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Correlations between the dynamics of parallel tempering and the free-energy landscape in spin glasses

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istence of a first-order transition leads to much longer equilibration times. These results in simple model landscapes prompted us to look for similar phenomena in the Edwards-Anderson model where different disorder realizations may have quite different free-energy landscapes. In this study, rather than measuring the free-energy landscape directly, we used the spin overlap (order parameter) distribution as a proxy. The overlap distribution is closely related to the free-energy landscape but is substantially easier to measure in simulations. Based on the results from simple model free-energy landscapes, we hypothesize that when the overlap distribution has a complex structure implying many free-energy minima the time scale for parallel tempering will tend to be longer than when the overlap distribution is simple. Our results confirm this hypothesis.

This study is part of a larger project whose goal is to understand the nature of the low-temperature phase of finite-dimensional spin glasses. The low-temperature phase of the Edwards-Anderson model is poorly understood and hotly debated. There are several competing theories for the low-temperature behavior of the model [14–23] and even though many large-scale investigations have been conducted [22–26], a conclusive theory correctly explaining all phenomena has not been agreed upon. Our recent simulations [27] point toward a two-pure-state picture such as the droplet picture [14, 15, 28–30] or the chaotic pairs picture [19, 20, 31]. One motivation for this work was to verify that the ensemble of disorder realizations used in Ref. [27] was indeed equilibrated. Therefore, we have measured both equilibration times and overlap distributions for all disorder realizations and correlated these quantities. We also demonstrate that the conservative use of the equilibration criterion introduced in Ref. [23] is sufficient to ensure that nearly all disorder samples are equilibrated.

Our results suggest both a method for improving parallel tempering and a warning when using it in spin-glass simulations. On the one hand, we find that many disorder realizations have quite short equilibration times. Thus it might be useful to implement an adaptive scheme where some disorder realization are simulated for shorter times than other realizations. State-of-the-art parallel tempering simulations of equilibrium spin glasses require huge amounts of CPU time because of the difficulty of reaching equilibrium and the need for a large ensemble of disorder realizations. Thus, such an adaptive scheme has the potential for large savings in CPU time. On the other hand, the fact that the overlap distribution (a quantity directly related to the controversy surrounding the low-temperature phase of spin glasses) is significantly correlated with the dynamics of the algorithm serves as a warning that one must be extremely careful to ensure that essentially all samples are well equilibrated in order to avoid systematic errors in measuring disordered-averaged equilibrium properties.

The paper is organized as follows: In Sec. II we introduce the model, the parallel tempering algorithm, as

well as the measured observables. In Sec. III we show our results, followed by conclusions.

II. MODEL AND METHODS

A. The Edwards-Anderson Ising spin glass

We study the three-dimensional Edwards-Anderson (EA) Ising spin-glass model, defined by the energy function

$$H = - \sum_{\langle i,j \rangle} J_{ij} s_i s_j. \quad (1)$$

The sum is over the nearest neighbors on a simple cubic lattice with periodic boundary conditions and side length L . The Ising spins s_i take values ± 1 and the interactions J_{ij} are quenched random couplings chosen from a Gaussian distribution with zero mean and variance one.

B. Parallel tempering Monte Carlo

Parallel tempering, also known as replica exchange Monte Carlo, is a powerful tool for simulating systems with rough free-energy landscapes [12, 13, 32] with applications across many disciplines. To date, it is the most efficient method for simulating spin glasses and other disordered systems in more than two dimensions at low temperatures where dynamics are slow.

The algorithm works as follows: Several copies (hereafter also referred to as *replicas*) of the system with the same disorder are simulated in parallel. Each replica is simulated at a different temperature using a standard Markov chain Monte Carlo (MCMC) technique such as the Metropolis or heat bath algorithms [11, 33, 34]. In this work we use the heat bath algorithm because of its better performance at low temperature. The set of temperatures is chosen to span both the low temperatures of interest, where equilibration is not feasible using single-temperature MCMC methods, and high temperatures where equilibration is fast. In addition to the MCMC sweeps at each temperature, there are also *replica exchange* moves between replicas. A proposed replica exchange move involves swapping the temperatures of two replicas at neighboring temperatures. A replica exchange move is accepted with probability p , where

$$p = \min[1, e^{(\beta - \beta')(E - E')}] \quad (2)$$

Here $\beta = 1/T$ is the inverse temperature of one replica and β' the inverse temperature of the neighboring replica, and E and E' are the corresponding energies of the two replicas. Equation (2) ensures that the entire Markov chain, including both single-temperature MCMC sweeps and replica exchange moves satisfies detailed balance and converges to equilibrium. Replica exchange allows replicas to diffuse from the lowest temperature to the highest

temperature and back again. These *round trips* enhance mixing and greatly reduce equilibration times for rough energy landscapes.

