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Boundary dual of bulk local operators Fabio Sanches and Sean J. Weinberg

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The Boundary Dual of Bulk Local Operators

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We provide a procedure to determine if a given nonlocal operator in a large N holographic CFT is dual to a local bulk operator on the geometry associated with a particular code subspace of the CFT. This procedure does not presuppose knowledge of the bulk geometry. We are able to pick out local operators in a large region of the bulk, called the "localizable region," that can extend beyond event horizons in certain cases. The method relies heavily on the quantum-error correcting structure of AdS/CFT and, in particular, on entanglement wedge reconstruction. As a byproduct of this machinery, we are able to reconstruct the metric in the localizable region up to a conformal factor. This suggests a connection between our program and the recent light-cone cut approach to bulk reconstruction.

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I. INTRODUCTION

The emergence of bulk locality in the AdS/CFT correspondence [1, 2] has yet to receive a satisfactory explanation in terms of the behavior of holographic CFTs. While gravity prohibits exact locality in a quantum theory, when the gravitational coupling is sufficiently small, local physics must be a good approximation in the bulk.

There should be a manifestation of this "emergence of locality" in the boundary theory.

One way to tackle this issue is by studying the ways in which bulk degrees of freedom are encoded in the CFT. It is thus natural to ask if there is a boundary dual of local bulk fields in the regime where semiclassical field theory holds. While the extrapolate dictionary [3] states that bulk fields at spacelike infinity are dual to local operators on the boundary, points deep in the bulk require a nonlocal holographic description. There are many wellknown ways to reconstruct bulk fields in terms of nonlocal boundary operators [3–6] with support in a variety of boundary regions. All of these procedures, however, require solving bulk equations of motion which presupposes knowledge of the bulk spacetime. If one were not explicitly told the metric in the bulk, is there any way to determine whether or not a given operator is bulk local? To put this question differently, is the concept of a local bulk operator in any way distinguished in the boundary theory?

The primary goal of this work is to address this question. We will find that a powerful tool to this end is the concept of subregion duality. The notion that a boundary domain of dependence should be thought of as being dual to some region of the bulk, which originally arose from considerations of causal wedge reconstruction, was made precise recently by [7–9] where it was concluded that a bulk operator can be reconstructed in a subregion of the CFT if and only if its support is contained in the entanglement wedge of that CFT region [9]. This conclusion was made in the context of a new development in AdS/CFT: the role of quantum error correction. It is now understood that a semiclassical bulk spacetime description is associated with a code subspace of the boundary Hilbert space, and that various inequivalent boundary reconstructions of bulk operators become equivalent when restricted to the code subspace.

This modern form of subregion duality will reveal a novel characterization of locality in the bulk. Given a holographic CFT and a code subspace dual to some un-

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known geometry, we will provide a procedure that can identify, up to certain caveats, whether or not an operator is dual to a bulk local operator. As a byproduct of our method, we are also able to reconstruct the causal structure (equivalently, the metric up to a conformal factor) of a large region in the bulk. In some examples, this region can penetrate event horizons.

Outline. We start, in section II, by reviewing the arguments and motivation for the quantum error correcting view in holography. In particular, we sketch the proof of [9] that a bulk operator is reconstructable in a boundary region if and only if its support is contained entirely in the entanglement wedge of that boundary region.

Section III contains the major constructions of this work. We define the notion of a superficially local operator without making direct reference to the bulk. These are bulk operators that are "as local as the boundary can directly tell." Their defining characteristic is the great variety of boundary regions in which they can be reconstructed. In a certain region of the bulk called the localizable region, operators are local if and only if they are superficially local. However, there are situations in which superficially local operators correspond to nonlocal bulk operators that are supported outside of the localizable region. The bulk regions in which these problematic operators lie will be referred to as *clumps*. Fortunately, clumps appear to always be identifiable from the boundary theory because they are associated with phase transitions. Thus, they can be identified and thrown away, leaving only the superficially local operators that are authentically dual to bulk local operators.

The set of superficially local operators can be given an equivalence relation by identifying two operators when they can be reconstructed in exactly the same boundary regions. After removing clumps, the set of equivalence classes of superficially local operators is naturally identified with the bulk localizable region.

In IV, we note that the commutation relations amongst these operators reveals the causal structure in the localizable region. Thus, we are able to reconstruct the metric in this portion of the bulk up to a conformal rescaling. This approach is similar at heart to that of [10] where a bulk reconstruction is accomplished by means of lightcone cuts. We argue, in fact, that there are numerous interesting connections between our approach and that involving cut singularities.

II. PRINCIPLES OF SUBREGION DUALITY

This section provides a brief review of the quantum error correcting view of AdS/CFT. Readers already familiar with the conclusions of [7, 9] may wish to proceed to section III

There is a zoo of different methods for expressing bulk fields in terms of CFT operators. The extrapolate dictionary [3] gives a precise relationship between limiting val $\mathbf{2}$

ues of bulk fields and CFT operators with corresponding scaling dimensions. It is also possible to express operators lying deeper in the bulk in therms of CFT quantities by solving equations of motion in the bulk [3–6, 11]. Of these approaches, one of relevance for our considerations is the causal wedge reconstruction, which generalizes the Rindler reconstruction of [4]. This prescription expresses local bulk fields in terms of CFT operators localized to a special boundary subregion. Specifically, if R is region in the boundary with domain of dependence $D^{\partial}(R)$, and if $CW(R) = J^+[D^{\partial}(R)] \cap J^-[D^{\partial}(R)]$ is the causal wedge [12] of R, then causal wedge reconstruction allows a bulk field in CW(R) to be expressed as a smeared operator in $D^{\partial}(R)$.¹

Causal wedge reconstruction suggests the possibility that subregions in the boundary are enough to understand the physics of associated bulk subregions. However, despite what is suggested from the analysis of [4], the causal wedge is, in general, not the largest possible region that a boundary subregion holographically describes in the semiclassical limit. Instead, the bulk region dual to a CFT region R is the entanglement wedge of R, denoted by EW(R) [13–15]. EW(R) can be defined as follows. Let Σ be a spacelike bulk surface that, after conformal compactification of M, is a Cauchy slice for the unphysical bulk spacetime. Require that Σ contains R and its HRT surface ext R. Let S denote the part of Σ between R and ext R. The domain of dependence of S (computed in the unphysical spacetime) is the entanglement wedge of R. It is known that $EW(R) \supseteq CW(R)$ [13]. As we review below, [9] gave a precise sense in which a boundary region R should really be thought of as being dual to its entanglement wedge. This is the most refined and powerful known form of "subregion duality" [16] in AdS/CFT.

Before discussing entanglement wedge reconstruction, we note that subregion duality, even in the form of [4], raises major puzzles [7]. For example, an operator $\phi(p)$ deep within the bulk can be taken to lie in many different causal wedges. Thus, a causal wedge reconstruction of the form

$$\phi(p) = \int_{D^{\partial}(R)} K(p, x) O(x) dx \qquad (\text{II.1})$$

manifestly commutes with all operators in the complement region \overline{R} . This argument can be repeated for many different boundary regions and used to show that a bulk field $\phi(p)$ near the center of AdS can be written in a way that manifestly commutes with any given operator in the boundary. This directly implies what should have been obvious: that each choice of reconstruction for $\phi(p)$ is a different operator in the CFT. This is not an inconsistency. Various reconstructions of $\phi(p)$ are distinct CFT

¹ The smearing function has to be understood in a distributional sense. For details see [11, 16]. Such subtleties will not be important for what follows.



FIG. 1. The operator depicted in the center of this figure is not in $CW(R_1)$, $CW(R_2)$, or $CW(R_3)$. However, it does lie in the causal wedge of the union of any two regions $CW(R_i \cup R_j)$ and can thus be written in terms of boundary operators in the algebra of the combined regions.

operators, but the CFT Hilbert space is much larger² than the Hilbert space relevant for a bulk operator on a spacetime background. The explanation of the multitude of distinct CFT operators is therefore that there is a special subspace of the Hilbert space, the code subspace, which describes the states that $\phi(p)$ is defined on. The restriction of all reconstructions of $\phi(p)$ to this subspace reproduce $\phi(p)$. This is a quantum-error correcting property of the CFT: the action of different operators defined in different regions is the same when restricting to special subspaces called *code subspaces*.

The necessity for such a redundant descriptions of bulk operators was made particularly obvious with the following argument [7] illustrated in figure 1. Consider a partition the boundary into 3 equal regions R_1, R_2 , and R_3 which only have points on their boundaries in common. Taking the vacuum state for simplicity, their causal wedges will not contain points that are close to the center of the bulk spacetime. Thus, there is no HKLL smearing over any one region that reconstructs a local bulk operator near the center. However, the causal wedge of the union of any two regions $CW(R_i \cup R_j)$ does contain the bulk point of interest and the HKLL procedure can be used. The different choices cannot represent the same

CFT operator, since their support is on causally disconnected regions. 3

Review of the DHW argument

The fact that the entanglement wedge EW(R) is the "largest" bulk region that can be reconstructed from the algebra of R will play a critical role in our work. For this reason, we will briefly review the arguments in [7, 9], focusing especially on the aspects of this literature that will be the most relevant for the framework that we begin to develop in section III.

