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Theory of spin-coherent electrical transport through a defect spin state in a metal/insulator/ferromagnet tunnel junction undergoing ferromagnetic resonance

N. J. Harmon* and M. E. Flatté†

Department of Physics and Astronomy and Optical Science and Technology Center, University of Iowa, Iowa City, Iowa 52242, USA

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We describe the coherent dynamics of electrical transport through a localized spin-dependent state, such as is associated with a defect spin, at the interface of a ferromagnet and a non-magnetic material during ferromagnetic resonance. As the ferromagnet’s magnetic moment precesses, charge carriers are dynamically spin-filtered by the localized state, leading to a dynamic spin accumulation on the defect. Local effective magnetic fields modify the precession of a spin on the defect, which also modifies the time-integrated total charge current through the defect. We thus identify a new form of current-detected spin resonance that reveals the local magnetic environment of a carrier spin located at a defect, and thus potentially the defect’s identity.

The emerging field of “quantum spintronics” seeks to engineer and manipulate single coherent spin systems for the sake of quantum-enhanced sensing/imaging technologies and quantum computing.¹ Defect spins in an insulating region between a ferromagnetic metal and a nonmagnetic conductor produce an array of coherent spin-dependent phenomena, including defect-associated spin pumping,²–⁴ thermal spin transport,⁵ and small-field magnetoresistance under electrical bias.⁶–⁸ Individual spin-coherent defects have even been electrically detected in precisely-designed junctions.⁹,¹⁰ Charge and spin dynamics have also been studied in systems consisting of a quantum dot connected to ferromagnetic leads.¹¹–¹³ However, the potential of a coherently-precessing source of spins, readily available from a ferromagnetic contact undergoing precession (such as from a spin torque oscillator) has not yet been explored; such a coherent source may be able to reach a single-defect-spin regime of spin pumping or dynamic spin polarization.

Here we predict observable coherent dynamics in the charge and spin transport through a single defect in the junction between a ferromagnetic material and a second, nonmagnetic (NM) conducting material, when the magnetism of the ferromagnet (FM) precesses in time such as during ferromagnetic resonance (FMR). During electrical transport the defect can become dynamically spin polarized, and its spin manipulated, even with negligible coupling between the defect and FM from a magnetic dipolar field or exchange interaction. This provides a single-defect-spin example of dynamic spin polarization. Analysis of the current through the device reveals the local spin character of a defect and its environment without the need of a microwave cavity. These effects, in the single-defect limit, would be detectable with a spin-polarized scanning tunneling microscope tip undergoing FMR, and should persist even for sequential hopping transport between the tip and the defect, as well as between the defect and the second conducting contact. A slower transport rate between the defect and the FM provides better resolution of the defect’s local environment, so long as the defect spin state’s coherence time is comparable to or exceeds the electrical transport rate through the junction.

Here we focus on a defect electronic structure corresponding to a single orbital state and two (oppositely-oriented) spin states, either unoccupied or singly occupied by a spin-1/2 electron. The junction is shown schematically in Fig. 1. Transport occurs as an electron spin, of arbitrary direction, hops from the left contact to the previously empty defect site and singly occupies the level. The electron’s subsequent motion will then be limited depending on the orientation of its spin relative to the majority spin polarization at the Fermi level in the FM; if parallel then the transport is rapid, while if antiparallel the transport is slower. Similar behavior will occur.

FIG. 1. (a) Diagram of the energy landscape of a ferromagnet/nonmagnetic (FM/NM) metal junction. The darker box specifies the NM metal and the middle planes represent the two energy levels of the defect which are separated by an on-site Coulomb energy U. The bias pushes electrons through the junction from the NM metal (left) to the FM (right). The vertical direction is energy whereas the lateral directions are spatial coordinates. (b) Schematic of the spatial orientation of various spins: the FM’s polarization, P F(t) (green arrow) precesses around an axis ω F M (black arrow). The spin of the defect s(t) (blue arrow) precesses in the sum of an externally applied and a local magnetic field, at a frequency ω d = ω + ω F M. In this panel ω F M = 0. The dynamical spin polarization of the defect follows the FM’s polarization. (c) For ω F M ≠ 0 the defect spin precesses around the static (ω F M = 0) steady state spin orientation (indicated by the orange line).
for hole spin transport, with opposite bias voltage and when
the hole hops to a defect site that is empty (of holes, and thus
doubly-occupied by electrons), or for defects with different
electronic state ordering, so long as the transport through
the defect states depends on spin. For example, a ground-state
spin-1 defect, such as a silicon carbide divacancy,\textsuperscript{14} will ex-
hibit essentially the same features as our spin-1/2 system, but
with opposite dynamic spin polarization. We focus on the case
shown in Fig. 1.