The parallel tempering algorithm has free parameters that include the set of temperatures and the ratio of single-temperature sweeps to replica-exchange sweeps. Optimizing parallel tempering therefore requires an appropriate choice of these parameters. The choice of the number of replicas N_T and their temperatures involves the following trade-off: If there are many closely-spaced temperatures, the energy distribution between adjacent temperatures overlaps strongly and the probability that a proposed replica exchange is accepted, see Eq. (2), is large. This suggests that the more replicas one uses, the better apart from the extra computational work involved in carrying out single-temperature sweeps of each replica. However, the motion of replicas in temperature space is diffusive such that the time scale for a round-trip scales approximately as the square of the number of temperatures. At least for simple model systems, parallel tempering is optimized if the number of temperatures scales as the square root of the number of spins [13]. The average time to complete one round trip is often used to characterize the performance of parallel tempering. Choosing a set of temperatures that minimizes the round trip time is one of the ways proposed to optimize parallel tempering [12, 35, 36].

C. Simulation parameters

For the parallel tempering algorithm we use $N_T = 16$ temperatures between $T = 0.2$ to 2.0 [37]. This set of temperatures was chosen heuristically in Refs. [23] and [24] to perform well for $L = 6$ and 8 . The corresponding average acceptance fractions for replica exchange moves are plotted in Fig. 1. It is likely that the simulations would be more efficient if more replicas were used near and above the critical region ($T_c \approx 0.96$ [25]) where the acceptance fractions are small. However, we believe that as long as the swapping probability is nonzero, our results will not change qualitatively. A bottleneck merely slows down the diffusion process but does not prevent it. For $L = 10$, the small acceptance fractions suggest that a larger number of temperatures might be more efficient. However, our goal is to understand correlations between static and dynamic quantities in parallel tempering for a given system size and so we have not sought to optimize the algorithm for each system size. We believe that the qualitative results obtained using our parallel tempering parameters would also hold for other reasonable values of the parameters.

By placing the hottest system temperature at $T \approx 2T_c$, we ensure that equilibration happens quickly, and we use one exchange sweep for each heat bath sweep ($N = L^3$ attempted spin updates). To calculate the spin overlap [Eq. (3)] we use two copies of the system at each temperature, therefore for each sample we simulate two sets of

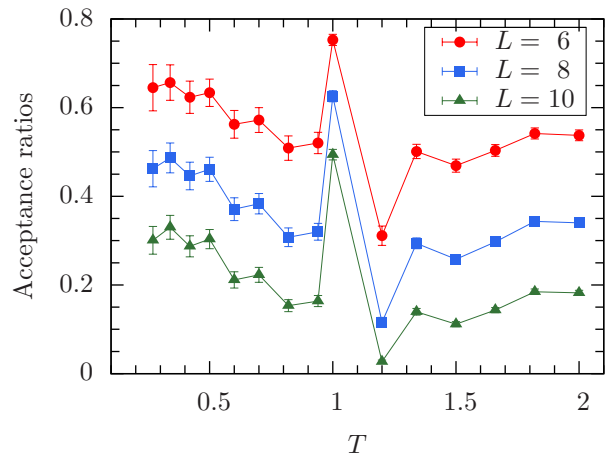


FIG. 1: (Color online) Average acceptance fraction as a function of temperature T for replica exchange moves. Note that $T_c \approx 0.96$.

replicas independently from each other.

As stated before, we employ one replica exchange sweep after one heat bath sweep. A heat bath sweep corresponds to sequentially attempting to update each spin at each replica once using the heat bath algorithm. An exchange sweep corresponds to randomly choosing $N_T - 1$ pairs of adjacent replicas and proposing exchanges for each. Both types of sweeps together make up one parallel tempering sweep. When no confusion arises we will call this unit of time simply a *sweep*.

For each system size we simulate approximately 5000 disorder realizations or *samples*. The simulations are equilibrated for at least 2^{24} sweeps for $L = 6$ and 2^{27} sweeps for $L = 8$ and 10 , then measurements are done for the same number of sweeps, see Table I for details. A fraction of samples required longer runs to meet the equilibration criteria discussed in Sec. IID2. For samples with very short equilibration times we performed runs to obtain fine-grained autocorrelation information, see Sec. IID2. In total, the data collection took approximately 140 CPU years on 12-core AMD Opteron 6174 CPUs.

D. Observables

1. Overlap distributions

The focus of the paper is to relate static equilibrium properties of individual spin-glass samples to the dynamics of the parallel tempering algorithm acting on that sample. The primary quantity that we measure to study both equilibrium properties and the dynamics of parallel tempering is the spin overlap q ,

$$q = \frac{1}{N} \sum_{i=0}^N s_i^{(1)} s_i^{(2)}, \quad (3)$$

TABLE I: For each system size L we equilibrate and then measure for at least 2^b Monte Carlo sweeps. T_{\min} (T_{\max}) is the lowest (highest) temperature used, N_T is the number of temperatures, and N_{sa} is the number of disorder realizations. For some $L = 10$ samples longer runs had to be performed to ensure equilibration.