Suppose that we are given⁴ a particular code subspace $G \subset H$ which is known to be a span of states obtained by acting with a small number of low energy operators on a state where a semiclassical bulk exists; in particular, within G, gravitational backreaction of bulk fields can be treated perturbatively. Dong, Harlow, and Wall (DHW) proved that if the support of an operator ϕ is contained in EW(R), then that operator can be reconstructed in R[9]. This means that there is an element of the algebra of R whose action on states in the code subspace is the same as the action of ϕ .

To understand the proof given in [9], we first refer to a result from quantum information. Refs. [7, 20, 21] show that if we have a code subspace G and some factorization of the full Hilbert space $G \subset H_R \otimes H_{\bar{R}}$, and if ϕ is some operator that acts within G (it's action send states in the code subspace to other states in the code subspace), then the following two statements are equivalent.

1. There exists an operator O_R on H_R such that for any $|\psi\rangle \in G$,

$$\phi|\psi\rangle = O_R|\psi\rangle \qquad \phi^{\dagger}|\psi\rangle = O_R^{\dagger}|\psi\rangle.$$
(II.2)

2. For any operator $X_{\bar{R}}$ on on $H_{\bar{R}}$, we have

$$\left[\phi, X_{\bar{R}}\right]\Big|_G = 0. \tag{II.3}$$

While this theorem follows purely from quantum information, it plays a critical role in the entanglement wedge reconstruction argument. As suggested by the notation, we will associate R with the factorization induced from boundary regions and G will be a code subspace with a semiclassical bulk interpretation. We can now discuss [9], which establishes that bulk semiclassical operators

² The basic concept that semiclassical excitations give rise to exponentially small subspaces of a Hilbert space describing quantum gravitational physics has played a role in many related areas. See, e.g., [17–19]

³ The mutual intersection actually includes points on the boundaries of the R_i . However, repeating the argument with slightly different regions circumvents the possibility that the reconstruction of ϕ is achieved only in the algebra of ∂R_i

⁴ While we take the code subspace as given, it should be possible to identify code subspaces purely from the CFT. For example, a necessary (but not sufficient) condition for a collection of states to lie in the same code subspace is that the collection has the property that subregions have entanglement entropies differing only by sub-leading contributions in N.

satisfy condition II.3, and the reconstructability follows because this is equivalent to II.2.

We know the boundary Hilbert space can be factorized into a region and its complement $H = H_R \otimes H_{\bar{R}}$. For states with a semiclassical bulk interpretation, we can think about the extremal surface anchored to ∂R as inducing its own tensor factorization of the code subspace $G_{EW(R)} \otimes G_{EW(\bar{R})}$.

Consider two states $|\psi_0\rangle, |\psi_1\rangle \in G$ and the reduced density matrices obtained by tracing out the appropriate complement regions in the two factorizations

$$\rho_{\bar{R}}^{0} = \operatorname{Tr}_{R} |\psi_{0}\rangle \langle\psi_{0}|$$

$$\rho_{\mathrm{EW}(\bar{R})}^{0} = \operatorname{Tr}_{\mathrm{EW}(R)} |\psi_{0}\rangle \langle\psi_{0}| \qquad (\mathrm{II.4})$$

Similarly, the density matrices $\rho_{\bar{R}}^1$ and $\rho_{\mathrm{EW}(\bar{R})}^1$ are defined by the state $|\psi_1\rangle$.

The statement of a theorem in [9] is that if the states satisfy:

$$\rho_{\mathrm{EW}(\bar{R})}^{0} = \rho_{\mathrm{EW}(\bar{R})}^{1} \implies \rho_{\bar{R}}^{0} = \rho_{\bar{R}}^{1} \qquad (\mathrm{II.5})$$

then, an operator of the form $\phi = \mathbb{1} \otimes \phi_{\mathrm{EW}(R)}$ acting only within the entanglement wedge of R will satisfy the two equivalent properties of II.2 and II.3.

To understand this, we note that the result in [8] established a precise relationship between the bulk and boundary modular hamiltonian. This provides the connection between the first equality and second equality in II.5. Now, the operator ϕ supported in the entanglement wedge of a boundary region R does not affect the state in the complement wedge (this just follows from semiclassical field theory). Thus, if we define $|\psi_1\rangle$ as

$$|\psi_1\rangle = e^{i\epsilon\phi}|\psi_0\rangle \tag{II.6}$$

the first equality in II.5 is satisfied. The second equality then implies that the expectation value of any operator in the algebra of \bar{R} is the same in both states:

$$\langle \psi_0 | X_{\bar{R}} | \psi_0 \rangle - \langle \psi_1 | X_{\bar{R}} | \psi_1 \rangle = 0 \tag{II.7}$$

Rewriting the second term using II.6 and expanding to first order in ϵ we obtain II.3.

This proves that within the code subspace, we can express operators in the entanglement wedge of R in terms of operators in the algebra of R. Moreover, if an operator on G has support outside EW(R), it must have no reconstruction in R. To see this, suppose that an operator ϕ on G had support outside EW(R) so that it fails to commute with some operator ϕ' on $EW(\bar{R})$. The argument above shows that there exists a reconstruction $O'_{\bar{R}}$ of ϕ' that acts on \bar{R} . If ϕ could be reconstructed with an operator O_R on R, we would have $[O'_{\bar{R}}, O_R] = 0$ which contradicts the fact that $[\phi', \phi] \neq 0$.

Our final conclusion is that an operator acting on a code subspace can be reconstructed in a region R of the CFT if and only if its support in entirely contained in EW(R). By exploiting the reconstructability for states

in the code subspace, we now explore how the bulk, including the conformal metric, is encoded in the CFT.

We note that the reconstructability argument itself is a statement about a special class of quantum states and makes no reference to the plank length in the bulk. However, in making the connection between the reduced density matrix in the entanglement wedge [8] and the boundary, one clearly needs to assume some notion of locality. In particular, this involves taking $N \to \infty$.

III. SUPERFICIALLY LOCAL OPERATORS

For the rest of this paper we work in the context of the "infinite N limit." It is assumed that there are code subspaces $\{G\}$ of the CFT Hilbert space H that are holographically dual to quantum field theory on (asymptotically AdS) spacetime backgrounds. Setting $N = \infty$ in this way may cause discomfort, especially with some of the more complicated things we discuss below, and for this reason we have provided appendix A which defines our quantities while taking the large N limit more carefully. Even without reading the appendix, the majority of our development can made much more precise simply by replacing equalities with approximate equalities which, in the large N limit, approach authentic equalities.

In this section we are going to almost completely answer a fundamental question: Suppose that a code subspace G is given and that we are told that G is dual to some unknown field theory on some unknown spacetime background. Let ϕ be a given operator on G. Is ϕ dual to a local operator? Note that we are given no information about ϕ (other than how it acts on G) and, in particular, it is probably not a local CFT operator. The ability to answer this question is equivalent to finding all of the CFT operators that are dual to local bulk operators with respect to our particular code subspace.

Prior work addresses related issues but falls short of providing a general identification of local bulk operators. Consider, again, the HKLL method [4]. If ϕ is a quantum field in the bulk M, then, given a point $p \in M$, it is possible to solve the field equation of motion and obtain an expression of the form

$$\phi(p) = \left(\int_{\partial M} K(p, x) O(x) d^{D-1} x \right) \Big|_{G}.$$
 (III.1)

Here, the boundary field O is the one associated with ϕ through the extrapolate dictionary. As discussed above, the integration kernel K is not unique. While different choices of K yield different CFT operators, the restriction of these different choices of operators to the code subspace G must always give the same answer.

At a first glance, equation III.1 appears to not only identify the nonlocal CFT operators that are dual to local bulk operators, but even provides a formula for them. This is not the case however. The integration kernel can only be found by solving equations of motion on the curved spacetime background M, and this assumes



FIG. 2. A nonlocal bulk operator ϕ_1 will clearly lie in fewer regions than an operator ϕ_2 whose support is entirely contained in the first $\mathcal{Q}(\phi_1) \subset \mathcal{Q}(\phi_2)$.

knowledge of what the background is. There are very few code subspaces for which the corresponding geometry is known. Another reason that the HKLL procedure is unsatisfactory for our purposes is that it only identifies a subset of the boundary operators that are dual to local bulk operators. We would like to find a more general characterization of locality in the bulk at leading order in 1/N.

A. Comparing Locality of Operators

Our guiding principle is that that, roughly speaking, the more local a bulk operator ϕ is, the more distinct boundary regions exist for which ϕ can be reconstructed. This follows from subregion duality as explained in section II. To make this concept more precise, we are going to employ the full power of the quantum error-correcting structure of AdS/CFT to introduce a function Q that maps operators on G to the collection of all possible boundary regions that can reconstruct a given operator. Q will then provide a measure of locality of every operator. We now explain this precisely.

