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Interaction of gapless spin waves and a domain wall in an easy-cone ferromagnet

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We theoretically study the interaction of spin waves and a domain wall in a quasi-one-dimensional easy-cone ferromagnet. The gapless spin waves on top of a domain wall are found to exhibit finite reflection in contrast to the well-known perfect transmission of gapful spin waves in easy-axis magnets. Based on the obtained scattering properties, we study the thermal-magnon-driven dynamics of a domain wall subjected to a thermal bias within the Landauer-Büttiker formalism, where transmitted magnons are shown to exert the magnonic torque on the domain wall and thereby drive it with the velocity linear to the applied thermal bias. The peculiar gapless nature of spin waves in easy-cone magnets enables the thermally-driven domain-wall motion even at low temperatures, differing from the easy-axis case where the domain-wall velocity is exponentially suppressed at low temperatures. Our work suggests that easy-cone magnets can serve as a useful platform to study the interaction of gapless spin waves and nonlinear excitations and thereby realize low-temperature magnon-related phenomena.

I. INTRODUCTION

Magnetic systems can hold a variety of topological defects, such as domain walls (DWs), vortices and skyrmions, and their dynamics have been studied for decades both for fundamental and practical interest [1]. In particular, magnetic DWs have drawn great attention due to their practical applications exemplified by domain-wall race track memory [2]. The mechanism of driving a DW has been studied extensively in several easy-axis magnets with various driving means, such as an external magnetic field [3, 4], and an electric current [5–11]. In addition to these means, spin waves also have been shown to be able to drive a DW [12–15]. Magnons, quanta of spin waves, carry spin \hbar in the opposite direction to the background spin, which enables them to push a DW by flipping their spin while moving across a DW and thereby transfer spin angular momentum to the DW according to the conservation of the total angular momentum. For easy-axis ferromagnets and antiferromagnets, it is well known that spin waves show perfect transmission through a DW [16–19]. Magnons in the easy-axis magnets have a finite gap to be excited and therefore the effects of thermal magnons on transport properties are exponentially suppressed at sufficiently low temperatures compared to the magnon gap.

Easy-cone magnets are another class of magnets having uniaxial anisotropy, in which ground-state manifolds form a couple of cones about the high-symmetry axis [20–23] [See Fig. 1(a)]. The ground states spontaneously break both the Z_2 and $U(1)$ symmetries by choosing, respectively, which of the cones to reside in and which direction within the cone is pointed at. The spontaneous breaking of these symmetries endows easy-cone magnets with the peculiar ability to support DWs [Fig. 1(c)] and gapless spin-wave excitations [Fig. 1(c)] in one system [24], which is absent in easy-axis magnets. In particular, the latter gapless property of spin waves in these magnets is expected to enable us to drive a DW with spin waves of lower energy compared to the case of a gapful

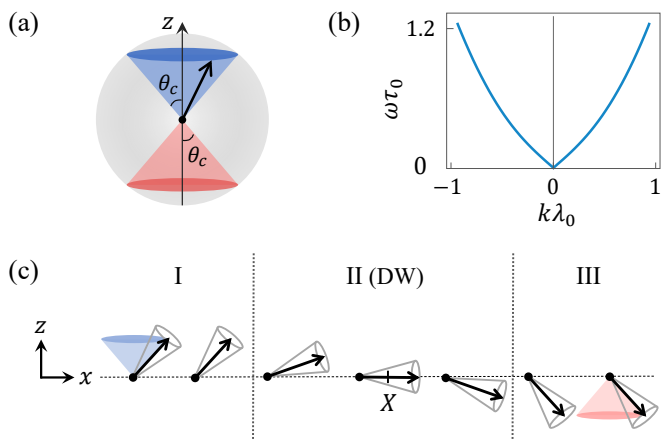


FIG. 1. (a) Ground-state manifolds of an easy-cone magnet in the unit sphere. The manifolds form a pair of cones about the z -axis with angle θ_c (upper blue) and $\pi - \theta_c$ (lower red). The black arrow on the blue cone represents one possible ground-state magnetization. (b) The gapless dispersion relation $\omega(k)$ of spin waves in a ground state of an easy-cone magnet. Both axes are in natural units of length and time, λ_0 and τ_0 . See the main text for their definitions. (c) Schematic illustration of a one-dimensional easy-cone magnet with a domain wall (DW). Region I(III) is in the ground state with uniform magnetization within the blue(red) cone. These regions are interpolated by the region II, where the DW is located (centered at X). The black arrows represent the magnetizations in a static DW profile, while the gray cones around them represent time-evolving magnetizations of spin waves.

easy-axis magnet.