L	b	T_{\min}	T_{\max}	N_T	N_{sa}
6	24	0.2	2.0	16	4961
8	27	0.2	2.0	16	5126
8	28	0.2	2.0	16	4
10	27	0.2	2.0	16	4360
10	28	0.2	2.0	16	353
10	29	0.2	2.0	16	241
10	30	0.2	2.0	16	73

where $N = L^3$ is the number of spins and the superscripts (1) and (2) indicate two independent copies of the system with the same disorder. The thermal and disorder average of the overlap is an order parameter for the system and the probability distribution of the thermally averaged overlap $P_J(q)$ for a given sample J reveals aspects of the free-energy landscape for that particular sample. The behavior of $P_J(q)$ for large systems and at low temperatures is one of the major open questions in the theory of spin glasses. Overlap distributions vary widely from sample to sample, as can be seen in the three examples shown in Fig. 2. Although there is no direct mapping between the free-energy landscape and $P_J(q)$, it is clear that numerous peaks in $P_J(q)$ imply numerous minima in the free-energy landscape. For example, samples corresponding to Figs. 2(b) and 2(c) have a more complicated free-energy landscapes than Fig. 2(a). Our central hypothesis is that samples with a more complicated free-energy landscape tend to have longer dynamic time scales.

From $P_J(q)$ we define $I_J(q_0)$ for different q_0 ,

$$I_J(q_0) = \int_{-q_0}^{q_0} P_J(q). \quad (4)$$

$I_J(q_0)$ is the weight of $P_J(q)$ in an interval near the origin and it serves as an approximate measure of the complexity of $P_J(q)$. For example, $I_J(0.2) \approx 0$ for the samples shown in Figs. 2(a) and 2(b), while $I_J(0.2)$ is large for the sample shown in Fig. 2(c). We compute $I_J(q_0)$ for eight values of q_0 from $q_0 = 0.2$ to 0.9 . It is worth noting that $I_J(q_0)$ —especially with $q_0 = 0.2$ —has been extensively used in studies of the low-temperature equilibrium properties of the EA model [23, 26].

2. Characteristic time scales

We measure two time scales for parallel tempering from the autocorrelation function of the overlap at the lowest

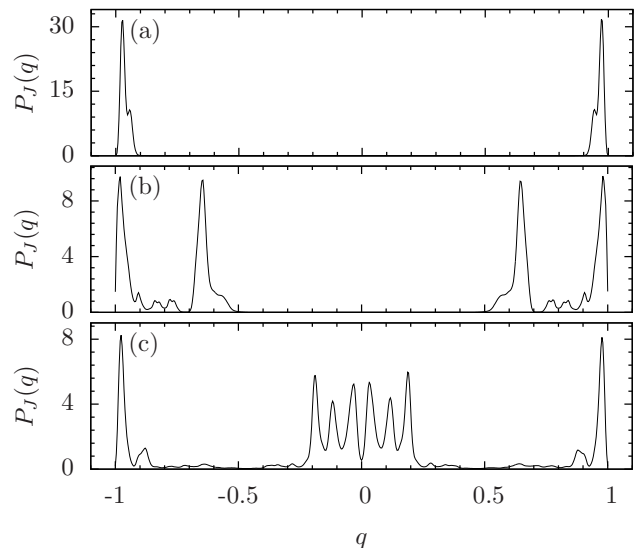


FIG. 2: Examples of overlap distributions $P_J(q)$ for three different disorder realizations J for $L = 8$. While the distribution in panel (a) has only two peaks, the distribution in panel (c) implies a very complex free-energy landscape. All panels have the same horizontal scale.

temperatures. For an arbitrary observable \mathcal{A} , the autocorrelation function $\Gamma_{\mathcal{A}}(t)$ is defined via

$$\Gamma_{\mathcal{A}}(t) = \frac{\langle \mathcal{A}(0)\mathcal{A}(t) \rangle - \langle \mathcal{A} \rangle^2}{\langle \mathcal{A}^2 \rangle - \langle \mathcal{A} \rangle^2}. \quad (5)$$

Here, $\mathcal{A}(t)$ is the observable measured at time t and $\langle \dots \rangle$ represents a thermal average [38]. Integrated and exponential autocorrelation times are computed from the autocorrelation function. The integrated autocorrelation time $\tau_{\text{int}}^{\mathcal{A}}$ is the integral of the autocorrelation function or, for discrete time, the sum of the autocorrelation function,

$$\tau_{\text{int}}^{\mathcal{A}} = \frac{1}{2} + \sum_{t=1}^{\infty} \Gamma_{\mathcal{A}}(t). \quad (6)$$

The integrated autocorrelation time is the time needed for two subsequent measurements of \mathcal{A} to decorrelate. It is a *lower bound* on the time needed to reach equilibrium from an arbitrary initial condition. To calculate $\tau_{\text{int}}^{\mathcal{A}}$ care must be taken when truncating the sum in Eq. (6) to avoid large statistical errors (explained below).

Figure 3 shows two typical examples of the autocorrelation function for the absolute value of the spin overlap $|q|$. For large times, the autocorrelation function is eventually dominated by noise. The noise floor is indicated in Figs. 3 by the horizontal (red) solid line. Because the noise floor is determined primarily by the number of data points used to compute the autocorrelation function, it can be chosen to be the same for all simulations of the same length. Our truncation procedure is to sum the autocorrelation function until it first hits the noise floor.

