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Altering the Stability of Surface Plastic Flow via Mechanochemical Effects

Anirudh Udupa\textsuperscript{a,*}, Tatsuya Sugihara\textsuperscript{b,*}, Koushik Viswanathan\textsuperscript{a}, Srinivasan Chandrasekar\textsuperscript{a}

\textsuperscript{a}Center for Materials Processing and Tribology, Purdue University, West Lafayette, IN 47907-2023, USA
\textsuperscript{b}Department of Mechanical Engineering, Osaka University, Suita, Osaka 565-0871, Japan

Abstract

We demonstrate a link between surface plastic flow and ambient chemical environment—a mechanochemical effect—in large-strain deformation of metals, using high-speed \textit{in situ} observations. This link, different from known mechanochemical effects, is studied using aluminum and an alcohol environment. Three distinct flow modes—sinuous, laminar and segmented—occur, depending on the alcohol action on the metal surface. Two transitions, one from sinuous to laminar and the other from sinuous to segmented flow are demonstrated. In both cases, the final flow modes are characterized by smaller deformation forces (order of magnitude) as well as much improved quality of the final surface. The action of the chemical medium itself is coupled to the flow mode, distinguishing it from other mechanochemical effects previously reported. The effect appears to be replicable to different degrees in other metal systems such as copper, iron, stainless steels and nickel. Based on the observations, a schematic stability phase diagram for plastic flow is proposed. Implications of the results for enhancing performance of cutting and surface deformation processes for soft and highly strain-hardening metals are discussed.

Keywords: metals; large-strain deformation; mechanochemical effect; flow stability;

*Corresponding author: audupa@purdue.edu
\*AU and TS made equal contributions to this manuscript
1. Introduction

It has long been appreciated that the nature of mesoscale plastic flow in metals is determined by considerations of stability [1–4]. The prime and most often cited example in this regard is, perhaps, the change from uniform homogeneous plastic flow to localized deformation in the form of shear bands [1, 5]. This example of a homogeneous to non-homogeneous flow transition occurs in an array of material systems, from rocks on the geological-scale [6] to structural metals on the mesoscale [5, 7, 8] and to glasses on the nanoscale [9]. However, the fact that other such transitions may also exist, particularly in large strain deformation, resulting in flows hitherto poorly understood, is only now beginning to be appreciated [10–12]. It is quite natural to expect that these transitions can also be explained in terms of changes in stability, thereby predicting characteristics of the resulting flow.

The nature of plastic flow is particularly important in large-strain deformation processes at or near free surfaces, i.e., unconstrained deformation. The proximity of the free surface to the deformation zone provides an additional degree of freedom for flow evolution, thereby being potentially conducive to spawning a rich variety of non-homogeneous flows. A common feature of these deformation processes is use of intense shear to effect changes in shape, microstructure and surface properties. Such processes are ubiquitous in materials processing and manufacturing, encompassing, to name a few, cutting, abrasion, and sliding [13, 14].

A related, but well known fact, is that surface plastic deformation is intimately linked to the environment to which the free surface is exposed to during deformation, as well as presence of thin surface layers (e.g., oxide films) [15]. For instance, exposing the surface of certain, otherwise highly ductile, metals to suitable chemical media is known to cause severe embrittlement, e.g., stress-corrosion cracking and hydrogen/liquid metal embrittlement [16–18]. These processes too are governed by stability considerations, such as the competition between continued plastic flow and fracture [19–21].

Naturally, given the important consequences of surface flow modes and the potentially central role of flow stability in determining them, it is of interest to examine the question—can we induce transitions from one flow mode to another, by utilizing a suitable chemical environment? This question is pertinent also from a practical point of view, for, driven by implications for machining, deformation processing and tribology, there is much interest in
controlling specific flow modes in surface plasticity [22, 23]. In manufacturing, the flow mode
determines process performance indices like forces, energy consumption, and surface quality.
Likewise, wear processes are closely linked with occurrence of non-homogeneous flow modes
near free surfaces [24–27].

In the course of an examination of this question, we discovered that metals can exhibit
widely different flow modes in the presence of suitable chemical media [10, 28]—a sub-class
of phenomena termed mechanochemical effects [22, 29]. Notably, a material independent
mechanochemical effect was found in cutting of ductile and highly strain hardening metals
[28]. By using a chemical medium that physically adheres to the metal’s surface, the type
of plastic flow was fundamentally altered. Based on surface energetics considerations, this
change was shown to resemble a local ductile-to-brittle transition.

The present paper describes a different, yet complementary, mechanochemical effect that
is material and chemical medium specific. We use a specially designed system—aluminum
plastically deformed to large strains in an alcohol environment—that demonstrates the intri-
cate coupling between surface plastic flow modes, both homogeneous and non-homogeneous,
and the surrounding chemical environment. The two key features of our system that helped
unearth this coupling are the ductility of Al and its chemical reactivity with alcohols. The
observations provide strong basis for the hypothesis that the plastic deformation mode oper-
ative at surfaces is determined by flow stability considerations. They also suggest possibilities
for beneficially utilizing these effects in cutting and deformation processing of metals. It is
of interest to note here that while the present study is focused on metals, mechanochemical
effects involving solid/liquid state chemical reactions have been exploited commercially in
non-metallic systems, e.g., chemomechanical polishing of Si and ceramics [30–32].