Recent technology to fabricate easy-cone magnets has advanced significantly, increasing the feasibility of easy-cone magnets for experimental studies and technological applications. The example materials include Co/Pt, Ta/Co₆₀Fe₂₀B₂₀/MgO, (Cr_{0.9}B_{0.1})Te, and NdCo₅ [25–31]. However, despite the aforementioned unique features of easy-cone systems compared to easy-axis systems, the spin-wave properties, the dynamics of solitons such as a DW, and their interactions in easy-cone magnets have

been studied little.

In this paper, we study the interaction of spin waves and a DW in an easy-cone ferromagnet within the Landau-Lifshitz framework. In Sec. II, we begin by giving a brief review of the easy-cone system and the DW solution therein. In Sec. III, we develop a theory for spin waves on top of a DW and compute the reflection and the transmission probability of the spin waves interacting with the DW. Using the scattering property obtained, in Sec. IV, we study the magnon-driven DW motion subjected to a thermal bias and obtain the DW velocity as a function of the temperatures involved, within the Landauer-Büttiker formalism. In particular, we show that the gapless nature of spin waves in easy-cone magnets gives rise to the finite DW velocity even at low temperatures, in contrast to the easy-axis case where the analogous DW velocity is exponentially suppressed as the temperature decreases due to the finite spin-wave gap.

II. EASY-CONE SYSTEMS

In this section, we describe easy-cone magnets, their symmetry properties, and ground states. We also present an exact solution for a domain wall.

A. Easy-cone magnets

We consider a quasi-one-dimensional ferromagnet along the x -axis with the potential energy given by

$$U[\mathbf{m}(x)] = \int \left[\frac{A}{2} (\partial_x \mathbf{m})^2 - \frac{K}{2} m_z^2 + \frac{K'}{2} m_z^4 \right] dx, \quad (1)$$

where $A > 0$ is the exchange coefficient, $K > 0$ is the effective first-order uniaxial anisotropy, and $K' > 0$ is the second-order uniaxial anisotropy [20–23]. Here, $K = K_u - \mu_0 M_s^2/2$ includes both the magnetocrystalline anisotropy $\propto K_u$ and the dipolar-induced shape anisotropy $\propto M_s^2$ (by assuming that the magnet has a sufficiently narrow cross-section so that the system can be considered quasi-one-dimensional [32]). Note that the first-order anisotropy favors the magnetization along the z -axis, while the second-order anisotropy tends to tilt the magnetization away from the z -axis. To parametrize the competition of these two effects, we define a dimensionless number $\kappa = K'/K$. The condition for the system to be an easy-cone magnet is given by $\kappa > 1/2$ [21], which will be assumed throughout the paper. The potential energy possesses two distinct symmetries. Firstly, it is invariant under time-reversal $\mathbf{m} \mapsto -\mathbf{m}$, showing the Z_2 symmetry of the system. Secondly, it is invariant under global rotations of the magnetization $\mathbf{m}(x) \mapsto \hat{R}_z(\varphi)\mathbf{m}(x)$, where $\hat{R}_z(\varphi)$ is a three-dimensional rotation matrix about the z -axis with angle φ , showing the U(1) spin-rotational symmetry of the system.