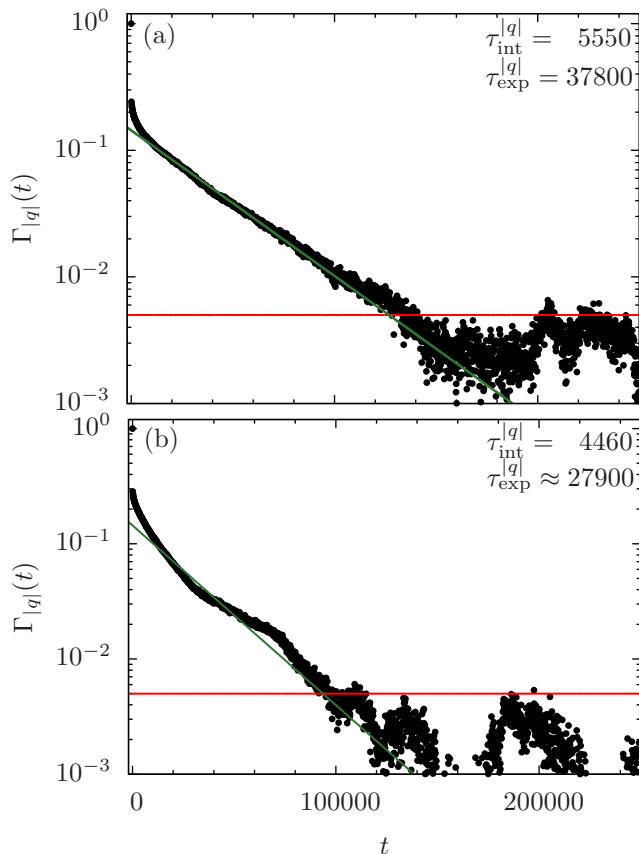


FIG. 3: (Color online) Autocorrelation function for the absolute value of the order parameter $\Gamma_{|q|}(t)$ as a function of simulation time for two different disorder realizations and system size $L = 8$. The horizontal (red) solid line at $\Gamma_{|q|} = 0.005$ represents the noise floor. The diagonal solid (green) lines represent exponential fits to the data. Both panels have the same horizontal scale.

We obtain the noise floor for each run length by visual inspection of $\Gamma_{|q|}(t)$ for many samples. We note that this approach introduces some slight systematic bias in our estimates of the integrated autocorrelation times. However, the main emphasis of this paper is to understand the very large sample-to-sample variations in time scales and, compared to these variations, the errors introduced by our truncation protocol are small.

We have computed autocorrelation functions for both $|q|$ and q and from these we have obtained $\tau_{\text{int}}^{|q|}$ and τ_{int}^q , respectively. To do this, we first compute a Fourier transform of the data and then invert the function to obtain the autocorrelation function. This method is considerably faster than a direct calculation. For $L = 6$, the simulations are run for 2^{24} sweeps, recording data for the computation of the autocorrelation functions every 10 sweeps. The noise floor for these runs is set to $\Gamma = 0.005$. Some samples have $\tau_{\text{int}}^{|q|}$ values of order 10 or less. For these, shorter data collection runs of 2^{18} sweeps have been done starting from an equilibrated spin con-

figuration stored at the end of the longer run. For these short runs data are collected every sweep to accurately measure the autocorrelation function up to time 10 and the full autocorrelation function is patched together from the short and long runs. The noise floor for these shorter runs is set to $\Gamma = 0.01$. If the noise floor is reached before $t = 10$, only the autocorrelation function generated by the short run is used. For both $L = 8$ and $L = 10$ the simulations are run for at least 2^{27} sweeps, recording data every 100 sweeps with shorter runs also needed for samples with small $\tau_{\text{int}}^{|q|}$ values. The noise floor used is the same as for $L = 6$.

The autocorrelation function is always calculated up to a maximum time lag of 1% of the total run length. Therefore, for some samples and, in particular for $L = 10$, the noise floor was not reached by this time and longer runs were necessary to obtain good statistics. For these $L = 10$ samples we simulate up to 2^{30} sweeps. 32 samples (approximately 0.6%) stayed above the noise floor even for the longest runs. To prevent a biasing of the results, these were not included in the analysis. However, it would be interesting to study these samples in detail in the future.

There is another method for truncating the sum in Eq. (6) introduced by Madras and Sokal [39] where the upper limit of the sum is determined recursively. An initial upper limit is chosen and τ_{int}^A is computed for that value, the new upper limit is determined as some factor (6 is suggested in Ref. [39]) times the current τ_{int}^A . The estimated value of τ_{int}^A is obtained when this process has converged. We experimented with this approach but did not find that it converged in a consistent way across all samples with very different autocorrelation functions. However, we note that our approach should have systematic errors no larger than those resulting from the method of Madras and Sokal with the upper limit set to $6\tau_{\text{int}}^{|q|}$ because the noise floor is not reached until at least $10\tau_{\text{int}}^{|q|}$ except for the very few samples with extremely small $\tau_{\text{int}}^{|q|}$ values.