Let \mathcal{R} denote the collection of all D-2 dimensional achronal submanifolds of ∂M . Informally, \mathcal{R} is the collection of all regions R upon which one would compute a von Neumann entropy by anchoring stationary surfaces [22, 23] to ∂R . Note that we are not restricting to a single time slice of ∂M . If $R \in \mathcal{R}$ and ϕ is an operator that, along with its hermitian conjugate, acts on the code subspace G, then ϕ is said to be reconstructable in R if there exists O in the algebra of R such that $O|_G = \phi$ and $O^{\dagger}|_G = \phi^{\dagger}$. We now give a critical definition:

Definition. Suppose that ϕ is an operator on G and

 $R \in \mathcal{R}$. Then, we define

$$\mathcal{Q}(\phi) = \{ R \in \mathcal{R} \mid \phi \text{ is reconstructable in } R \}.$$

Whatever the (unknown) geometry of M is, subregion duality (see section II) gives a geometrical condition for $\mathcal{Q}(\phi)$ to contain a region R. Specifically, $R \in \mathcal{Q}(\phi)$ if and only if the (bulk) support⁵ of ϕ is contained in the entanglement wedge of R. This immediately implies the following properties of \mathcal{Q} :

Proposition III.1. Let ϕ_1 and ϕ_2 be two operators on the code subspace G. Then,

- 1. If supp $\phi_1 \supseteq$ supp ϕ_2 , then $\mathcal{Q}(\phi_1) \subseteq \mathcal{Q}(\phi_2)$,
- 2. if supp $\phi_1 = \text{supp } \phi_2$, then $\mathcal{Q}(\phi_1) = \mathcal{Q}(\phi_2)$.

Note that the converses to these statements, though seemingly desirable, are false in many cases. This is somewhat disappointing: the bulk support of an operator is a property of the operator's bulk description while Qis a function that is manifestly defined in the boundary theory. Our goal is to find a "boundary-only" characterization of bulk locality, so we would be much better off if the converse to Proposition III.1 were in fact true.

What \mathcal{Q} does accomplish is that it identifies the support of an operator to the greatest possible "resolution" that the boundary theory can easily see. For this reason we define an equivalence relation on operators on G: $\phi_1 \sim \phi_2$ if $\mathcal{Q}(\phi_1) = \mathcal{Q}(\phi_2)$. We use the notation $[\phi]$ to denote the equivalence class of ϕ with respect to this relation. In other words, $[\phi] = Q^{-1}(Q(\phi))$. Two operators are in the same class if they are "the same as far as \mathcal{Q} can tell." We can attempt to compare the locality of two operators by putting a partial ordering on the collection of equivalence classes by writing $[\phi_1] \leq [\phi_2]$ if $\mathcal{Q}(\phi_1) \subseteq \mathcal{Q}(\phi_2)$ (which is a well-defined relation). Note that a trivial operator like the identity on G, denoted by $\mathbf{1}_G$, can be reconstructed in any region. Thus, $[\phi] \leq [\mathbf{1}_G]$ for any operator ϕ on G.

We are now ready to give a plausible characterization of a local bulk operator by means of Q.

Definition. Suppose that ϕ is an operator on G. ϕ is said to be *superficially local* if

- 1. $[\phi] \neq [1_G]$ and
- 2. Every operator ϕ' with the property that $[\phi] \leq [\phi']$ has $[\phi'] \in \{[\phi], [1_G]\}.$

⁵ The support of an operator is defined as follows. Let A be a (possibly nonlocal) operator on a quantum field theory on the curved spacetime M. Let U be the set of points in M such that for every point p in U, every local bulk operator at p commutes with A. Then, the support of A, denoted by supp A, is given by $M \setminus (J_+(U) \cup J_-(U))$

We emphasize that the definition of a superficially local operator makes reference only to the boundary theory. Thus, we can use this definition to offer an answer to the question posed above: if we are given a large N CFT with a Hilbert space H, a subspace G of H, and an operator ϕ , and if we told that G is a code subspace corresponding to an unknown bulk spacetime, then we can guess that ϕ is a local operator in the dual bulk theory if it acts on G and if its restriction to G is a superficially local operator. This answer turns out to be right in many cases.

The word "superficial" is used for two reasons. First, as we will shortly see, there are examples of asymptotically AdS spacetimes for which some local bulk operators (for instance, those lying close to a spacelike singularity) are not superficially local. Second, we will not prove that every superficially local operator is local in the bulk. The first of these deficiencies is completely unavoidable and it is tempting to contemplate its relation to the difficulties of using AdS/CFT to describe points deep within a black hole interior [24] (although we will not pursue such contemplations here). The second apparent deficiency is not a problem: in section IV we will argue that it is possible to identify when a given equivalence class of superficially local operators contains operators that are not actually local in the bulk. This argument will be made in the boundary theory. The concept of superficial locality therefore provides a way to confidently identify a very large collection of operators on G that should be interpreted as local operators in the bulk. We now explain exactly which bulk operators can be found in this way.

B. The Localizable Region

As above, let M be the asymptotically AdS bulk spacetime that is dual to a code subspace G of a CFT in the large N limit with Hilbert space H. In this section we are going to identify a special subset of M, denoted by Loc(M), which has the property that local bulk operators at points in Loc(M) can be successfully identified in the boundary theory through the consideration of superficially local operators.

Definition. The *localizable region* of M, denoted Loc(M), is the set of points $p \in M$ satisfying

- 1. If supp $\phi = \{p\}$, then ϕ is superficially local and
- 2. if supp $\phi = \{p\}$ and $[\phi'] = [\phi]$, then supp $\phi' = \{p\}$.

Elements of Loc(M) will sometimes be called *localizable* points. Note that Loc(M) is a subset of the bulk and its definition makes reference to the concept of the bulk support of an operator, so this definition is not particularly transparent from the boundary theory. However, a connection with the boundary theory becomes apparent when Loc(M) = M:

Proposition III.2. If Loc(M) = M, an operator ϕ on G is superficially local if and only if it is local in the

bulk. Moreover, if ϕ_1 and ϕ_2 are two superficially local operators with $[\phi_1] = [\phi_2]$, then they must be local at the same bulk point.

Proof. If ϕ is a local operator, the definition of Loc(M) immediately demands that ϕ is superficially local. Conversely, let suppose that ϕ is superficially local. If ϕ is not local in the bulk, then there are at least two distinct points p and q in the support of ϕ . Let ϕ' be a local operator at p. By Proposition III.1, the fact that $\text{supp} \phi' \subseteq \text{supp} \phi$ means that $[\phi] \leq [\phi']$. But ϕ is superficially local and ϕ' is nontrivial so we conclude that $[\phi] = [\phi']$. The definition of the localizable region now demands that $\sup \phi = \{p\}$, a contradiction.

Now suppose that ϕ_1 and ϕ_2 are two superficially local operators with $[\phi_1] = [\phi_2]$. From what we just proved, we know that ϕ_1 is local at some point, so the definition of the localizable region immediately demands that ϕ_1 and ϕ_2 are local at the same point.

This result is a first step to providing a boundary description of Loc(M) because the notion of superficial locality is one of the boundary theory. Unfortunately the hypothesis of Proposition III.2 is often too much to ask for. To better understand this, consider the following result which which establishes a geometrical bulk interpretation of Loc(M).⁶

Theorem III.1. $p \in Loc(M)$ if and only if there exists a subset \mathcal{R}_0 of the collection of boundary regions \mathcal{R} such that

$$\bigcap_{R \in \mathcal{R}_0} \mathrm{EW}(R) = \{p\}.$$

Proof. Suppose first that there exists \mathcal{R}_0 satisfying the condition given in the statement of the theorem. Fix a local bulk operator ϕ at p so that supp $\phi = \{p\}$. $\mathcal{Q}(\phi)$ must contain all regions R with $p \in EW(R)$ so, in particular, $\mathcal{R}_0 \subseteq \mathcal{Q}(\phi)$. If ϕ' is some operator on G with $[\phi'] \ge [\phi]$, then $\mathcal{Q}(\phi) \subseteq \mathcal{Q}(\phi')$ so we have

$$\begin{split} \operatorname{supp} \phi' &\subseteq \bigcap_{R \in \mathcal{Q}(\phi')} \operatorname{EW}(R) \subseteq \bigcap_{R \in \mathcal{Q}(\phi)} \operatorname{EW}(R) \\ &\subseteq \bigcap_{R \in \mathcal{R}_0} \operatorname{EW}(R) = \{p\}. \end{split}$$

This implies that ϕ is superficially local so the first condition for $p \in \text{Loc}(M)$ is satisfied. If it happens that the operator ϕ' above satisfies $[\phi'] = [\phi]$, our argument still applies and we must therefore have $\sup \phi' \subseteq \{p\}$. It is not possible to have $\sup \phi' = \emptyset$ since this would require

⁶ Theorem III.1 elucidates the connection between our program and the ideas of [25–30]. Note this work is primarily interested in the reconstruction of bulk geometry while our focus is on operator reconstruction. However, below in section IV we will reconstruct aspects of the bulk geometry.

that $[\phi'] = [\phi] = \mathcal{R}$ which is false. We conclude that supp $\phi' = \{p\}$ and thus that $p \in \operatorname{Loc}(M)$.