Given the potential energy, the couple of cones of the ground-state manifold [Fig. 1(a)] are determined as fol-

lows. Their angle about the high-symmetry axis (z -axis) are $\theta_c = \arccos \sqrt{(2\kappa)^{-1}} (< \pi/2)$ for the upper blue cone and $\pi - \theta_c$ for the lower red cone, respectively. Note that the angles are determined by κ , the relative strength of the first- and the second-order anisotropies, as expected. A ground state is a uniform array of the magnetization \mathbf{m} which belongs to one of the given manifolds. It is well described by the spherical coordinates θ and ϕ where $\mathbf{m} = (\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta)$, and is given by

$$\theta(x) = \theta_c \quad \text{or} \quad \pi - \theta_c, \quad (2)$$

$$\phi(x) = \Phi, \quad (3)$$

in which each coordinate breaks one of two symmetries: θ breaks Z_2 symmetry and ϕ breaks U(1) spin-rotational symmetry.

For the following discussions, it is convenient to use the following natural units of length, time and energy:

$$\lambda_0 = \sqrt{A/K}, \quad \tau_0 = s/K, \quad \epsilon_0 = \sqrt{AK}, \quad (4)$$

where s is the spin density.

B. Domain walls

The easy-cone system supports another stable state referred to as a DW, which connects two uniform ground states in different manifolds while minimizing the potential energy. That is, a DW is a stationary solution satisfying $\delta U/\delta \theta_0 = 0$ and $\delta U/\delta \phi_0 = 0$, with boundary conditions $\theta_0(x \rightarrow \mp\infty) = \theta_c$ and $\theta_0(x \rightarrow \pm\infty) = \pi - \theta_c$. The exact solution is available [33, 34] which is given by

$$\theta_0(x) - \frac{\pi}{2} = \pm \arctan \left[\frac{1}{\sqrt{2\kappa-1}} \tanh \left(\frac{x-X}{\lambda_d} \right) \right], \quad (5)$$

$$\phi_0(x) = \Phi, \quad (6)$$

where $\lambda_d = \lambda_0 \cdot \sqrt{\frac{4\kappa}{2\kappa-1}}$ is the DW width. See Fig. 1(c) for the schematic illustration of the DW described by the Eq. (5) with plus sign and Eq. (6) with $\Phi = 0$. Here, the polar angle changes from θ_c to $\pi - \theta_c$ as x varies from $-\infty$ to ∞ while the azimuthal angle is uniform. In Eq. (5), X represents the DW center at which the polar angle is $\pi/2$. Due to the translational invariance of our system, X is arbitrary and thus represents the zero-energy mode associated with spontaneous breaking of the translational invariance by the DW. In this paper, we are interested in spin waves on top of this DW, which we turn to below.

III. INTERACTION OF SPIN WAVES WITH A DOMAIN WALL

In this section, we study spin-wave dynamics on top of a DW. In particular, we confirm the gapless dispersion and show that the incident spin wave is partially reflected from the DW regardless of its frequency, which is in contrast to the well-known perfect transmission in easy-axis magnets [16–19].

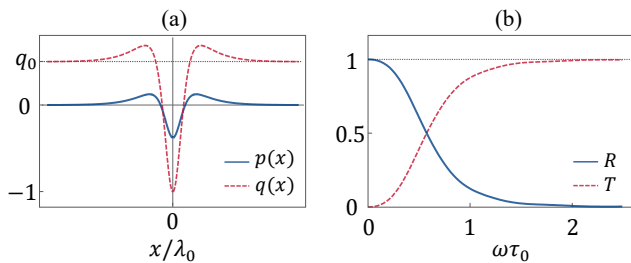


FIG. 2. (a) The plots of $p(x)$ (blue solid) and $q(x)$ (red dashed line) in the spin-wave equation (10) with $q_0 = 1$. Both are even functions and converge to constant values far away from the DW. The middle region where $p(x)$ and $q(x)$ vary corresponds to the DW. (b) The probability of reflection R (blue solid) and transmission T (red dashed) of a spin wave scattering with a DW, as a function of frequency $\omega\tau_0$. Their sum $R+T$ shown as the dotted black line is confirmed to be unity. Both (a) and (b) are for $\theta_c = \pi/4$.