The manuscript is organized as follows. Section 2 provides background information on
surface plastic flow modes and the speciality of the aluminum-alcohol system. The details
of the experimental system are discussed in Sec. 3, followed by the results (Sec. 4). We
explain the results within the framework of flow stability and propose a phase diagram for
evaluating stability in the presence of chemical media (Sec. 5). This section also discusses
some implications for manufacturing processes with metals and related avenues for future
work. Concluding remarks are presented in Sec. 6.
2. Background

The prototypical mode of plastic flow in large strain deformation is one of steady homogeneous strain, typically with smoothly varying and time-independent strains. In addition, three other flow modes have been identified, one until recently unknown, each with their own distinct features.

2.1. Four distinct surface plastic flow modes

To best illustrate these flow modes and their features, a prototypical large-strain, simple shear deformation geometry is presented in Fig. 1, schematically depicting all four flow modes. This configuration resembles plane-strain cutting and involves imposition of simple shear on a moving workpiece using a sharp wedge-shaped tool. The shearing process removes a thin layer of material from the workpiece, the chip, see Fig. 1. The four flow modes result in distinct morphologies in the chip, a fact that has only recently begun to be appreciated.
based on combined *in situ* and *ex situ* analyses [11, 12, 33], even though chip morphologies themselves have been studied for a long time [5, 13, 34–36]. The four modes are: 1) steady homogeneous deformation, henceforth referred to as laminar flow (Fig. 1(a)); 2) shear band flow, with periodic deformation restricted to very narrow zones [1, 3, 5], as in Fig. 1(b); 3) segmented flow characterized by non-uniform deformation and periodic fracture, as in Fig. 1(c); and 4) the more recently uncovered sinuous flow, typified by surface (plastic) buckling, material folding, and highly non-homogeneous straining (Fig. 1(d)) [10, 11]. The latter three modes, being non-homogeneous and unsteady, will be referred to as non-laminar flow modes. *In situ* and *ex situ* observations [12] have established that these different flow modes result in chips with characteristic morphologies (signatures), see Fig. 1. Similar flow modes and wear particle morphologies have also been observed in sliding, another well-known, large-strain deformation process [27].

2.2. Role of stability

This rich diversity of flow modes in cutting and sliding is a direct consequence of the presence of the free surface, and is quite distinct from the more limited flow patterns typical of constrained deformation processes like bulk metal forming [37]. Which of these flow modes actually occurs in a certain situation is determined by stability criteria, including considerations of surface plastic buckling [33], crack growth from free surface flaws [15, 38] as well as the material’s inherent propensity to exhibit flow localization [3]. In manufacturing and materials processing, a large body of evidence exists to show that the flow mode and stability of flow are strongly influenced by the initial deformation state of the metal (e.g., annealed, pre-strained) and deformation geometry (e.g., die angle) [13, 37]. Furthermore, the presence of specific chemical environments is known to introduce additional constraints on flow stability, by promoting auxiliary processes such as crack nucleation and growth.

2.3. Aluminum and its reactivity with alcohols — a model system

The use of Al and alcohols as a model system for studying chemical environment effects on surface plastic flow has three primary advantages.
Firstly, commercially pure aluminum, based on the initial deformation state of its surface, is known to demonstrate at least 3 of the 4 flow modes discussed in Fig. 1. Therefore, using this metal for studying large strain deformation allows us, in principle, to probe the effect of a chemical environment on multiple flow modes within the same material system.

Secondly, fresh Al surfaces readily react with alcohols to form alkoxides, an important class of compounds characterized by aluminum-oxygen-carbon bonding. Industrially, alkoxides such as isopropoxide and sec-butoxide are important for production of ketones and aldehydes, where they are employed as reducing agents. When a fresh Al surface reacts with isopropyl alcohol, the resulting aluminum isopropoxide formed is a white solid (melting point 118°C), otherwise usually prepared by an elaborate synthesis method via formation of an amalgam.

Thirdly, alcohols and the resulting alkoxides can be effective lubricants. The lubrication is claimed to be effected by a negative-ion-radical mechanism that changes the interface conditions during sliding.

Thus the Al-alcohol system offers much scope for altering the nature of the shear deformation at surfaces (e.g., Fig. 1), both via formation of alkoxide layers to effect surface energy changes and via lubricant films to change the friction at and near the deformation zones.