We now prove the converse. Let p lie in Loc(M). Suppose that there does not exist any $\mathcal{R}_0 \subseteq \mathcal{R}$ with $\bigcap_{R \in \mathcal{R}_0} EW(R) = \{p\}$. Let ϕ be a local operator at p which requires that ϕ is superficially local. There must exist a point $q \in M$ with

$$q \in \left(\bigcap_{R \in \mathcal{Q}(\phi)} \mathrm{EW}(R)\right) \setminus \{p\}$$

Now consider a local operator ϕ' at the point q. Since q lies in the entanglement wedge of every region whose entanglement wedge contains p, we have $[\phi] \leq [\phi']$. The superficial locality of ϕ , along with the fact that ϕ' is not trivial, implies now that $[\phi] = [\phi']$ which, by the definition of Loc(M), implies that $\text{supp } \phi' = \{p\}$ which is a contradiction.

Theorem III.1 is a useful tool for identifying examples of localizable regions in asymptotically AdS spacetimes as we will do in section III D. For now, we only advertise some facts that may be of interest. Localizable regions can extend quite far into the bulk spacetime. For the same reason that extremal surfaces can penetrate event horizons in some cases, Loc(M) can intersect a black hole interior. However, points that are too close to spacelike singularities are not localizable. Another interesting property of localizable regions is that they are not always subsets of the portion of the bulk that is accessible to boundary-anchored extremal codimension 2 surfaces with minimal area. In other words, Loc(M) can have a nonempty intersection with the entanglement shadow [31]. Before discussing these examples, however, we are going to introduce an object that will greatly increase the motivation for studying the localizable region.

C. The Space of Classes

The object that we now study is the collection of all equivalence classes of superficially local operators on G. We suggestively denote this set by \tilde{M} :

$$\tilde{M} = \{ [\phi] \mid \phi \text{ is a superficially local operator on } G \}.$$

Given that an element $P \in \tilde{M}$ is a set of operators, all of which have the same value of Q, it is convenient to let define Q(P) as $Q(\phi)$ for any choice of $\phi \in P$.

An intuitive picture of \tilde{M} is clear when M = Loc(M). In this case, Proposition III.2 shows that there is a oneto-one correspondence between \tilde{M} and M. The correspondence is that a point $p \in M$ is identified with the collection of all local operators at p. This reveals a new approach to bulk reconstruction from the boundary theory, somewhat similar in spirit to that of [10], which we will explore below. Let us now make no assumptions about Loc(M) and determine the general structure of \tilde{M} . What we are going to find is that \tilde{M} is equal to Loc(M) with the possible addition of some extra points in \tilde{M} . We refer to these unwanted extra points as "clumps."

First suppose that $p \in \operatorname{Loc}(M)$ and let ϕ be a local bulk operator at p. Then, $[\phi]$ consists only of local operators at p. (This follows directly from the definition of the localizable region.) As a consequence, a copy of $\operatorname{Loc}(M)$ can always be identified in \tilde{M} . Another thing that we can immediately show is that if Φ is any superficially local operator whose support consists of more than one point, then $\operatorname{supp} \Phi \cap \operatorname{Loc}(M) = \emptyset$. To see, this, suppose that $p \in \operatorname{supp} \Phi \cap \operatorname{Loc}(M)$ and consider a local operator ϕ at p. We would then have $[\Phi] \leq [\phi]$ with Φ superficially local so $[\Phi] = [\phi]$. This contradicts the definition of $\operatorname{Loc}(M)$ since Φ is nonlocal.

We cannot exclude the possibility that there exist nonlocal superficially local operators. To investigate this issue carefully, we introduce a map C that sends a point P in \tilde{M} to a subset of M as follows:

$$C(P) = \bigcup_{\Phi \in P} \operatorname{supp} \Phi.$$

C has some nice properties:

Proposition III.3. Suppose that P and Q are elements of \tilde{M} . Then,

- 1. If every element of P is a local bulk operator, then there exists a point $p \in Loc(M)$ such that $C(P) = \{p\},\$
- 2. if P contains a nonlocal operator, then $C(P) \cap Loc(M) = \emptyset$,
- 3. if $C(P) \cap C(Q) \neq \emptyset$, then P = Q and, in particular, C is injective.

Proof. 1. If P consists of only local operators, then all of those operators must be at the same bulk point. To see this, suppose that ϕ_1 and ϕ_2 are two local bulk operators at bulk points p_1 and p_2 respectively. Now $\mathcal{Q}(\phi_1) = \mathcal{Q}(\phi_2)$ so any linear combination $\alpha\phi_1 + \beta\phi_2$ must satisfy $[\phi_1] \leq [\alpha\phi_1 + \beta\phi_2]$. The superficial locality of ϕ_1 now proves that $[\phi_1] = [\alpha\phi_1 + \beta\phi_2]$ which contradicts the assumption that P consists only of local operators unless $p_1 = p_2$. Now let p denote the unique point in M where the elements of P are supported. It is obvious now that $C(P) = \{p\}$. Moreover, every local operator at p must lie in P and since there are no operators in P with support beyond $\{p\}$ we conclude that $p \in \operatorname{Loc}(M)$.

2. Assume that P contains a nonlocal bulk operator and suppose that $q \in C(P) \cap \operatorname{Loc}(M)$. Let ϕ denote a local operator at q. There must be some operator $\Phi \in P$ with $q \in \operatorname{supp} \Phi$ so $[\Phi] \leq [\phi]$ from which the superficial locality of Φ implies that $[\Phi] = [\phi]$ which is equivalent to the statement that $[\phi] \in P$. But this means that ϕ , a local operator in $\operatorname{Loc}(M)$, is equivalent to a nonlocal operator. This is a contradiction. 3. Suppose that there exists a bulk point $x \in C(P) \cap C(Q)$. Let ϕ denote a local operator at x. An argument identical to what was given for the proof of statement 2 shows that $\phi \in P$ and $\phi \in Q$. But P and Q are equivalence classes so the fact that they share an element means that P = Q.

This argument shows that \tilde{M} can be thought of as the union of Loc(M) with some extra points. Each extra point P has the property that C(P) is a subset of M with more than one element. These objects are subtle enough to deserve a name:

Definition. Suppose that $P \in \tilde{M}$ has the property that C(P) has more than one element. Then, we will call both P and C(P) a *clump*.

Clumps are somewhat problematic because both local and nonlocal operators in clumps are superficially local. They therefore represent a potential threat to our approach. However, there is good news: we will argue in section III E that clumps can be identified and removed using only the boundary theory (e.g. without relying on concepts like the bulk support of operators). Roughly speaking, clumps are associated with phase transitions for holographic entanglement entropy, and such phase transitions are visible in the boundary.

We are now in a position to give a much stronger answer to the fundamental question posed at the beginning of this section about identifying the operators on G that are dual to local operators in the bulk.

Theorem III.2. If there are no clumps, an operator ϕ on the code subspace G is dual to a local bulk operator in the localizable region if and only if ϕ is superficially local.

If we assume the clump conjecture of section III E, which provides a way to identify and eliminate clumps, this conclusion provides the boundary dual to the concept of a bulk local operator (within a certain region of the bulk).

D. Examples

Examples can greatly clarify the machinery we have been developing. In particular, the spacetimes below demonstrate several features:

- Despite being associated with HRT surfaces, Loc(M) can probe entanglement shadows.
- Loc(M) can intersect black hole interiors (but it does not extend arbitrarily closely to spacelike singularities).
- In regions that are close to spacelike singularities, local operators are not superficially local.
- Clumps can occur, but the only known examples are associated with phase transitions where extremal surfaces "jump" around them.



FIG. 3. Conical AdS is an example of how points in the bulk that are not directly probed by extremal surfaces can still be in the localizable region. Despite the entanglement shadow (the grey cylinder), points can be localized because they can intersect boundaries of entanglement wedges.

Vacuum AdS

The simplest example is when M is vacuum AdS space (or any small perturbation of vacuum AdS) with dimension $D \ge 2 + 1$. For any point $p \in M$, theorem III.1 immediately shows that $p \in \text{Loc}(M)$. This is because in AdS space, one can always construct D - 1 codimension 2 stationary surfaces intersecting p, whose tangent spaces at p are pairwise distinct, and then find the corresponding boundary regions $R_1, \ldots R_{D-1}$ on which these stationary surfaces are anchored. To prove that $p \in \text{Loc}(M)$, we then consider the collection of regions $\{R_1, \ldots, R_{D-1}, \bar{R}_1, \ldots, \bar{R}_{D-1}\}$ and apply this set to theorem III.1.

Conclusion: If we somehow know that G is dual to a spacetime close to vacuum AdS, then an operator on G is local if and only if it is superficially local. The space of classes of superficially local operators, \tilde{M} , is a reconstruction of the bulk.

Conical AdS

Anti-de Sitter space with a conical deficit is a simple example of a spacetime with an entanglement shadow 7

⁷ To our knowledge, [31] and related work has only studied regions that are not probed by minimal surfaces anchored to static

[31]. Given that Loc(M) can be defined by means of HRT surfaces, one might suspect that for conical AdS, Loc(M) is a proper subset of M. We will explain why this is not the case and that, in fact, we again have Loc(M) = M.