A. Spin waves

In order to consider a spin wave on top of a DW, we divide the magnetization $\mathbf{m}(x, t)$ into the static DW profile $\mathbf{m}_0(x; X, \Phi)$ and a small perturbation $\delta\mathbf{m}$. In the local frame, the small perturbation can be written as

$$\delta\mathbf{m}(x, t) \approx \hat{\theta} \delta_1(x, t) + \hat{\phi} \delta_2(x, t), \quad (7)$$

where $\hat{\theta} = \partial\mathbf{m}_0/\partial\theta$, $\hat{\phi} = (1/\sin\theta_0)(\partial\mathbf{m}_0/\partial\phi)$, and \mathbf{m}_0 form the local orthonormal frame.

By linearizing the Landau-Lifshitz equation [35] about the DW solution while neglecting the damping

$$\frac{\partial\mathbf{m}}{\partial t} = -\frac{\delta U}{\delta\mathbf{m}} \times \mathbf{m}, \quad (8)$$

in the local coordinate system, we have a set of first-order equations in the small field $\delta\mathbf{m}$ given by

$$-\dot{\delta}_1(x, t) = -\delta_2'' + p(x)\delta_2, \quad (9a)$$

$$\dot{\delta}_2(x, t) = -\delta_1'' + q(x)\delta_1, \quad (9b)$$

with

$$p(x) = 2\cos^2\theta_0(x) - 3\kappa\cos^4\theta_0(x) - 1/(4\kappa), \quad (10a)$$

$$q(x) = [2\cos^2\theta_0(x) - 1] + 2\kappa[3\cos^2\theta_0(x) - 4\cos^4\theta_0(x)]. \quad (10b)$$

See Fig. 2(a) for the exemplary plots of $p(x)$ and $q(x)$ for $\theta_c = \pi/4$. Note that $p(x)$ approaches zero as $x \rightarrow \pm\infty$, which stems from the spontaneous breaking of the U(1) spin-rotational symmetry in ground states and is associated with the gapless nature of spin waves therein [36]. However, $q(x)$ approaches a finite value $q_0 = 2 - 1/\kappa$ as $x \rightarrow \pm\infty$, representing the finite energy cost for the magnetization to be tilted away from the easy-cone manifolds. Far away from the DW where $p(x)$ and $q(x)$ are uniform, the spin-wave equation has plane-wave solutions

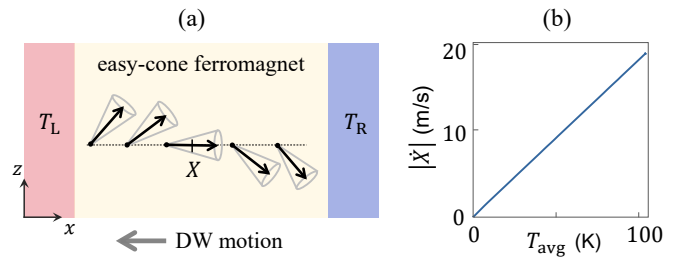


FIG. 3. (a) A schematic illustration of a setup for a thermally driven DW. An easy-cone ferromagnet with a DW is placed between two thermal reservoirs that maintain constant temperatures T_L and $T_R (< T_L)$, respectively. Each reservoir injects thermal magnons into the magnet, which exert a torque on the DW and thereby push it to the region with higher temperature. (b) DW speed in the setup (a) in the presence of damping $\alpha = 0.1$

, as a function of $T_{\text{avg}} = (T_L + T_R)/2$. The temperature difference $\Delta T = T_L - T_R$ is set to $0.1T_{\text{avg}}$. For the used material parameters, see the main text.

$\delta_n(x, t) = A_n \exp(ikx - i\omega t)$ with the dispersion relation given by

$$\omega(k) = \sqrt{k^2(k^2 + q_0)}. \quad (11)$$

See Fig. 1(b) for the plot and note that the gap is zero.

One may notice that taking the limit of κ to 0 does not bring Eqs. (10) to the Pöschl-Teller potential, and Eq. (11) to the gapful dispersion. See Appendix B for the appropriate treatment of general easy-axis magnets having finite second-order anisotropy.