A heuristic picture helps visualize the resonance condition
for transport through the defect state during precession of the
FM’s spin polarization. The spin polarization of the FM’s
Fermi-level carriers, $P_R(t)$ (green arrow), precesses around an
axis $\omega_{FM}$ (black arrow), depicted parallel to $\hat{z}$ in Fig. 1. The
cone angle is the angle between $P_R(t)$ and $\omega_{FM}$. The equi-
librium polarization of the FM when not undergoing FMR is
$P_R||\hat{z}$. The probability for a carrier to enter the FM depends
on the relative orientation of the carrier’s spin, $s(t)$ (blue arrow), and $P_R(t)$. For the simplest picture consider
the FM to be 100% spin polarized, for which only a carrier
with some spin component parallel to $P_R(t)$ may tunnel into
the FM. For the case of a small FM, the FM remains as a single
domain when undergoing FMR.

The spin on the defect site, associated with the carrier, can
also precess due to the influence of an applied magnetic field
as well as a local effective field arising from hyperfine inter-
actions, exchange interactions with neighboring sites, or other
effects. The directions of precession vectors will be described
using a polar angle $\theta$ relative to $\omega_{FM}||\hat{z}$ and an azimuthal an-
gle $\phi$ relative to the $\hat{x}$ axis, with a subscript corresponding
to the specific precession vector. The local field is considered
to be independent of the applied magnetic field, and causes the
defect spin to precess according to the precession vector $\omega_d$.
The applied magnetic field precesses the defect spin accord-
ing to the precession vector $\omega_d$, and the total precession will be
$\omega_d = \omega_0 + \omega_d$. To distinguish this precession frequency
from apparent precession due to spin filtering, the precession
frequency $\omega_d$ will be referred to as the defect spin’s Larmor
frequency.

Dynamic spin polarization emerges on the defect site, and is
largest when $\omega_d = 0$, shown in Fig. 1(b). Under bias the
defect occupation is continually replenished, until the carrier
spin on the defect is oriented antiparallel to $P_R$ and no further
transport occurs until the carrier spin decoheres or the FM
polarization changes. This spin filtering process results in the
defect spin tracking approximately antiparallel to $P_R(t)$, there-
fore blocking the current through the junction. Figure 2 illus-
trates the details of the spin-coherent effects on charge current
during FMR, beginning with an unoccupied defect spin state.
Figure 2(a) demonstrates (orange line) that $s(t) \cdot P_R(t) \to -1$
after transient dynamics.

Figure 1(c) shows the changing dynamics for a non-
vanishing Larmor precession of the carrier spin on the defect,
and for $\omega_d$ perpendicular to $\omega_{FM}$. For $\omega_{FM} = 0$ the defect
spin precession causes the dynamic spin polarization gener-
ated from spin filtering in transport into the FM to rotate in the $yz$
plane and be oriented along the orange line, which is
determined by the relative precession frequency and spin fil-
tering rate to be

$$s(t) = -\frac{2\gamma_L|\hat{r}_L P_R + \gamma_R \omega_d \times P_R + (\omega_d \cdot P_R) \omega_d|}{(\gamma_R(1 - P_R^2)(\omega_d) + 2\gamma_L)(\gamma_R^2 + \omega_d^2)},$$

with

$$\chi(\omega_d) = \frac{\gamma_R^2 + (\omega_d \cdot \hat{r}_R)^2}{\gamma_r^2 + \omega_d^2},$$

where $\gamma_L$ is the hopping rate from the left conductor to the
defect and $\gamma_R$ the hopping rate from the defect to the FM.

For $\omega_{FM} \neq 0$ the dynamical defect spin polarization $s(t)$
precesses at the frequency $\omega_{FM}$ around the orange line, as
indicated in Fig. 1(c). Figure 2 displays the current for this
configuration off resonance [Fig. 2(b)] and on resonance
[Fig. 2(c)]. When off resonance some beating occurs in the
transient stage until the defect spin $s(t)$ is synchronized with
$P_R(t)$.\textsuperscript{15} On resonance, corresponding to $\omega_{FM} = |\omega_0 + \omega_p| = \omega_0$, the amplitudes of the defect spin’s precession and the cur-
rent oscillations increase.
The off-resonant power spectrum (red) of the current oscillations, Fig. 3(a), shows peaks at both the FMR frequency (ω_{FM}) and the defect spin’s precession frequency (ω_d); the peak at ω_d is a transient, as shown with integration times of 5, 10, 20 × 10^{-3} s, and in the inset. When on resonance (black), ω_{FM} = ω_d, s(t) and P_R(t) are synchronized and s(t) increases, producing larger amplitude current oscillations. Figure 3(b) shows the dependence of the current’s power spectrum at the FMR frequency, P_{ω_d}, on ω_d for several different orientations θ_d.