Let *n* be an integer greater than 1 and consider, for example, $M = \text{AdS}_{2+1}/\mathbb{Z}_n$. The metric can be written as

$$ds^{2} = -\left(\frac{1}{n^{2}} + \frac{r^{2}}{L^{2}}\right)dt^{2} + \left(\frac{1}{n^{2}} + \frac{r^{2}}{L^{2}}\right)^{-1}dr^{2} + r^{2}d\phi^{2}$$
(III.2)

where $-\infty < t < \infty$, r > 0, and $\phi \in [0, 2\pi)$. There is a critical radius $r_{\rm crit}$ such that no HRT surface intersects the region $r < r_{\rm crit}$. If $\{R_s\}$ is a continuous nested family of boundary regions with R_{-1} a small region and R_1 wrapping around almost the entire boundary, the HRT surface anchored to R_s , $extR_s$, will discontinuously jump around the shadow at some critical value of s. Note that this phenomenon is not related to extremal surface barriers [32] but is instead a consequence of there being more than one stationary codimension 2 surface anchored to any given boundary region: no HRT surface enters the shadow because there would always be another stationary surface that does not enter the shadow with smaller area. The discontinuous jump can be regarded as a phase transition in the sense that the von Neumann entropy $S(R_s)$, regarded as a function of the parameter s, has a discontinuous derivative at the jump.

If $p \in M$ lies outside of the entanglement shadow, we must have $p \in \text{Loc}(M)$ for the same reason that every point is localized in vacuum AdS. On the other hand, suppose that p lies within the entanglement shadow. To show that $p \in \text{Loc}(M)$, all we need, by theorem III.1, is a finite set of boundary regions such that the intersection of their entanglement wedges is $\{p\}$.

This can by done by considering regions like those shown in figure 3. Note that only two regions are shown in the figure but that the point can be completely localized by adding other boundary regions such as rotations of the regions depicted. The trick here is easy to understand: it is not necessary for HRT surfaces to intersect localized points as long as boundaries of entanglement wedges intersect them instead.

Conclusion: If G is dual to a spacetime close to $\operatorname{AdS}_{2+1}/\mathbb{Z}_n$, then an operator on G is local if and only if it is superficially local. The space of classes of superficially local operators, \tilde{M} , is a reconstruction of the bulk.

Two-Sided Black Holes

In the case where M is an eternal AdS-Schwarzschild geometry, which has two disconnected boundary components, the localizable region extends into the black hole



FIG. 4.

interior but does not probe all the way to the singularity. This is depicted in figure 4. Many points in the interior region can be localized by considering boundary regions that consist of two disconnected components lying in different boundaries (see figure 4). HRT surfaces, however, do not reach points that are arbitrarily close the future or past singularities: there is a critical radius $r_{\rm crit}$ (smaller than the black hole radius) that no boundary-anchored extremal surface extends beyond [14, 32]. Figure 5 proves that local operators at points with radius $r < r_{\rm crit}$ are not superficially local. This portion of the spacetime is completely missed by our methods and will thus be called the *inaccessible region*.

Conclusion: If G is dual to an eternal AdS-Schwarzschild geometry (with two boundary CFTs), then an operator ϕ on G is superficially local if and only if it is dual to a local bulk operator at a bulk point with $r > r_{\rm crit}$. The space of classes of superficially local operators, \tilde{M} , is a reconstruction of the region of M with $r > r_{\rm crit}$.

Dynamical Black Holes

The previous example might have given the impression that Loc(M) cannot intersect a black hole interior without appealing to entanglement between two CFTs. This is not the case. Consider a black hole that forms from collapse in an asymptotically AdS spacetime. Then, it has been demonstrated [33] that HRT surfaces probe the black hole interior (although they do not approach the

boundary regions rather than the general stationary surfaces appearing in the calculation of covariant holographic entanglement entropy. Below we assume that the general features of the entanglement shadow in standard examples are unchanged if non-static surfaces are considered.



FIG. 5. When a point (purple) is close to a spacelike singularity, it is very difficult for the point to be in Loc(M). Quite generally, HRT surfaces are prevented from approaching such singularities [14, 32]. In this figure, the horizontal dashed line is a surface with the property that no HRT surface intersects its future. (This is more restrictive than an extremal surface barrier, which would prohibit smooth deformations of stationary surfaces.) A local operator at the purple point cannot be superficially local since a point in its past (blue) will typically be contained in strictly more entanglement wedges.

singularity arbitrarily closely). Because such HRT surfaces can be anchored to boundary regions at a variety of angular positions, we conclude that Loc(M) enters the black hole interior in this case. Note, however, that figure 5 again explains why regions too close to the singularity are not localizable.

Bag of Gold

Our fourth example is a "bag of gold" spacetime (see, e.g., [34]). The manifold M is an AdS-Schwarzschild spacetime with one of its two asymptotic regions removed and replaced with a patch of de Sitter space. The spacetime is static and spherically symmetric. Its Penrose diagram is shown in figure 6. We will label the regions in the diagram I-IV as shown in the figure (note that region II includes the de Sitter patch). It is very important to understand that unlike the two-side AdS-Schwarzschild spacetime, M has only one asymptotic boundary with topology $S^{D-2} \times \mathbf{R}$. The time slice Σ that is marked in figure 6 has the topology of $\mathbf{R}^{\mathbf{D}-1}$. In particular, Σ is simply connected and the homology constraint for HRT surfaces will not play any interesting role here. The dotted line in region I is a surface beyond which no HRT surface probes.

We will argue the following.

- 1. Loc(M) is the portion of region I that is probed by HRT surfaces.
- 2. \tilde{M} has a single clump whose image under C (see section III C) is all of region II. Thus, we will say that region II is a clump.
- 3. The rest of the spacetime (including regions II and IV) is neither localizable nor within clumps. It is "inaccessible."





FIG. 6. The bag of gold geometry we consider is obtained by removing an asymptotic region from an AdS black hole and replacing it with a patch of de Sitter space. As discussed in the text, the localizable region is the portion of region I that is accessible to HRT surfaces and region II is a single clump. The remaining portion of the spacetime is "inaccessible" in the sense that no operator with support in these regions is superficially local.

First let us discuss why region II is a clump. Like conical AdS, this spacetime exhibits phase transitions in its HRT surfaces as well as an entanglement shadow. Consider the boundary time slice $\sigma = \partial \Sigma$ and let R_{ψ} be a spherical cap on σ with opening angle ψ (defined so that $R_{\pi} = \sigma$). The spacetime in region I is identical to region I of AdS-Schwarzschild so the structure of stationary codimension 2 boundary-anchored surfaces must also be the same and, in particular, there are always two distinct stationary surfaces anchored to R_{ψ} . At $\psi = \pi/2$, there is a phase transition with a discontinuity in the first derivative of $S(R_{\psi})$. At this transition, the minimal surface jumps around the entire region II. Note also that HRT surfaces fail to even contact the bifurcation throat: there is, once again, a minimal radius in region I, $r_{\rm crit}$, greater than the black hole radius, within which no HRT surface extends.

If $\psi < \pi/2$, the spatial region V_{ψ} on Σ between R_{ψ} and its HRT surface ext R_{ψ} is confined to region I. Thus $\mathrm{EW}(R_{\psi})$ is confined to region I; this follows from the fact that $\mathrm{EW}(R_{\psi}) = D(V_{\psi})$ after compactification. Meanwhile, When $\psi > \pi/2$, V_{ψ} contains the entire intersection of Σ with region II and $\operatorname{EW}(R_{\psi})$ must contain all of region II. These observations were made for a simple spherical cap on the time-reversal symmetric slice Σ , but they hold very generally: any time we consider a nested family of boundary regions $\{R_s \in \mathcal{R}\}$, $\operatorname{EW}(R_s)$ is confined to region I for s smaller than some critical value and $\operatorname{EW}(R_s)$ contains all of region II when s exceeds this value.

What this shows is that if ϕ_1 and ϕ_2 are two bulk operators with support in region II, we must have $\mathcal{Q}(\phi_1) =$ $\mathcal{Q}(\phi_2)$. Moreover, note that any operator ϕ which is supported in region II must be superficially local. To see this, consider any $x \in M \setminus ($ region II). If x is in region I or III, take a spherical cap like R_{ψ} with $\psi > \pi/2$, but place it on a boundary time slice at very early time. No matter how early time time is taken, time-translation invariance guarantees that region II is still contained in $EW(R_{\psi})$, but by sending the boundary time slice to $-\infty$, we can put any point in regions I or III in the future of ext R_{ψ} . This means that there exists some $R \in \mathcal{Q}(\phi) \setminus \mathcal{Q}(\phi')$ so $\phi \leq \phi'$. The same argument can be made if x is in region IV by sending the boundary time slice to $+\infty$. We conclude that ϕ must be superficially local and region II is thus a clump (since all operators with support in region II are superficially local and have the same image under \mathcal{Q}).

Let us finally study the remainder of the spacetime. The portion of region I that is probed by HRT surfaces is readily seen to be contained in Loc(M). We now outline an argument that, in fact, this probed region is exactly Loc(M). Figure 5 gives an explanation of why local operators in region III cannot be localized. More generally, consider a local bulk operator ϕ_x at a point x lying outside of the region probed by HRT surfaces but also lying outside of the clumped region II. If R is a boundary region with $x \in \text{EW}(R)$, then R must be large enough to have undergone a phase transition so that region II is contained in the entanglement wedge of R as well. This means that if Φ is any superficially local operator in the clump, we have $\mathcal{Q}(\phi_x) \subsetneq \mathcal{Q}(\Phi)$. This shows that ϕ_x cannot be superficially local.