B. Reflection and transmission probability

The incident spin wave is found to be partially reflected from the DW. The probability of reflection and transmission were obtained by numerically solving Eqs. (9) within the Green's function formalism detailed in the Appendix A. See Fig. 2(b) for the plots of the probabilities for $\theta_c = \pi/4$, which represents one of our main results. Note the finite reflection probability at the whole energy ranges, which is in contrast to the reflectionless spin waves in the easy-axis counterpart. The transmission probability increases as the spin-wave energy increases, since the effect of the energy barrier on its transmission becomes weaker at high energies.

When a spin wave is quantized, a quasiparticle referred to as a magnon emerges. The reflection probability and the transmission probability of magnons are the same as the ones for the spin waves, which we will invoke below when discussing the thermal-magnon-driven DW motion.

IV. DOMAIN-WALL MOTION DRIVEN BY THERMAL MAGNONS

In this section, we study the DW motion driven by the scattering of thermal magnons. See Fig. 3(a) for the schematic illustration of a system. An easy-cone magnet with a single DW is placed between the left and the right thermal reservoirs that maintain finite temperatures T_L and T_R , respectively. We employ the Landauer-Büttiker formalism by assuming ballistic magnon transport to obtain the DW motion [37–39], as done in Refs. [40, 41]. In Eq. (18), we present the DW velocity as a function of the average temperature $T_{\text{avg}} = (T_L + T_R)/2$, which is another main result of ours.

A. Magnonic force and torque

Thermally populated magnons move between the two thermal reservoirs. When traveling magnons are transmitted through a DW, they exert a torque on it by changing their spin. The torque by the right-moving magnons, which come out of the left reservoir, is given by

$$\tau_L = \int d\epsilon \, 2\hbar \cos \theta_c \cdot T(\epsilon) \cdot n_B \left(\frac{\epsilon}{k_B T_L} \right) \frac{1}{2\pi\hbar}, \quad (12)$$

with polarization along the z -direction, where n_B is Bose-Einstein distribution function and k_B is Boltzmann constant. Here, the factor $2\hbar \cos \theta_c = \hbar \cos \theta(x \rightarrow -\infty) - \hbar \cos \theta(x \rightarrow \infty)$ represents the angular-momentum transfer from a single magnon to the DW, $T(\epsilon)$ is the transmission probability of magnons with energy ϵ , and the last factor $1/(2\pi\hbar)$ comes from the product of a density of states per unit length and the group velocity $d\omega/dk$ [40]. Similarly, the torque τ_R exerted on the DW by the magnons moving from the right reservoir to the left reservoir can be obtained. The net torque $\tau = \tau_L + \tau_R$ can be approximated by

$$\tau \approx \frac{\cos \theta_c}{\pi} \Delta T \int d\epsilon \, T(\epsilon) \cdot \left. \frac{\partial n_B}{\partial T} \right|_{T_{\text{avg}}}, \quad (13)$$

for $\Delta T \ll T_{\text{avg}}$, where $\Delta T = T_L - T_R$ is the temperature difference between the two reservoirs.

A reflected magnon, however, exerts a force on the DW. By the derivation analogous to the above torque case, the net force exerted on the DW by magnons coming out of the two reservoirs can be approximated by

$$F \approx \Delta T \int d\epsilon \, \frac{k}{\pi} \cdot R(\epsilon) \cdot \left. \frac{\partial n_B}{\partial T} \right|_{T_{\text{avg}}}, \quad (14)$$

where k/π is a product of $2\hbar k$ —the linear-momentum transfer by a single magnon— and $1/(2\pi\hbar)$ —the product of a density of states per unit length and the group velocity. Here, $R(\epsilon)$ is the reflection probability of magnons with energy ϵ by the scattering with the DW. Again, the approximation is valid for $\Delta T \ll T_{\text{avg}}$.