We now describe how the charge current through the junction during FMR is calculated including the spin-coherent dynamics of the defect. The current operators involving the two contacts, from the NM contact to the defect (‘left’ current), and from the defect to the FM (‘right’ current), are explicitly constructed and combined with a coherent density matrix treatment of the carrier spin dynamics. The following ansatz describes the ‘right’ current operator

\[ \dot{I}_R(t) = \frac{e}{2} \hbar \mathcal{R} \hat{P}_R(t) \hat{\rho}(t) + \hat{\rho}(t) \hat{P}_R(t) \],

where \( \hat{P}_R(t) \) is the polarization operator of the FM and \( \hat{\rho}(t) \) the density matrix of the defect’s carrier spin. The second term of Eq. (3) ensures hermiticity. \( \hat{P}_R(t) = \frac{1}{2} (I + \hat{P}_R(t) \cdot \hat{\sigma}) \) describes an imperfect spin filter (\( \hat{P}_R(t) \) is not idempotent unless \( P_R = 1 \)). \[ \mathcal{R} \] is determined by Tr(\( \hat{P}_R \)), precesses around \( \omega_{FM} \) and is determined by

\[ \dot{\hat{P}}_R(t) = -\frac{i}{\hbar} [\hat{\rho}_{FM} \cdot \sigma, \hat{P}_R(t)]. \]

An analytic solution for \( \hat{P}_R(t) \) is available using an algebraic solver. The explicit form of the matrix \( \hat{P}_R(t) \) is found in Appendix A. To account for the finite line width of the FMR, the power spectrum is convolved with a Lorentzian function of width Γ. A description of the convolution is found in Appendix B.

\[ \mathcal{R} \] represents the movement of charge combined with spin information encoded in the matrix elements. Charge (spin) current is \( i_R = \text{Tr} \hat{P}_R (\hat{I}_L, \hat{R} = \text{Tr} \hat{I}_L \hat{\sigma}) \). The right charge current once the defect site is filled is

\[ i = \text{Tr}(\hat{I}_R) = \frac{1}{2} (1 + s(t) \cdot \hat{P}_R(t)) e^\gamma_R, \quad \text{with } s = \text{Tr}(\hat{\rho} \hat{\sigma}), \]

which illustrates the dependence of the current on the relative alignment of the defect spin and FM’s polarization. For \( \gamma_R \gg \gamma_L \) the defect state is predominately filled. For a spin-polarized contact that is an STM tip, the tip can be moved away from the impurity until \( \gamma_L \gg \gamma_R \). The amplitude of current oscillations, for small cone angles and \( \gamma_L \gg \gamma_R \), scales as \( P_{L}^{2} \).

The ‘left’ current (NM contact to defect) can be derived in a similar fashion after constraining the defect to be at most singly occupied. For a left conductor with a static magnetization,

\[ \hat{I}_L(t) = e' \gamma_L [1 - \text{Tr}(\hat{P}(t))] \hat{P}_L, \]

where \( \hat{P}_L = \frac{1}{2} (I + \hat{P}_L \cdot \sigma) \) is the polarization operator of the left conductor. This formalism can be generalized to include dynamic magnetization of the left conductor, although here we present results only for a NM, i.e. \( P_L = 0 \). Charge conservation demands that the ‘left’ current be the same as the ‘right’ current for a time-independent \( \hat{P}_R(t) \) or when the current is averaged over a precession period of \( \hat{P}_R(t) \), so \( \text{Tr}_d \hat{P}_L = \text{Tr}_d \hat{P}_R \).