Conclusion: Suppose that G is dual to the bag of gold geometry. If ϕ is a superficially local operator, then it is either a local operator in the portion of region I probed by extremal surfaces or it is some operator (which need not be local) with support in region II. The clump conjecture of section IIIE is valid for this spacetime, so the problematic superficially local operators can be identified and discarded. After doing so, the remaining superficially local operators exactly form the collection of all bulk local operators in Loc(M).

E. The Clump Conjecture⁸

In this section we propose a way to use the boundary theory to identify and remove clumps from \tilde{M} . Specifically we give an alternative definition of a clump that does not make direct reference to the bulk and we conjecture that our two definitions are equivalent. We know of no counterexamples to the conjecture and there is good evidence for its general validity.

The basic motivation is as follows. If $P \in \tilde{M}$ is a clump, then, by definition, C(P) contains more than one bulk point. Generically, clumps have nonzero spacetime volume. On the other hand, we know that no entanglement wedge can contain only part of a clump: if $R \in \mathcal{R}$, then either $C(P) \subseteq EW(R)$ or $C(P) \cap (EW(R))^{\circ} = \emptyset$. These observations indicate that if R_s is a continuous nested one-parameter family of regions in \mathcal{R} such that $R_s \in \mathcal{Q}(P)$ for s > 0 and $R_s \notin \mathcal{Q}(P)$ when s < 0, we must have some form of a discontinuity in the entanglement wedges $EW(R_s)$ as a function of s at s = 0. Such discontinuities occur when the HRT surfaces anchored to $\{R_s\}$ jump discontinuously. But such a jump can often be seen in the boundary theory in the form of a discontinuity in a derivative of the von Neumann entropy of the boundary regions R_s .

Before stating the conjecture formally, we give a useful definition:

Definition. Let ϕ be an operator on G and $R \in \mathcal{Q}(\phi)$. R is said to be *minimal* if whenever $R' \subsetneq R$, $R \notin \mathcal{Q}(\phi)$.

We will also introduce the map \overline{Q} by letting $\overline{Q}(\phi)$ denote the collection of minimal elements of $Q(\phi)$. Additionally, if $P \in \tilde{M}$, we will define $\overline{Q}(P)$ as $\overline{Q}(\phi)$ for any choice of $\phi \in P$ (all choices of ϕ have the same $\overline{Q}(\phi)$).

As suggested above, phase transitions in the boundary theory will play a role in the boundary identification of clumps. To be clear, a "phase transition" refers to the following situation. Suppose that $\{R_s | -1 < s < 1\}$ is a regular⁹ one-parameter family of boundary regions with $R_{s_1} \subsetneq R_{s_2}$ whenever $s_1 < s_2$. Let $S(R_s)$ denote the von Neumann entropy of the boundary region R_s in any state¹⁰ in the code subspace G. We say that there is a phase transition at s = 0 if some derivative of $S(R_s)$ at s = 0 is discontinuous. Moreover, if $R \in \mathcal{R}$, we will say that there is a phase transition at R if there is some

⁸ Section III E presents material that significantly strengthens our conclusions. However, it may be distracting to focus on such technicalities and some may choose to pass over this section.

⁹ By "regular" we mean that R_s deforms smoothly enough that we are not introducing discontinuities in any derivative of von Neumann entropy by choosing an awkward parameterization of regions.

 $^{^{10}}$ $S(R_s)$ is state-dependent, but the spacetime background is approximately fixed within the code subspace G, so assertions about phase transitions will be state-independent at leading order.

one parameter deformation of the form above, $\{R_s\}$, with $R_0 = R$.

We now state our proposal for identifying and removing clumps. We will refer to it as the *clump conjecture*:

Suppose that $P \in \tilde{M}$. P is a clump if and only if for every $R \in \overline{Q}(P)$, there is a phase transition at R.

We immediately note that this conjecture is consistent with the examples provided in section III D. The only example we gave of a clump is that of the bag of gold spacetime which always features phase transitions for minimal regions. Consider, however the example of $\operatorname{AdS}_{2+1}/\mathbb{Z}_n$. This may appear to contradict the clump conjecture because it is a spacetime with no clumps but which does posses phase transitions. However, consider regions like the ones depicted in figure 3. These are indeed minimal regions for the operator at the point depicted (which corresponds to a point in \tilde{M} . However, there is no phase transition at such a region. This is why the statement of the clump conjecture requires that there is a phase transition for every $R \in \bar{Q}(P)$.

IV. RECONSTRUCTION OF CAUSAL STRUCTURE AND BEYOND

From here on we assume the validity of the clump conjecture (which we strongly expect) and use a new definition of \tilde{M} :

 $\tilde{M} = \left\{ [\phi] \mid \phi \text{ is superficially local and } [\phi] \text{ is not a clump} \right\}$

This can be done using only the boundary theory. Simply begin with \tilde{M} as defined previously, and then remove clumps from it by using the clump conjecture.

With this new definition, a major conclusion of section III is that in some sense \tilde{M} is isomorphic to Loc(M)although we have not been very clear about what sort of isomorphism this is. We are now going to take the view that \tilde{M} can be thought of as a reconstruction of the bulk very seriously. We will successfully determine a metric on \tilde{M} up to a conformal rescaling. This will be done using only information available in the boundary theory (which includes the definition of \tilde{M} itself). The manifold \tilde{M} and its causal structure will exactly reproduce that of Loc(M). This constitutes a boundary reconstruction of the metric on Loc(M) up to its conformal factor.

A. Spacelike Separation and Microcausality

The key insight to identifying a causal structure on \tilde{M} is to note that \tilde{M} consists of collections of operators on the code subspace G and that the commutation relations amongst those operators must betray an aspect of the bulk spacetime geometry. This suggests the following definition:

Definition. Suppose that $P, Q \in \tilde{M}$. We say that P and Q are *spacelike separated* if for every $\phi_1 \in P$ and $\phi_2 \in Q$, we have $[\phi_1, \phi_2] = 0$. Otherwise, we say that P and Q are *causally related*.

There are two things to immediately notice about this definition. First, while we have defined the statement that P and Q are causally related, we have not yet given meaning to the statement that P is to the future of Q. This will be addressed below. Second, note that for P and Q to be causally related, all that is necessary is that there exists some $\phi_1 \in P$ and some $\phi_2 \in Q$ such that ϕ_1 and ϕ_2 fail to commute. It is certainly not necessary that all such operators would fail to commute.

In special cases, it is possible to conclude that P and Q are spacelike separated without relying directly studying the commutativity of their operators. If it happens that there exists $R_1 \in \mathcal{Q}(P), R_2 \in \mathcal{Q}(Q)$ with the property that R_1 and R_2 are spacelike separated in the boundary, meaning that

$$\left(J_+^{\partial}(R_1) \cup J_-^{\partial}(R_1)\right) \cap R_2 = \emptyset,$$

then microcausality in the boundary field theory guarantees that any operators O_1 and O_2 in the algebras of R_1 and R_2 respectively must have $[O_1, O_2] = 0$. In particular, for any $\phi_1 \in P$ and $\phi_2 \in Q$, we can find reconstructions of ϕ_1 and ϕ_2 in R_1 and R_2 respectively and conclude that $[\phi_1, \phi_2] = 0$. However, this situation is too much to ask for in general.

In the case where two classes P and Q are causally related, the above logic indicates that there absolutely cannot be any $R_1 \in \mathcal{Q}(P), R_2 \in \mathcal{Q}(Q)$ with the property that R_1 and R_2 are spacelike separated in the boundary. This is consistent with a theorem in bulk geometry which is a necessary result for the consistency of entanglement wedge reconstruction:

Proposition IV.1. Let M be an asymptotically AdS spacetime and suppose that $p, q \in M$ are bulk points with $q \in I_+(p)$. Suppose, moreover, that there exist boundary regions $R_1, R_2 \in \mathcal{R}$ such that $p \in EW(R_1), q \in EW(R_2)$. Then, $(I^{\partial}_+(R_1) \cup I^{\partial}_-(R_1)) \cap R_2 \neq \emptyset$.

Proof. Choose a Cauchy surface σ of ∂M with $R_1 \subseteq \sigma$ and let $\bar{R}_1 = \sigma \setminus R_1$. Let Σ be any AdS-Cauchy surface for the bulk with $\partial \Sigma = \sigma$ and write $\Sigma = S \cup \bar{S}$ where $S \cap \bar{S}$ is the HRT surface of R_1 . Then, $q \notin EW(\bar{R}_1)$. (This follows from the fact that $EW(R_1) = D(S)$ and $EW(\bar{R}_1) = D(\bar{S})$.)

