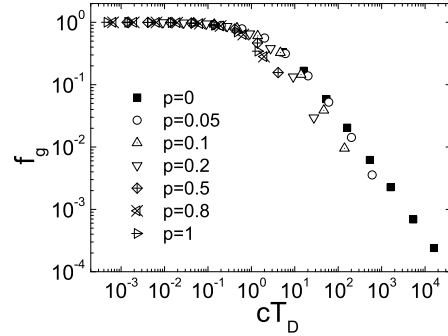
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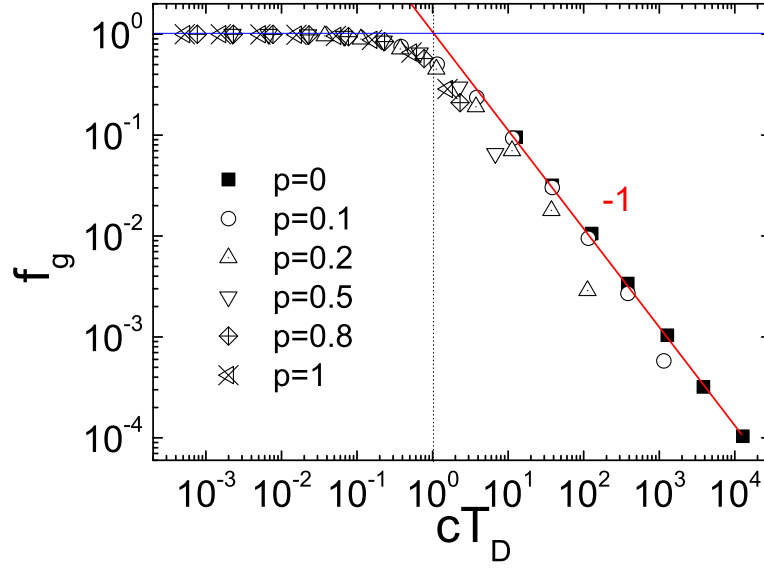
FIG. 2: (Color online) Log-log plot of f_g vs cT_D for ER networks with $\langle k \rangle = 10$ where T_D is the MFPT in the case with no traps calculated from Eqs. (3) and (4). Here, we vary the trap concentration c and $N = 100000$, for various values of p.

(a)   (b)

FIG. 3: (Color online) (a) Log-log plot of f_g vs c for various values of p for SF networks with $\gamma = 2.5$ and $N = 20000$. (b) Log-log plot of f_g vs cT_D for the same SF networks where T_D is the MFPT for the case of no traps. Results are for different trap concentration c, $N = 20000$ and for various values of p.