Construction of the defect density matrix \( \hat{\rho}(t) \) consistently connects the currents and determines their sensitivity to spin and applied magnetic fields. The stochastic Liouville equation is suited well for this type of problem, so

\[ \dot{\hat{\rho}}(t) = -\frac{i}{\hbar} [\hat{\mathcal{H}}, \hat{\rho}(t)] - \gamma_L \{ \hat{P}_R(t), \hat{\rho}(t) \} + 2 \gamma_L [1 - \text{Tr}(\hat{P}(t))]. \]

The first term of Eq. (7) produces the coherent evolution of the spin, the second term (curly braces are anti-commutators) the spin-selective nature of tunneling into the FM. The last term describes hopping onto the defect site from the left contact. \( \hat{\mathcal{H}} = (\hbar/2) \omega_d \cdot \hat{\sigma} \) is the spin Hamiltonian at the defect site. In typical insulators the localization length of the defect’s wave function is wide enough to encompass a large number of randomly oriented nuclei, so a local hyperfine field \( \omega_d \) can be
accurately approximated as a classical vector. The spin density matrix is obtained from a numerical solution to Eq. (7), and the current from either Eq. (3) or Eq. (6).

Although the resonances always occur when \( \omega_{FM} = \omega_0 \), independent of precession axis direction, it is possible to determine \( \omega_0 \) by measuring \( \omega_0 \) at resonance, for several different directions of \( \omega_0 \), as \( \omega_0 \) at resonance will vary with direction from \( \omega_{FM} - \omega_0 \) to \( \omega_{FM} + \omega_0 \). In Fig. 4(a) the current’s power spectrum at the FMR frequency, \( P_{\omega_{FM}} \), is shown as a function of \( \omega_0 \) for three different directions of \( \omega_0 \), for an example hyperfine local field \( \omega_0 = (-0.3, 0.1, 0.2)\omega_{FM} \). This theory applies also to two independent defects through which parallel currents run. Fig. 4(b) displays sweeps of \( \omega_0 \) at \( \theta_0 = \pi/2 \) and three different \( \phi_0 \), similar to the single defect scenario. Now resonances occur at two different applied fields for each sweep. Further description of the resonant detection is located in Appendix C. These resonant features are not contingent on \( \theta_0 = \pi/2 \) but remain for \( \theta_0 < \pi/2 \).

![FIG. 4. (a) Plots showing the integrated current at \( \omega_{FM} \) when the applied field, \( \omega_0 \), is swept. Resonances occur when \( \omega_0 = |\omega_0 + \omega_d| = \omega_{FM} \). Here \( \omega_0 = (-0.3, 0.1, 0.2)\omega_{FM} \). (b) Two resonance features appear when two defects are probed. Each colored curve corresponds to an independent sweep of the magnetic field in the \( x-y \) plane at an angle \( \phi_0 \). For the two defects, \( \omega_{1,2} = (-0.3, 0.1, 0.2)\omega_{FM} \) and \( \omega_{1,2} = (0.4, 0.1, -0.1)\omega_{FM} \). Curves in (a) and (b) are normalized to the highest peak and labeled by the applied field’s azimuthal angle \( \phi_0 \). Parameters are identical to those used in Fig. 3.

\( \omega_{FM} \) is fixed in Figs. 3(b) and 4 as \( \omega_0 \) varies. For a ferromagnetic thin film with the easy axis of the contact in the film plane, the component of the applied magnetic field along the hard axis, if sufficiently small, does not influence \( \omega_{FM} \) but does change \( \omega_0 \) and \( \omega_d \). We assume the magnetic field component along the hard axis is varied in order to vary \( \omega_d \) leaving \( \omega_{FM} \) fixed.

The relevant timescale for differential precession of the carrier spin and the FM is the timescale for hopping from the defect to the FM. For typical scanning tunneling microscopy measurements with currents of 0.1 – 30 nA, the timescale for hopping from a defect to a ferromagnetic tip would be 0.05–1.6 ns. For spins on the defect coherent on this timescale, which is known to be the case for many examples of localized spins, the features described here will emerge. By comparing this hopping time to the precession time of the carrier spin on the defect in a local magnetic field, the sensitivity to local fields can be estimated to be of the order of \( \sim 10 \) mT, characteristic of hyperfine fields for many types of defects. Local fields in the range of 1-100 mT correspond to FMR frequencies \( \omega_{FM} = 0.1 – 10 \) GHz which is not an uncommon range for a wide range of materials. Smaller currents will improve sensitivity to \( \omega_0 \).

Spin-coherent evolution of a carrier spin at a defect produces resonant features in the charge conductivity of a ferromagnet/insulator/nonmagnet junction. From this, small numbers of defects, or a single defect, can be identified by matches between the ferromagnetic resonance frequency of a contact and the local precession of the spin(s) of the defect(s). The approaches described here would also permit the preparation of specific desired defect spin states through appropriate choices for the ferromagnet’s precession frequency, leading to controlled studies of the coupled dynamics of two coherent spins. We have purposely chosen small currents in our model to mimic tunneling between the defect and a spin-polarized scanning tunneling microscope. An interesting extension would be to investigate larger currents where spin-torque effects between the defect spin and FM become important.