Suppose that we had $R_2 \subseteq D^{\partial}(\bar{R}_1)$. Wall's entanglement wedge nesting theorem [14] implies that this would require that $EW(R_2) \subseteq EW(\bar{R}_1)$ which contradicts the fact that $q \in EW(R_2)$. Thus, R_2 is not contained (entirely) in $D^{\partial}(\bar{R}_1)$. On the other hand, the boundary is flat so $D(\bar{R}_1) = \partial M \setminus (I^{\partial}_+(R_1) \cup I^{\partial}_-(R_1))$. We conclude that R_2 intersects $I^{\partial}_+(R_1) \cup I^{\partial}_-(R_1)$. \Box

B. Time Orientation

Suppose that P and Q are points in M that are causally related. Then, the corresponding bulk points, p and q respectively, must either have $p \in J_+(q)$ or $q \in J_+(p)$. But how do we know which?

There may be a very direct way to answer this question. Here, however, we give a topological answer. In appendix B we explain how \tilde{M} be be made into a topological space. The basic idea is fairly obvious: two points in \tilde{M} are close to each other if their images under Q are close. Because this topology will be consistent with the bulk topology on Loc(M), we can make use of topological features of the causal structure of the spacetime Loc(M).

Of particular use is the fact that if $p \in M$, $J_{+}(p)$ is connected (as is $J_{-}(p)$). Because Loc(M) may be a proper subset of M, it is possible that $J_+(p) \cap Loc(M)$ is not connected. Nonetheless, we can consider the connected component of $J_+(p) \cap Loc(M)$ that contains p. The same construction must be possible in \tilde{M} , but we have to be somewhat more careful. For $P \in \tilde{M}$, we can consider the set of points K that are causally related to P. This includes P itself. We can then consider $K \setminus \{P\}$ and look at the two connected components of K that are arbitrarily close to P. (There must be exactly two such components because the topology on \tilde{M} needs to be consistent with that of Loc(M).) We label these two components $J_{+}(P)$ with the understanding that we have yet to determine which component deserves a plus sign and which deserves a minus sign.

Suppose we arbitrarily choose which of the two regions is to be called $\tilde{J}_+(P_0)$ for one particular point P_0 . In all but the most pathological of connected spacetimes, this fixes the time orientation for every other point in the spacetime. For example, suppose that P_1 is another point in \tilde{M} and that $P_1 \in \tilde{J}_+(P_0)$. (Here we are making use of our arbitrary decision about $\tilde{J}_+(P_0)$.) Then, we must assign the orientation at P_1 so that $P_0 \in \tilde{J}_-(P_1)$. But now, if we find another point $P_2 \in \tilde{J}_-(P_1)$, we must have that $\tilde{J}_+(P_2)$ contains P_1 . Continuing in this way, we can expect to be able to fix the time orientation for every point in \tilde{M} as long as it is connected. This process is depicted in figure 7

But what about the overall time orientation? That is, how do we decide on $\tilde{J}_+(P_0)$ in our example above? This can be done by beginning with a point in \tilde{M} that corresponds to local boundary operators at some boundary point. On ∂M , we already have a notion of future and past. Thus, if we take P_0 to be an equivalence class consisting only of local boundary operators at a point $x \in \partial M$, we can decide upon $\tilde{J}_+(P_0)$ by requiring that if P_1 is another class of local boundary operators lying at a point y then $P_1 \in \tilde{J}_+(P_0)$ only if $y \in J^{+}_{+}(x)$.

We have now succeeded in defining a causal structure on \tilde{M} that must be consistent with that on Loc(M). As a consequence, we have reconstructed the metric in Loc(M) up to an undetermined conformal factor.



FIG. 7. If the definition of the future and past of a point $P_0 \in \tilde{M}$ is chosen, there is an immediate constraint on the time orientation at other points in \tilde{M} . In this figure, the orientation at P_0 also fixes the orientation at P_1 and P_2 .

C. Comparison with Light-Cone Cut Reconstruction

There is a compelling connection between the bulk reconstruction developed here and a recent approach to bulk reconstruction involving light-cone cuts due to Engelhardt and Horowitz [10]. Cut reconstruction is a new area of research [35–38], and remarkably, a number of the ideas involving cuts appear to have analogs in superficial locality reconstruction. We now detail the similarities and differences between the two approaches.

• Large N: Both cut reconstruction and reconstruction with superficial locality require in their current forms that the classical limit be taken. Light cone cuts are associated with singularities of correlation functions of local boundary operators that only resolve in the large N limit. These singularities in the boundary theory are at first mysterious but have a simple explanation if one knows about the dual bulk: if there is a bulk point p in the causal wedge of the boundary, then cut singularities are singularities of boundary n-point functions $\langle O(x_1) \dots O(x_n) \rangle$ that can occur when the boundary points lie on the future and past cuts of p: $C_{\pm}(p) = (\partial J_{\pm}(p)) \cap \partial M$. These singularities are generally known as bulk-point singularities and have been considered in several contexts prior to that of cuts [39, 40]. In particular, [40] provided an example showing that such singularities are not expected to arise without sending N to infinity. This is consistent with the fact that there should not be

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any notion of a local bulk scattering point when N is finite. Similarly, our consideration of superficially local operators and their equivalence classes is certainly only expected to reproduce local bulk physics in the large N limit. At finite N there are no local (gauge-invariant) observables in the quantum gravity [41, 42], so it is not clear why one would even seek to study any notion of exactly local bulk operators in this case. It is, of course, interesting to contemplate whether or not either of these approaches suggests new ways to think about approximate locality at finite but large N.

- Specification of a state: Cut reconstruction, in its original form, presupposes that we are given a particular quantum state ψ in the CFT Hilbert space and that we are told that ψ is dual to some *unknown* bulk geometry.¹¹ The task is then to study correlation functions in that state (which can be done using the boundary theory only) to determine aspects of the bulk interpretation of ψ (like the bulk geometry). Similarly, throughout this paper we have assumed that we are given a code subspace G and that we are told that G has the bulk interpretation of being the Hilbert space of a quantum field theory on some unknown spacetime background. We then consider various operators acting on G and ask which of them are superficially local (which can be done using the boundary theory only).
- Identification of points with a boundary object: The next step in cut reconstruction is to make an identification between the set of light-cone cuts and the set of points in the causal wedge of the boundary. On the other hand, here we identify points in Loc(M) with equivalence classes of superficially local operators.
- Reconstruction of the Conformal Metric: It is possible to assign a causal structure to the set of cuts. This causal structure is consistent with the causal structure in the set of bulk points corresponding to the cuts (with some caveats that can be addressed). As a result, the set of cuts provides a reconstruction of the metric in the causal wedge of the boundary, $CW(\partial M)$, up to a conformal factor. Similarly, we are able to identify a causal structure on \tilde{M} , the set of classes of superficially local operators, and we therefore obtain a reconstruction of the conformal class of the metric in the bulk region Loc(M). It is known that in some cases, Loc(M) extends further into the bulk than $CW(\partial M)$ does: in the case of a dynamical black hole, Loc(M) can intersect the

black hole interior. We do not know whether or not it is always the case that $CW(\partial M) \subseteq Loc(M)$.

• Local operators and the connection between the two *methods*: The premise of our approach was to solve a different problem from bulk reconstruction. Superficial locality provides a way to identify the operators on a code subspace G that are dual to local bulk operators. Identification of bulk local operators has not yet been a goal of light-cone cut reconstruction, but it is a promising direction. In fact, such considerations suggest a way to directly relate cut reconstruction to our program. Consider a point $P \in M$ and also consider a light-cone cut C_{\pm} associated with singularities in correlation functions computed in a state $\psi \in G$. We would like to know how to tell if the bulk point associated with P is the same as the bulk point associated with C_{\pm} (clearly this is only plausible for bulk points in the intersection of $CW(\partial M)$ and Loc(M).

We suggest the following approach to this problem. Consider a superficially local operator $\phi \in P$ and take a collection of boundary points x_1, \ldots, x_n close to points in C. Now, consider two different correlation functions:

$$F_n(x_1, \dots, x_n) = \langle \psi | O(x_1) \dots O(x_n) | \psi \rangle$$

$$G_n(x_1, \dots, x_n) = \langle \psi | \phi O(x_1) \dots O(x_n) | \psi \rangle.$$

If ϕ is indeed a local operator at the vertex of the cut C, then a signature of that property will be encoded in the relationships between F_n and G_m for various values of n and m. We do not pursue this idea further in the present work.

V. DISCUSSION

Relying only on subregion duality between the boundary and bulk spacetimes, our construction addresses the following question. Given a CFT and a code subspace dual to an unknown geometry, can we tell if some operator is dual to a bulk local operator? To answer this question, we exploit the curious feature that numerous distinct boundary regions can reconstruct a local bulk operator. Once we identify the set of local bulk operators in the localizable region, the relations among those operators reveal bulk causal structure.

Furthermore, because the program focuses on entanglement wedges, as opposed to the extremal surfaces themselves, the operators we identify can lie behind horizons and within entanglement shadows in many examples. As expected, however, there are still regions for which our procedure fails to completely describe locality (these regions are often behind horizons). If we assume bulk locality still holds even within these regions, its encoding in the CFT is different than that of operators in the localizable region.

¹¹ In [38], the theory of cuts was put into a framework that did not strictly rely on the presumption of the existence of a bulk, but where an extra dimension can be seen to emerge in appropriate cases.