B. DW motion

The torque and the force on the DW by the scattering with thermal magnons give rise to the DW motion as follows. The equations of motion for the DW parameters, the position X and the angle Φ , are given by (in natural units defined in Eq. (4))

$$\begin{pmatrix} g & \alpha\eta_\Phi \\ \alpha\eta_X & -g \end{pmatrix} \begin{pmatrix} \dot{X} \\ \dot{\Phi} \end{pmatrix} = \begin{pmatrix} \tau \\ F \end{pmatrix}, \quad (15)$$

where $g = -2 \cos \theta_c$ is the gyrotropic coupling constant between \dot{X} and $\dot{\Phi}$ [42], α is the Gilbert damping constant, η_X and η_Φ are the parameters that represent energy dissipations associated with the translational and rotational motion, respectively, which are given by

$$\eta_X = \frac{1}{\sqrt{4\kappa}} [(\kappa - 1)(\pi - 2\theta_c) - \sqrt{2\kappa - 1}], \quad (16)$$

$$\eta_\Phi = \frac{2\kappa - 1}{2\kappa} \cdot L - \frac{1}{\sqrt{\kappa}} (\pi - 2\theta_c), \quad (17)$$

with L , the length of a magnet. Here in Eq. (15), the left-hand sides in the absence of the damping are the time derivatives of the spin angular momentum and the conserved linear momentum of a DW, respectively, which are derived through the Noether's theorem [41, 43]. The former $g\dot{X}$ can be easily understood by considering the dependence of the total spin on the DW position, which determines the lengths of the spin-up and spin-down regions: $S_{\text{tot}}^z \propto \pm X$ (Minus sign for increasing $S^z(x)$, which is the case of Fig.3(a)). For the torque and the force given in Eq. (13) and (14), the DW velocity is given by

$$\dot{X} = \frac{1}{g^2 + \alpha^2 \eta_X \eta_\Phi} (g\tau + \alpha\eta_\Phi F) \quad (18)$$

in natural unit [Eq. (4)]. We numerically obtained the velocity by using the material parameters of NdCo₅ given by lattice constant $a = 0.5$ nm, saturation magnetization $M_s = 1.1 \times 10^6$ A/m, $A = 1.1 \times 10^{-11}$ J/m, $K = 2.4 \times 10^6$ J/m³, $K' = 1.6 \times 10^6$ J/m³, and thereby $\kappa = 0.67$ [28–31]. Here in τ and F , the probabilities $T(\epsilon)$ and $R(\epsilon)$ can be affected by the presence of magnon damping in accordance with the fluctuation-dissipation theorem [44]. However, in this work, our main focus is to provide a simple phenomenological theory for the interaction of a magnon current and a DW and thus we considered the effect of spin dissipation only on the dynamics of the DW, not on the magnon scattering with a DW by assuming that the damping is sufficiently small that magnons do not decay significantly until they finish their interaction with a DW [40, 45]. We remark here that, if a qualitatively accurate prediction is needed for the DW velocity, one has to account for the effect of the finite magnon damping on the DW dynamics in the theory in order to be consistent with the fluctuation-dissipation theorem. Figure 3(b) shows the velocity of the thermally driven

DWs in NdCo_5 of length $L = 10\lambda_d$ in the presence of magnetic damping $\alpha = 0.1$, as a function of T_{avg} with $\Delta T = 0.1T_{\text{avg}}$. Note that there is no exponential suppression of the DW velocity as the average temperature decreases, which can be attributed to the gapless nature of spin waves in easy-cone magnets.

V. SUMMARY AND DISCUSSION

We have studied how spin waves and a DW interact in a one-dimensional easy-cone ferromagnet within the Landau-Lifshitz phenomenology [35]. Specifically, we have studied the scattering properties of spin waves with a DW and obtained the reflection and the transmission probability as a function of the wave frequency. Based on this, we have further investigated the magnon-current-driven dynamics of a DW under a thermal bias within the Landauer-Büttiker formalism [37–39]. The DW velocity is shown to be linear to the applied thermal bias and to increase as an average temperature rises. In particular, the gapless feature of magnons is shown to enable the thermal DW motion at low temperatures without exponential suppression. In Sec. IV, we only considered spin-transfer torque induced by thermal magnons. In general discussion on thermally-driven DW motion, however, one should take into account an entropic torque as well [46–48], which reveals the effect of thermal excitation that leads to the increase of spin disorder in a DW. We assumed the thermal gradient in our system is present only at the interfaces with thermal reservoirs and magnets and absent inside the magnet so that the free energy of the DW remains the same within the magnet regardless to its position, and thus neglected an entropic torque.