The second time scale that we consider is the exponential autocorrelation time τ_{exp}^A , defined by the asymptotic exponential decay of the autocorrelation function,

$$\Gamma_A(t) \sim Ae^{-t/\tau_{\text{exp}}^A}. \quad (7)$$

Except for observables orthogonal to the slowest mode of the Markov chain, τ_{exp}^A is the characteristic time of the slowest mode and is thus the exponential time scale to reach equilibrium from an arbitrary initial state [40].

In principle, τ_{exp}^A is the most important time scale for studying disordered systems because the main difficulty is reaching thermal equilibrium (controlled by τ_{exp}^A) rather than collecting enough uncorrelated data at equilibrium (controlled by τ_{int}^A). Unfortunately, calculating τ_{exp}^A for a large number of samples is difficult because it requires an automatized fitting process. For some samples, such as the one shown in Fig. 3(a), the autocorrelation function decays nearly exponentially over most of

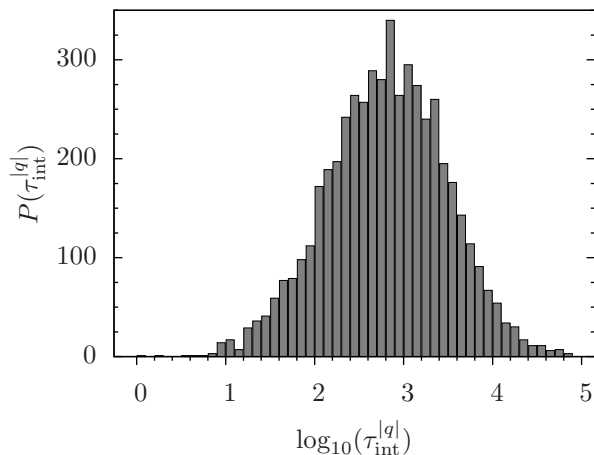


FIG. 4: Logarithmic histogram of the integrated autocorrelation times $\tau_{\text{int}}^{|q|}$ for $L = 8$. The data are normally distributed and show that a small fraction of samples is extremely difficult to equilibrate.

the observable time range, allowing for a precise fitting and extraction of $\tau_{\text{int}}^{|q|}$. However, for many samples the autocorrelation function is *not* exponential for the measured times, as can be seen in Fig. 3(b) and, for these samples, an automatic fitting procedure would not be reliable. For that reason, the time scale that we correlate with the static properties of the EA spin glass is the integrated autocorrelation time. We have studied $\tau_{\text{exp}}^{|q|}$ by hand for a small subset of the data set and find that for those samples where a reasonable fit is possible, $\tau_{\text{exp}}^{|q|}$ is in the range of 1 to 15 times $\tau_{\text{int}}^{|q|}$. Most, but not all, samples share the behavior seen in the examples in Figs. 3 that there is an initial sharp decline before the (approximately) exponential decay sets in. This sharp decline explains why $\tau_{\text{exp}}^{|q|}$ is typically larger than $\tau_{\text{int}}^{|q|}$.

Finally, we also measured the round-trip time τ_{RT} for each sample, defined as the average time after equilibration is achieved, for a replica to diffuse from the lowest to the highest temperature and then back to the lowest temperature again [12].

III. RESULTS

Figure 4 shows the probability distribution for $\tau_{\text{int}}^{|q|}$ for $L = 8$. In agreement with previous studies [8, 9, 25], the figure reveals that the equilibration times for spin glasses are very broadly distributed. The distributions for $L = 6$ and 10 are similar although with different means and standard deviations, as shown in Tables II and III, respectively. Tables II and III also show the mean and standard deviation of τ_{int}^q . The values for τ_{int}^q are similar to those for $\tau_{\text{int}}^{|q|}$, however the standard deviations are somewhat smaller. Figure 5 shows a scatter plot with each point representing one sample for $L = 8$.

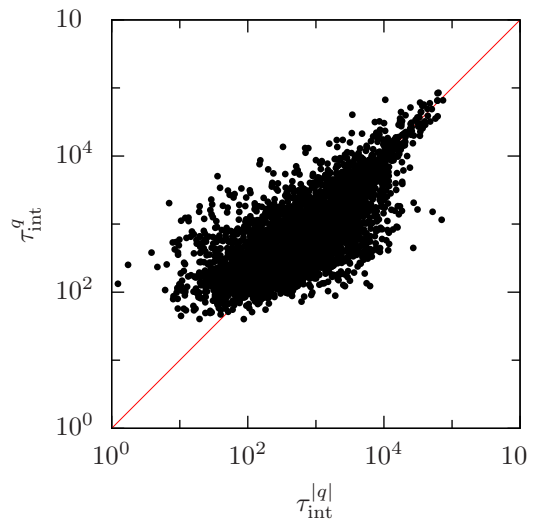


FIG. 5: (color online) Scatter plot of τ_{int}^q vs. $\tau_{\text{int}}^{|q|}$ for $L = 8$. The diagonal (red) solid line corresponds to $\tau_{\text{int}}^q = \tau_{\text{int}}^{|q|}$. Note that $\tau_{\text{int}}^{|q|}$ is often smaller than τ_{int}^q because the decorrelation of q requires global spin flips while the decorrelation of $|q|$ does not.