Subregion duality is a common property of holography. The holographic entanglement entropy prescription [22, 23] and the fact that entanglement wedge reconstruction is possible [9], lead us to the conclusion that quantum error correction is a feature of any theory with a holographic description. This is an extra constraint on holographic CFTs, which must encode information in a way consistent with bulk reconstruction, and can be seen as a requirement of CFTs having a bulk dual.

Remaining Considerations

Finite N: While we have addressed how locality, for the portion of the bulk in the localizable region, emerges from quantum error correction, there are still gaps that need to be understood. To what extent does locality fail at finite N? Gravitational effects prohibit the existence of local bulk observables. However, the quantum error correcting properties of subregion duality hold beyond leading order and it may therefore be elucidating to consider an approximate form of our approach at finite N. This may shed light on the subtleties of the large N limit and the relationship between exact quantum gravity and the infinite N theory.

The conformal factor: While there is no obvious way to reconstruct the conformal factor on M, we can argue that more information than just the causal structure is available to us. Consider a point $P \in M$ with the special property that for some boundary region $R \in \mathcal{R}$, both R and its complement \overline{R} lie in $\mathcal{Q}(P)$. The only geometrical interpretation of this scenario is that operators in Pcorrespond to a point on the HRT surface ext R. This means that in addition to the conformal metric on M we also know the minimal area anchored extremal surfaces as well as the (regulated) areas of those surfaces, determined by the von Neumann entropies of corresponding boundary regions [22, 23, 43, 44]. Noting that stationary surfaces and their areas are not invariant under conformal transformations, the conformal factor on the metric is significantly constrained. We leave further investigation in this direction to future work.

Note: during the final stages of this project, [45] appeared on the arXiv which discusses related ideas.

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Appendix A: The large N limit

In discussing the main concepts in the text, we have assumed that local bulk operators exist, hoping to present our construction in an intuitive fashion. However, exact bulk locality only exists when $N = \infty$, and gravitational effects are turned off. When N is large but finite, gravitational effects demands that any gauge invariant bulk operator will be nonlocal in some way [41, 42]. Nevertheless, bulk effective field theory still makes sense within the code subspace of holographic CFTs. This is possible because nonlocal effects become small, since they come with some positive power of the gravitational coupling. The suppression in N allows us to discuss local bulk fields (perhaps smeared over a region $\sim l_p$) and perturbatively add nonlocal effects (by appropriately dressing the fields for example), so long as we work in the appropriate code subspace.

Here, we explain how the constructions in the main text can be made precise by appropriately applying the large N limit to decouple nonlocalities due to gravity. Consider a CFT satisfying the appropriate requirements for having a bulk dual (see e.g. [46]). The theory has some parameter, $\epsilon(N)$, which corresponds to the gravitational coupling in the bulk and taking $\epsilon \to 0$ means turning off gravitational effects (i.e. sending $N \to \infty$). Different values of ϵ correspond to different boundary theories (with different central charges) with an associated Hilbert space H_{ϵ} .

For $\epsilon \neq 0$, no gauge-invariant operator ϕ_{ϵ} , restricted to the appropriate code subspace G_{ϵ} , will be local in the bulk. However, as we decrease ϵ , the strength of nonlocal gravitational effects decreases, and some operators and some operators in the CFT will start to resemble what one expects for local operators in semiclassical field theory; intuitively these would be the operators that would limit to local fields in the $\epsilon = 0$ limit. For example, if we think about semiclassical fields that are gravitationally dressed, the gravitational coupling suppresses the nonlocal dressing.

Consider now a family of operators, $\{\phi_{\epsilon}\}_{\epsilon>0}$, with ϕ_{ϵ} acting on the code subspace G_{ϵ} for all $\epsilon > 0$.¹²

Definition. Let $R \in \mathcal{R}$ be a boundary region and let \overline{R} be a complement of R. We say that a family $\{\phi_{\epsilon}\}_{\epsilon>0}$ is reconstructable in R if for any family of operators $\{O_{\epsilon}^{\overline{R}}\}_{\epsilon>0}$ in the algebra of \overline{R} for H_{ϵ} and for any family of states $\{\psi_{\epsilon}\}_{\epsilon>0}$ with $\psi_{\epsilon} \in G_{\epsilon}$,

$$\lim_{\epsilon \to 0} \langle \psi_{\epsilon} | [\phi_{\epsilon}, O_{\epsilon}^{R}] | \psi_{\epsilon} \rangle = 0$$
 (A.1)

¹² Decreasing ϵ decreases the strength of gravitational backreaction. In order to keep any nontrivial background fixed while changing the value of ϵ , we must separate "background matter" from excitations. As we send $\epsilon \to 0$, the stress tensor for the background matter must be rescaled appropriately to maintain a nontrivial background. This emphasizes the subtlety in the definition of G_{ϵ}

As reviewed in section II, this implies that, when ϵ is very small, there is some operator O_{ϵ}^{R} in the algebra of R, whose action on G_{ϵ} is that of the operator ϕ_{ϵ} (up to corrections in ϵ).

Note that most of these families of operators will not limit to a semiclassical local bulk field. The "limit" might be a smeared operator in EW(R) or the family of operators could oscillate forever within EW(R) and never converge in any sense. However, some special class of such families do limit to local operators.

In order to test whether or not a collection of operators approaches a local field as ϵ becomes small, we introduce a generalization of the procedure in the text. The idea is to make the fundamental object of study the collection of ϵ -dependent families of operators as opposed to the set of operators on a fixed code subspace. Following the framework from section III, we introduce a map Q that acts on families of operators as follows:

$$\mathcal{Q}(\{\phi_{\epsilon}\}_{\epsilon>0}) = \{R \mid \{\phi_{\epsilon}\}_{\epsilon>0} \text{ is reconstructible in } R\}$$
(A.2)

For some of these sequences, the set $\mathcal{Q}(\{\phi_{\epsilon}\}_{\epsilon>0})$ will be the result expected for a field localized to a point in the bulk. If this is the case, we can think of $\{\phi_{\epsilon}\}_{\epsilon>0}$ as a set of operators whose bulk interpretation is a semiclassical field (built on a background associated with a code subspace) whose nonlocal gravitational effects disappears as $\epsilon \to 0$. For such sequences of operators, taking the $\epsilon \to 0$ limit is can be thought of as "undressing" ϕ by consistently tuning down gravitational effects while keeping the background fixed.

We can use this new definition of \mathcal{Q} to define equivalence classes of families of operators and then the notion of superficial locality¹³ exactly as we do in section III. All of the developments in the main text can be done in this formalism.

Appendix B: Topology of \tilde{M}

In this appendix we explain how a topology on \hat{M} can be constructed using only the boundary theory. We make no assumptions here about whether or not clumps are present. Despite appearances, the purpose of this construction is not so much to demonstrate mathematical rigor as it is to provide motivation for the statement that \hat{M} , an object defined in the boundary theory, can be regarded (in the absence of clumps) as a "copy" of Loc(M), a region of spacetime that certainly has a nice topological structure.

The boundary theory is taken to be on a flat space which, after conformal compactification, is a cylinder. (The case where there are multiple disconnected boundaries is a straightforward generalization of the construction below.) A spatial region $R \in \mathcal{R}$ is thus bounded so its boundary, ∂R , is compact. Choose some global coordinate system on this flat spacetime (that is, fix a conformal frame), and define a Euclidean metric d between two points via geodesic (Euclidean) distance. We can now give a metric on \mathcal{R} denoted by D, by defining D(R, R')as the Hausdorff distance between ∂R and $\partial R'$.¹⁴ This definition of distance is problematic in the case where $\partial R = \emptyset$. However, if $\partial R_1, \partial R_2 = \emptyset$ and $\partial R_3 \neq \emptyset$, we simply define $D(R_1, R_2) = 0$ and $D(R_1, R_3) = \infty$.

Given $\epsilon > 0$, let $B_{\epsilon}(R)$ be the subset of \mathcal{R} consisting of regions R' with $D(R, R') < \epsilon$. A topology on \tilde{M} can now be obtained by taking $P \in \tilde{M}$ and defining $U_{\epsilon}(P)$ as the set of points $P' \in \tilde{M}$ such that for every $R \in \mathcal{Q}(P)$, there exists $R' \in \mathcal{Q}(P') \cap B_{\epsilon}(R)$. The collection of sets $\{U_{\epsilon}(P) \mid \epsilon > 0, P \in \tilde{M}\}$ forms a topological base from which a topology can be defined.

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¹³ Note that the definition of superficial locality works very nicely with our new definition of Q. If it happened, for example, that $\{\phi_{\epsilon}\}_{\epsilon>0}$ were a family of operators that oscillates from place to place as $\epsilon \to 0$, then we can be sure that this family would not be superficially local unless it were to oscillate within a clump.

¹⁴ Given a metric space (S, d), the Hausdorff distance is a metriclike function that can be defined in terms of d to measure the distance between two subsets of S in a reasonable fashion. The Hausdorff distance is a legitimate metric on the collection of nonempty compact subsets of S so our definition of D provides a metric on the subset of \mathcal{R} where $\partial R \neq \emptyset$ because ∂R is always compact.

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