In the future, it might be worth investigating a two-dimensional easy-cone magnet that harbors a one-dimensional DW with chiral spin rotation along with it. Here, one can expect magnon deflection by the emergent magnetic field, which is formed exclusively at the DW [49–52]. The analogous research has been conducted for easy-axis ferromagnets with gapful magnons in Ref. [53]. Compared to the ferromagnetic case, we expect that the easy-cone counterpart would allow us to study the interaction of gapless magnons and a DW with chiral spin rotation.

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Appendix A: Scattering of spin waves with a domain wall

We present a numerical method to compute the scattering parameters of spin waves. To compute them, it is important to include evanescent waves ($\sim e^{\pm kx}$) in addition to a plane-wave solution [54]. Here \tilde{k} is an imaginary wave number with dispersion relation $\omega(\tilde{k}) = \sqrt{\tilde{k}^2(\tilde{k}^2 - q_0)}$. We set an ansatz

$$\begin{aligned} \Psi_i &= \begin{pmatrix} e^{ikx_i} + r e^{-ikx_i} \\ r' e^{\tilde{k}x_i} \end{pmatrix}, \text{ for } i = 0, -1, -2, \dots, \\ \Psi_i &= \begin{pmatrix} t e^{ikx_i} \\ t' e^{-\tilde{k}(x_i - x_N)} \end{pmatrix}, \text{ for } i = N + 1, N + 2, \dots, \end{aligned} \quad (\text{A1})$$

outside the DW, which lies in the $i = 1, 2, \dots, N$ th sites. Here e^{ikx} represents an incoming spin wave, r (r') and t (t') is the reflection and transmission coefficient, respectively for the travelling (evanescent) mode.

The recurrence relation of the spinors, Ψ_i is in the form of

$$\omega \Psi_i = -[t] \Psi_{i-1} + [s_i] \Psi_i - [t] \Psi_{i+1}. \quad (\text{A3})$$

Here the $[t]$ and $[s_i]$ are 2×2 matrices, which can be specified from the spin-wave equation (9).

Note that the relations for the spinors at the DW boundaries—i.e., the ones for $(-1, 0, 1)$ -th or $(N, N + 1, N + 2)$ -th spinors—will give equations for r, r', t, t' , once we know Ψ_1 and Ψ_N that are inside the DW. To this end, let us define the propagator $[G]$, which is the $N \times N$ matrix whose elements are 2×2 matrices :

$$[G]_{ij} = \begin{cases} [t] & , j = i \pm 1 \\ [\omega I - s_i] & , j = i \\ [0] & , \text{otherwise} \end{cases}, \quad (\text{A4})$$

where $[I]$ is the 2×2 identity matrix. The whole spinors inside the DW including Ψ_1 and Ψ_N are determined :

$$\begin{pmatrix} \Psi_1 \\ \Psi_2 \\ \vdots \\ \Psi_{N-1} \\ \Psi_N \end{pmatrix} = [G] \begin{pmatrix} -[t] \Psi_0 \\ 0 \\ \vdots \\ 0 \\ -[t] \Psi_{N+1} \end{pmatrix}. \quad (\text{A5})$$

Therefore, Eq.(A3) of $i = 0$ and $N + 1$ reduce to a set of four linear equations for r, t, r', t' :

$$-[t] \Psi_{-1} + [-\omega I + s_0 + t G_{11} t] \Psi_0 + [t G_{1N} t] \Psi_{N+1} = \mathbf{0}, \quad (\text{A6})$$

$$[t G_{N1} t] \Psi_0 + [-\omega I + s_{N+1} + t G_{NN} t] \Psi_{N+1} - [t] \Psi_{N+2} = \mathbf{0}, \quad (\text{A7})$$

from which we obtain the probability of reflection, $|r|^2$, and of transmission, $|t|^2$.