TABLE II: Mean values of the logarithms of τ_{int}^q , $\tau_{\text{int}}^{|q|}$ and τ_{RT} for system sizes $L = 6 - 10$.

L	6	8	10
$\log_{10}(\tau_{\text{int}}^q)$	1.7164(58)	2.8366(75)	3.8711(84)
$\log_{10}(\tau_{\text{int}}^{ q })$	1.6035(90)	2.8065(94)	3.8881(97)
$\log_{10}(\tau_{\text{RT}})$	3.6217(28)	4.4571(34)	5.2421(42)

TABLE III: Standard deviations of the logarithms of τ_{int}^q , $\tau_{\text{int}}^{|q|}$ and τ_{RT} for system sizes $L = 6 - 10$.

L	6	8	10
$\log_{10}(\tau_{\text{int}}^q)$	0.408	0.534	0.592
$\log_{10}(\tau_{\text{int}}^{ q })$	0.631	0.672	0.685
$\log_{10}(\tau_{\text{RT}})$	0.194	0.242	0.293

The x and y coordinates are determined by τ_{int}^q and $\tau_{\text{int}}^{|q|}$, respectively. The data illustrate that τ_{int}^q and $\tau_{\text{int}}^{|q|}$ are strongly correlated, especially for those samples with the longest integrated autocorrelation times. The observation that $\tau_{\text{int}}^{|q|}$ can take smaller values than τ_{int}^q is presumably a consequence of the fact that the decorrelation of q requires global spin flips while the decorrelation of $|q|$ does not.

Figures 6(a) and 6(b) show scatter plots of $\tau_{\text{int}}^{|q|}$ vs $I_J(q_0)$ for $L = 8$ and $q_0 = 0.2$ and $q_0 = 0.8$, respectively. Each point represents one sample. These figures show that $\tau_{\text{int}}^{|q|}$ is correlated with $I_J(q_0)$ and the correlation is stronger for larger values of q_0 . It is also striking that large values of $I_J(q_0)$ are never associated with very small

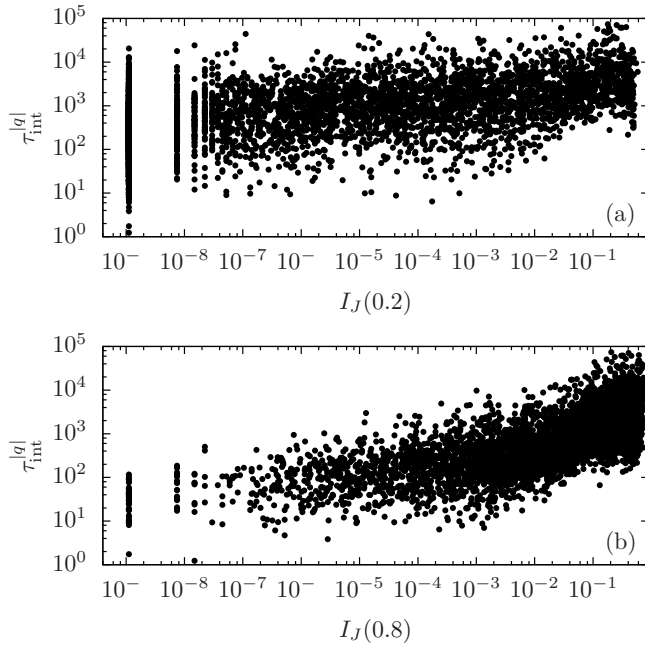


FIG. 6: Scatter plot for all $L = 8$ samples of $\tau_{\text{int}}^{|q|}$ vs $I_J(q_0)$ for (a) $q_0 = 0.2$ and (b) $q_0 = 0.8$. The empty area underneath the scatter for large $I_J(q_0)$ clearly shows that realizations with large values of $I_J(q_0)$ can never have small values of $\tau_{\text{int}}^{|q|}$.

integrated autocorrelation times (similar results are obtained for the other system sizes studied). This suggests that when the free-energy landscape is complex, time-scales are large, as one would naively expect.