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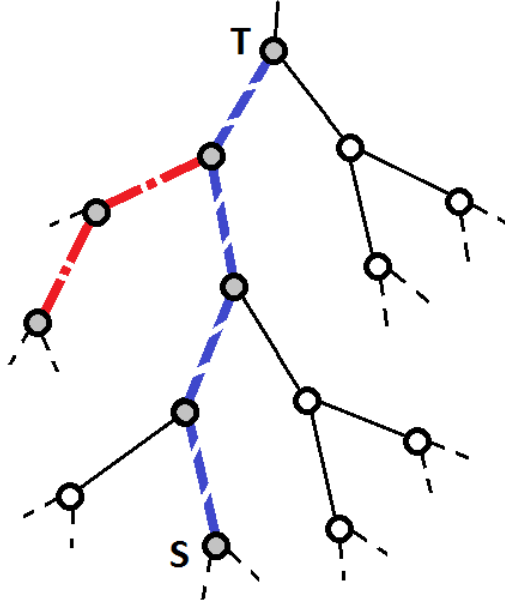
FIG. 4: (Color online) For a sufficiently large value of p, we assume that the mean number of distinct nodes S can be approximated by D(dashed blue)$+\frac{1}{2}(T_D - D)$(dash dot red)$= \frac{1}{2}(T_D + D)$.
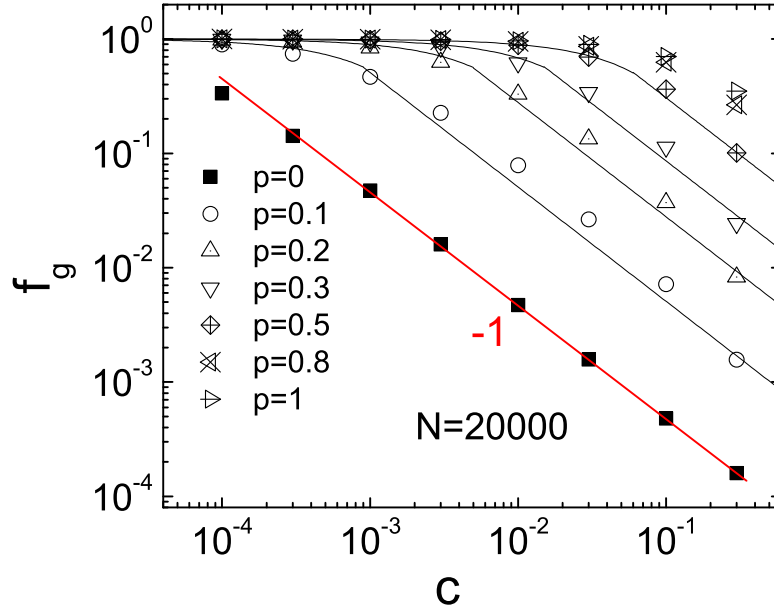
FIG. 5: (Color online) Log-log plot of f_g vs c in ER networks with $\langle k \rangle = 10$ and $N = 20000$. The symbols represent simulation results while the lines correspond to the approximated analytic expressions Eqs. (7) and (8). Note that we assume that Eq. (3) can be approximated by $c_{th} = 1.1/T_D$.
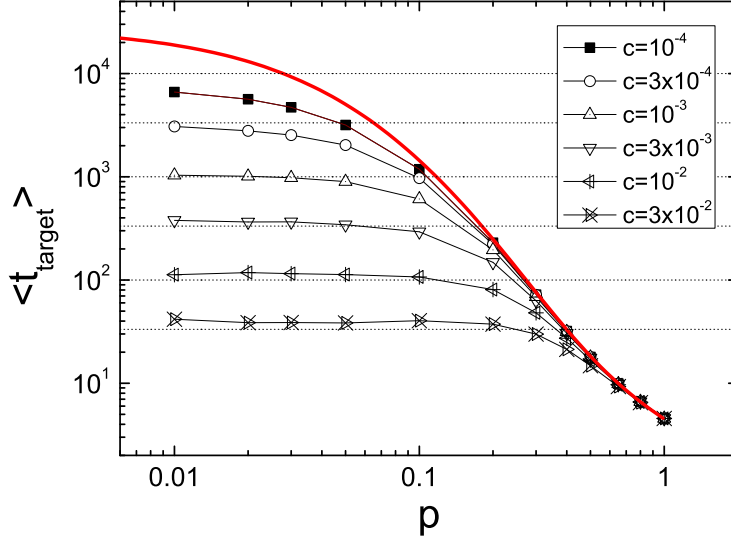
FIG. 6: (Color online) $\langle t_{target} \rangle$ vs p for ER networks with $\langle k \rangle = 10$, $N = 20000$, for various values of c. The dotted lines correspond to the $1/c$ values and the red bold curve to the p dependence of the MFPT without traps according to Eq. (4).
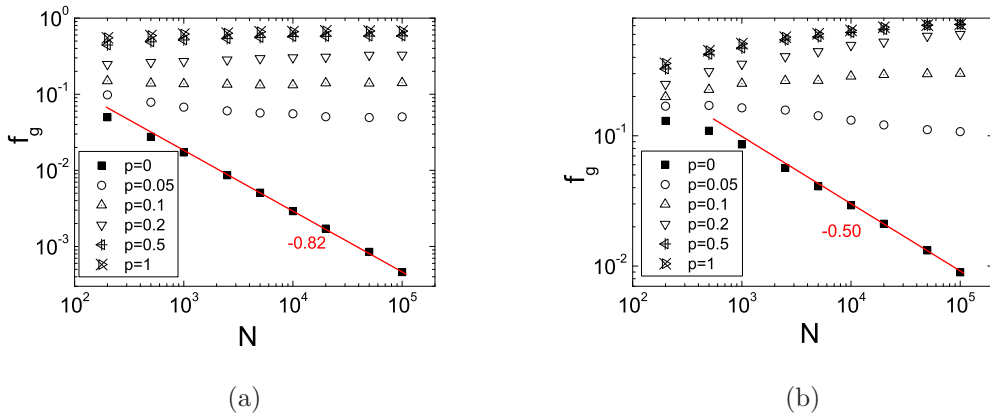

FIG. 7: (Color online) Log-log plot of f_g vs N when the largest hub is a trap for SF networks with a) $\gamma = 2.2$ and b) $\gamma = 3$. Note that the slopes for the unbiased case agree well with Eq. (11).
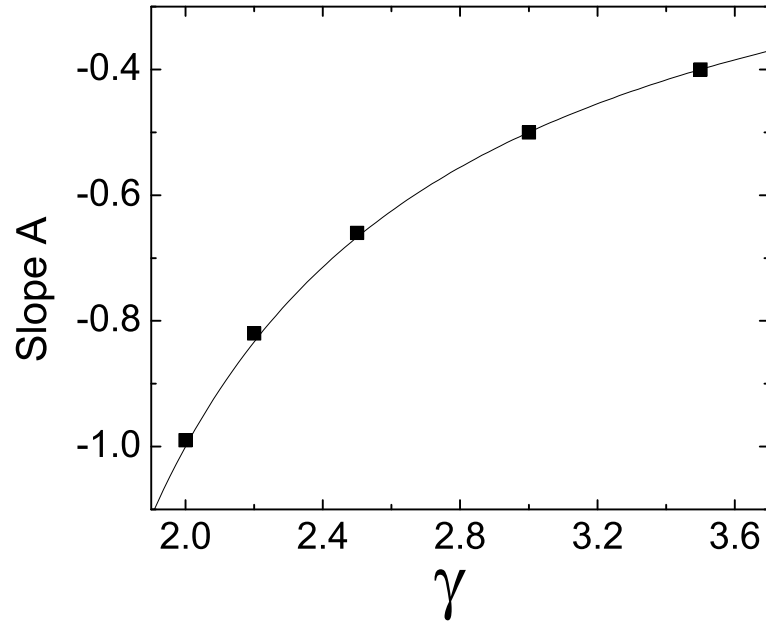
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FIG. 8: Eq. (11) suggests that $\log f_g \sim A \log N$ where $A = -1/(\gamma - 1)$. The line represents the theoretical $A = -1/(\gamma - 1)$. The symbols are slopes from simulations of unbiased case $(p = 0)$ obtained from figures like 7(a) and 7(b).