Appendix B: Spin-wave equations in general easy-axis magnets

We present the alternative forms of the potentials $p(x)$ and $q(x)$ [Eqs. (10)], the dispersion relation [Eq. (11)], and a static DW solution [Eq. (5)] for a general easy-axis system that has a finite second order anisotropy K' . For $K > 0$ and $\kappa = \frac{K'}{K} \in (-\infty, \infty)$, a system is an easy axis if $\kappa \leq 1/2$ and an easy cone if $\kappa > 1/2$.

The potentials for spin waves on top of a DW $\theta_0(x)$ are given by

$$p(x) = \begin{cases} 2 \cos^2 \theta_0(x) - 3\kappa \cos^4 \theta_0(x) - (1 - \kappa) & , \kappa \leq 1/2 \\ 2 \cos^2 \theta_0(x) - 3\kappa \cos^4 \theta_0(x) - 1/(4\kappa) & , \kappa > 1/2 \end{cases}, \quad (\text{B1})$$

$$q(x) = [2 \cos^2 \theta_0(x) - 1] + 2\kappa [3 \cos^2 \theta_0(x) - 4 \cos^4 \theta_0(x)], \quad (\text{B2})$$

where the domain wall solution $\theta_0(x)$ is implicitly given

by

$$\cos^2 \theta_0(x) = \begin{cases} \frac{(1-\kappa) \tanh^2(\sqrt{1-2\kappa} x)}{(1-2\kappa) + \kappa \tanh^2(\sqrt{1-2\kappa} x)} & , \kappa \leq 1/2 \\ \frac{\tanh^2(\sqrt{2\kappa-1} x / \sqrt{4\kappa})}{(2\kappa-1) + \tanh^2(\sqrt{2\kappa-1} x / \sqrt{4\kappa})} & , \kappa > 1/2 \end{cases}. \quad (\text{B3})$$

One can retrieve the well-known Walker solution and the Pöschl-Teller potential for the special case of $\kappa = 0$, where the second-order anisotropy vanishes:

$$\cos^2 \theta_0(x) = \tanh^2 x, \quad (\text{B4})$$

$$p(x) = q(x) = 1 - 2 \operatorname{sech}^2 x. \quad (\text{B5})$$

Dispersion relation is given by

$$\omega(k) = \sqrt{(k^2 + p_0)(k^2 + q_0)}, \quad (\text{B6})$$

where p_0 and q_0 are the limits of $p(x)$ and $q(x)$ at infinity, respectively:

$$\begin{cases} p_0 = q_0 = 1 - 2\kappa & , \kappa \leq 1/2 \\ p_0 = 0, q_0 = 2 - \kappa^{-1} & , \kappa > 1/2 \end{cases}, \quad (\text{B7})$$

from which the gapful nature of easy-axis case is recovered. The equality of the limits in the easy-axis case comes from ambiguity in choosing axes $\hat{\theta}$ and $\hat{\phi}$. (Both are ill-defined so one can take $\hat{\theta} \equiv \hat{x}$, $\hat{\phi} \equiv \hat{y}$.) The $\kappa > 1/2$ case can be understood from the footnote [36].

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- $$\mathcal{U}_{\text{gnd}+\text{sw}}^{\text{ani}} = \mathcal{U}_{\text{gnd}}^{\text{ani}} + \frac{q_0}{2} \langle \delta_1^2(x, t) \rangle_t + \frac{p_0}{2} \langle \delta_2^2(x, t) \rangle_t,$$
- where the anisotropy energy densities of a ground state with and without spin waves are respectively given by $\mathcal{U}_{\text{gnd}}^{\text{ani}}$ and $\mathcal{U}_{\text{gnd}+\text{sw}}^{\text{ani}}$. The time-averaged δ_2 term is an energy cost due to the deviation in the $\hat{\phi}$ -direction, which should be zero because a magnetization stays in the ground-state manifold. Second, the p_0 and q_0 also appear in the spin-wave dispersion relation:
- $$\omega(k) = \sqrt{(k^2 + p_0)(k^2 + q_0)},$$
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