To quantify the correlations between $\tau_{\text{int}}^{|q|}$ and $I_J(q_0)$, we use the Pearson correlation coefficient r [41], whose estimator for a finite data set $\{(x_i, y_i)\}$ is

$$r = \frac{\sum_{i=0}^M (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_{i=0}^M (x_i - \bar{x})^2 \sum_{i=0}^M (y_i - \bar{y})^2}}, \quad (8)$$

where M is the size of the data set and the overbar indicates the average over the data set. If $r = 1$ there is an exact linear relationship between x and y while a small value of r indicates the absence of any linear dependence. Pearson r values for $\log_{10}(\tau_{\text{int}}^{|q|})$ vs $\log_{10}[I_J(q_0)]$ for our data are shown in Table IV and Fig. 7 for the system sizes studied and different values of q_0 . These results clearly demonstrate that longer parallel tempering time scales are correlated with more complicated overlap distributions. The strength of the correlation is slightly weaker for larger systems. The fact that r increases with q_0 suggests that the presence of additional peaks in $P_J(q)$ increases $\tau_{\text{int}}^{|q|}$ independent of whether those peaks are near the origin or not.

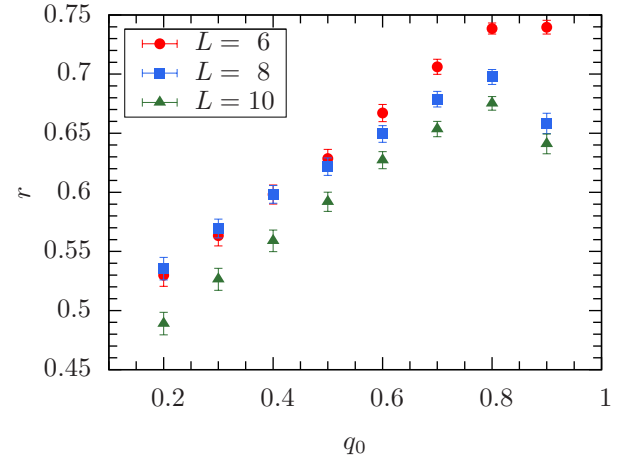


FIG. 7: (Color online) Pearson correlation r between $\log_{10}[I_J(q_0)]$ and $\log_{10}(\tau_{\text{int}}^{|q|})$ vs q_0 . The data suggest that longer parallel tempering time scales are correlated with more complicated overlap distributions.

TABLE IV: Pearson correlation r between the overlap weight $\log_{10}[I_J(q_0)]$ for various q_0 and the logarithm of the integrated autocorrelation time for the overlap $\log_{10}(\tau_{\text{int}}^{|q|})$ for the three system sizes, L . The bottom row shows the correlation coefficient between the logarithm of the round trip time $\log_{10}(\tau_{\text{RT}})$ and $\log_{10}(\tau_{\text{int}}^{|q|})$.

q_0	$L = 6$	$L = 8$	$L = 10$
0.2	0.5299(94)	0.5355(95)	0.4889(95)
0.3	0.5634(86)	0.5693(79)	0.5264(93)
0.4	0.5982(80)	0.5983(75)	0.5590(91)
0.5	0.6286(77)	0.6217(73)	0.5920(80)
0.6	0.6671(72)	0.6494(70)	0.6272(72)
0.7	0.7062(63)	0.6788(66)	0.6535(65)
0.8	0.7385(46)	0.6975(63)	0.6752(57)
0.9	0.7397(58)	0.6583(85)	0.6410(83)
$\log_{10}(\tau_{\text{RT}})$	0.014(19)	0.114(17)	0.126(20)

On the other hand, we find that the round trip time is not correlated with $\tau_{\text{int}}^{|q|}$ or, by extension, $I_J(q_0)$. Figure 8 is a scatter plot of τ_{RT} vs $\tau_{\text{int}}^{|q|}$ for $L = 8$ (compare with Fig. 5). Each point represents one sample and the diagonal line is $\tau_{\text{RT}} = \tau_{\text{int}}^{|q|}$. It is clear from this figure that τ_{RT} has a much smaller variance than $\tau_{\text{int}}^{|q|}$ and that the correlation between the two is minimal. The last row of Table IV shows the Pearson r value between $\log_{10}(\tau_{\text{RT}})$ and $\log_{10}(\tau_{\text{int}}^{|q|})$ and quantifies the lack of correlation between τ_{RT} and $\tau_{\text{int}}^{|q|}$. Note that the authors of Ref. [26] consider a time scale related to the motion of replicas in parallel tempering and also find no correlation with $I_J(q_0)$.

If the highest temperature is chosen such that its mixing time is one heat bath sweep, then $\tau_{\text{RT}} \geq \tau_{\text{int}}^{|q|}$ because there will be no memory of the spin state of the replica between successive visits to the lowest temperature, as

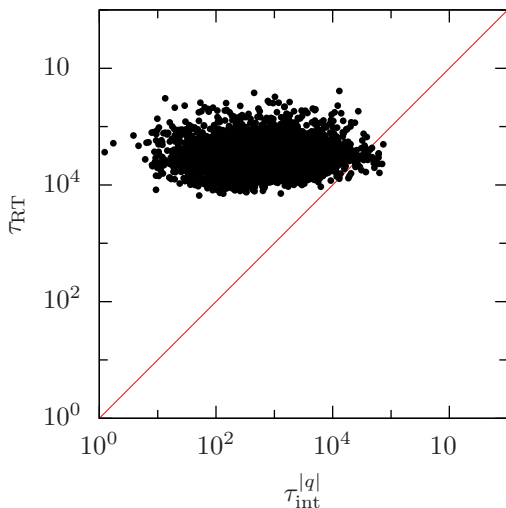


FIG. 8: (Color online) Scatter plot of the average round trip time τ_{RT} vs $\tau_{int}^{[q]}$ for $L = 8$. The diagonal (red) line is $\tau_{RT} = \tau_{int}^{[q]}$. The data show almost no correlation between these quantities.