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Appendix A: Ferromagnet Polarization Dynamics

The matrix describing the evolution of the ferromagnet’s polarization is \( \dot{\hat{P}}_R(t) \) which can be determined by solving Eq. (4) of the main text which we rewrite here:

\[
\dot{\hat{P}}_R(t) = -\frac{i}{\hbar} \hat{H}_0 \hat{P}_R(t) \cdot \hat{\sigma}. \quad (A1)
\]

In general \( \hat{P}_R \) has spherical angle coordinates \( (\alpha, \beta) \) and \( \hat{H}_0 \) is initially pointed in the direction \( (\alpha_0, \beta_0) \). The full solution is too large to express here but can be determined with a computer solver such as Mathematica.

The form reduces considerably for certain values of the angles. For \( \alpha = \beta = \beta_0 = 0 \) (which we assume throughout the main text), the cone angle between \( \hat{P}_R(t) \) and \( \hat{P}_{FM} \) is \( \alpha_0 \), and

\[
\dot{\hat{P}}_R(t, \alpha \to 0, \beta \to 0, \beta_0 \to 0) = \frac{1}{2} \left( \frac{1 + P_{RF}^2}{P_{RF}^2} \right) \hat{P}_{RF} \\left( \frac{1}{1 - P_{RF}^2} \right) \quad (A2)
\]

where \( v = 2 \cos(\alpha_0) \) and \( u = \sin \alpha_0 \cos \omega_{FM} t - i \sin \omega_{FM} t \).
The polarization vector is found through the standard relation $P_i = \text{Tr} \sigma_i T_R(t)$:

$$P_R = P_R \left( \sin \alpha_0 \cos(\omega_{FM} t) \right) \sin \alpha_0 \sin(\omega_{FM} t) \cos \omega_0 ,$$

Appendix B: Power spectrum convolution

Equation (1) here gives a single ferromagnetic resonance (FMR) frequency whereas the FMR spectrum has a line width in actuality. The line width of the resonant peak in the power spectrum (Fig. 3 (a) in main text) is governed by the FMR line width, $\Gamma$. To account for the finite FMR line width we convolve the pure power spectrum with a Lorentzian line shape. If $p^*$ is the raw power spectrum, then

$$p(\omega) = \int_{-\infty}^{\infty} p^*(y) \frac{\Gamma^2}{\Gamma^2 + (y - \omega)^2} dy \quad (B1)$$

is the power spectrum displayed in Fig. 3 (a) of the main text. $\Gamma = 0.005 \Gamma_{FM}$ is taken as the FMR line width. The power at the frequency $\omega_{FM}$ is $P_{0FM} = p(\omega_{FM})$.

Appendix C: Determining Local Field using the Resonance Condition

As $\omega_0$ is swept, resonances may occur in the range $\omega_{FM} - \omega_0$ to $\omega_{FM} + \omega_0$. These bounds are found by solving for $\omega_0$


\begin{equation}
\omega_{FM}^2 = \omega_0^2 + 2 \omega_0 \omega_i + \omega_i^2 \quad \text{(C1)}
\end{equation}

The three ‘measurements’ of Figure 4(a) yield three different resonance conditions which can be used to ascertain the magnitude of each local field component via the resonance condition

For two or more defects the process is identical to that of a single defect once each peak is assigned to a specific defect. The defect assignment is possible since the peak for a particular defect once each peak is assigned to a specific defect. The sign of $\omega_{F,2}$ is ambiguous, but a fourth measurement with the applied field slightly cantled out of the $x-\gamma$ plane can resolve the sign. To do so may force $\omega_{FM}$ to change linearly with $\omega_0$ in which case the resonance conditions would change. However we do not expect the magnitude of $\omega_{FM}$ to vary strongly with $\omega_0$ if the angle of inclination is small so, for simplicity, we assume $\omega_{FM}$ to be constant in this case as well.

\begin{itemize}
    \item * nicholas-harmon@uiowa.edu
    \item † michael_flatte@mailaps.org
    \item 13 C. A. Merchant and N. Markovic, “Current and shot noise mea-


15 A brief animation of the magnetization and defect spin dynamics is found in the online Supplementary Information.