can be seen in Tables II and III, as well as Fig. 8. Figure 8 shows that τ_{RT} is much larger than $\tau_{int}^{[q]}$ for most samples. One explanation for this is that (for most samples) the spin state of the coldest replica can be decorrelated by diffusion from the lowest temperature to an intermediate temperature and back; full round trips are not needed for decorrelation.

Note that if we repeat the study for τ_{int}^q instead of $\tau_{int}^{[q]}$, the correlation values would show the same qualitative trend as for $\tau_{int}^{[q]}$, but they would on average be slightly smaller.

Finally, we also test equilibration with the method introduced by Katzgraber *et al.* in Ref. [23] for short-range spin glasses with Gaussian disorder between the spins. In this method, the average energy per spin

$$u = -\frac{1}{N} \sum_{\langle i,j \rangle} [J_{ij} \langle s_i s_j \rangle]_{av}, \quad (9)$$

where $[\dots]_{av}$ represents a disorder average and, as before, $\langle \dots \rangle$ denotes the Monte Carlo average for a given set of bonds, can be related to the link overlap

$$q_l = \frac{1}{N_b} \sum_{\langle i,j \rangle} s_i^{(1)} s_j^{(1)} s_i^{(2)} s_j^{(2)} \quad (10)$$

via an integration by parts over the interactions J_{ij} between the spins. In Eq. (10) $N_b = dN$ with $d = 3$ the space dimension represents the number of bonds in the system. One obtains:

$$[\langle q_l \rangle]_{av} = 1 - \frac{T|u|}{d}, \quad (11)$$

where T is the temperature.

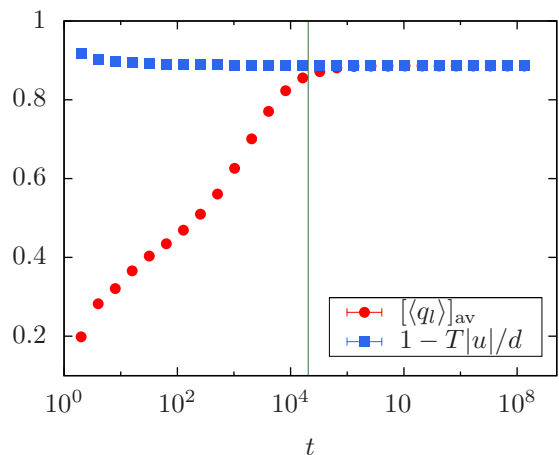


FIG. 9: (color online) Average link overlap $[\langle q_l \rangle]_{av}$ (red circles) and $1 - T|u|/d$ (see Eq. (11), blue squares) as a function of time t for $L = 8$ and $T = 0.20$. For $t \gtrsim 10^5$ sweeps both data sets agree suggesting that the system is in thermal equilibrium. The vertical (green) line in the figure represents the time for which 99% of the samples have values of $\tau_{int}^{[q]}$ less than this time. Error bars are smaller than the symbols.

Figure 9 shows representative results for $L = 8$ and $T = 0.2$, the lowest temperature simulated. At approximately 10^5 Monte Carlo sweeps both data computed directly from the energy per spin (blue squares) and data computed from the link overlap (red circles) agree within error bars. Note that 99% of the $\tau_{int}^{[q]}$ values for this system size are smaller than the point marked with the solid vertical green line. Thus, for the simulated time of over 10^8 Monte Carlos sweeps, the data are well equilibrated. This suggests that a conservative use of the equilibration criterion developed in Ref. [23] will guarantee that almost all of the samples are equilibrated.

IV. CONCLUSIONS

We have found one factor that explains the broad distribution of time scales in parallel tempering for spin glasses: The roughness of the free-energy landscape of each individual sample directly affects its equilibration time scales. In accordance with previous observations on the parallel tempering method [13], if there are many minima in the free-energy landscape, a sample requires more time to equilibrate. The equilibrium distribution of the spin overlap serves as proxy for the complexity of the free-energy landscape. Our results show that individual samples need to be tested individually to ensure proper equilibration, as previously suggested in Ref. [9]. However, we show that the equilibration test developed in Ref. [23] is a viable alternative for system sizes currently accessible in simulations if applied conservatively. Furthermore, the parallel tempering round-trip times seem to be unaffected by the complexity of the free-energy landscape and should therefore not be used as a mea-

sure of how well a system is equilibrated.

The clear correlations between algorithmic (nonequilibrium) time scales and the equilibrium complexity of the free-energy landscape opens the door for alternate studies of the nature of the spin-glass state, a problem that remains controversial.

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