3. Experimental Details

Large strain deformation is imposed using the model framework of a workpiece sliding at constant velocity $V_0$ against a rigid wedge (tool/die), see Fig. 2. As the workpiece is pushed against the wedge/tool, a thin layer of material, of initial thickness $h_0$, is continuously deformed under simple shear and removed as a ‘chip’ of thickness $h_C$, with a fresh surface created on the workpiece. The ratio $\lambda = h_C/h_0$ is typically between 2 and 20, depending on the underlying flow mode. This configuration, analogous to cutting, is well-characterized in terms of loading and chip deformation. For the experiments described in this manuscript, $V_0$ was fixed at 5 mm/s. The low speed ensures that thermal effects on the deformation are minimal: for these conditions, the temperature change was estimated to be $< 5^\circ C$. The undeformed chip thickness ($h_0$) value was set nominally at 50 µm.
in the experiments. However, due to compliances in the tool and work holding system, it was difficult to exactly achieve this set value. In practice, we used iterative adjustment of the \( h_0 \) setting to get an actual value that was close to the targeted value. The exact \( h_0 \) in the experiments was measured both from the images and by utilizing a dial indicator; these values were respectively 55 \( \mu m \), 49 \( \mu m \) and 53 \( \mu m \) for the dry cutting, IPA and alkoxide cutting experiments, respectively.

3.1. Workpiece and tool properties

The tool was made of a commercial grade WC-Co alloy, with cutting edge width of 2.3 mm (equal to chip width), edge radius of < 5 \( \mu m \), and rake angle \( \alpha = 10^\circ \) (Fig. 2). The workpiece was commercially pure Al (Al 1100, dimensions 75 mm length \( \times \) 25 mm height \( \times \) 6 mm width). The workpiece was prepared in an initially annealed state, by heating in a furnace at 550\(^\circ\)C for 4 hours and then furnace-cooling to room temperature. The reason for using aluminum in the annealed condition was because in this state it is soft and ductile, and exhibits unsteady sinuous via plastic buckling while cutting [33]. This enables examination of unsteady and, potentially, multiple flow modes within the same material system.

3.2. In-situ characterization of surface plastic flow modes

Plastic flow in the deformation zone during chip formation was recorded in situ using a high-speed CMOS camera (PCO dimax) coupled to a long working distance microscope objective, see Fig. 2 right. The deformation zone was illuminated using a 150 W halogen lamp. A glass block was clamped against the side face of the workpiece to constrain the deformation to remain plane-strain, see Fig. 2 Images were captured at 500 frames per second and spatial resolution of 1.4 \( \mu m \) per pixel. The image sequences were analyzed using a digital image correlation technique—Particle Image Velocimetry (PIV)—to obtain quantitative details of flow, such as effective (von Mises) strain and strain rate fields, and flow line patterns [10]. This data enabled detailed mapping of the underlying surface plastic flow modes.

Concurrently, forces on the tool, both parallel (cutting force \( F_c \)) and perpendicular (thrust force \( F_t \)) to \( V_0 \) were recorded using a mounted piezoelectric dynamometer (Kistler 9272, natural frequency \( \sim 2 \) kHz). The cutting force \( F_c \) is the primary contributor to the deformation.
energy/power since it is oriented parallel to $V_0$ [13]. From these components, the resultant force was obtained, as well as the force components parallel ($F_p$) and perpendicular ($F_n$) to the tool face in contact with the chip. Since the actual $h_0$ values were slightly different for each of the three experimental conditions (dry, IPA and alkoxide), the forces were normalized by dividing by $h_0$ to obtain specific force values ($\bar{F}_p = F_c/h_0, \bar{F}_t = F_t/h_0$) for each of the conditions. The specific force values and specific energy are used to characterize and analyze the energy dissipation corresponding to the three conditions (flow modes).

The topography of the cut (residual) surface in the wake of the tool was characterized using an optical profilometer (Zygo NewView 8300) to obtain surface roughness data, and details of defects such as tears and cracks.

### 3.3. Role of chemical environment

A series of cutting experiments was carried out within the framework of Fig. 2 to examine how the chemical environment in the vicinity of the workpiece and chip surface, influenced the plastic flow modes. The reactivity of a freshly generated Al surface with isopropyl alcohol (henceforth IPA), coupled with the lack of reactivity between IPA and an oxide-covered Al surface, allowed four different chemical conditions to be studied, see Fig. 3:

1. **Dry cutting, Fig. 3(a):** In the first series of experiments, the cutting was performed without use of IPA or any other fluid.

2. **IPA cutting, Fig. 3(b):** In a second series of experiments, the tool-workpiece region
was flooded with commercially available IPA. In this ambient condition the tool-chip contact interface is altered due to the formation of a layer of aluminum isopropoxide (alkoxide) on the chip under-surface, facilitated by the freshly generated oxide-free Al surface. Absent such an oxide-free surface, this reaction between aluminum and IPA needs either the presence of a catalyst or high temperatures to overcome the natural oxide layer. Figure 3(b) indicates locations where alkoxide is formed as freshly exposed aluminum comes in contact with IPA. The alkoxide layer thus formed acts as a lubricating film at the tool-chip contact (see Sec. 2).

3. Alkoxide cutting, Fig. 3(c): A third series of cutting experiments was performed by cutting without any IPA at all, but with an alkoxide film on the workpiece free surface, remote from the tool-chip contact zone. This film is formed as follows. The IPA cutting (above), besides altering the chip under-surface, leaves behind an alkoxide layer along the entire length of the residual (cut) surface, see Fig. 3(b). This is because the freshly generated and oxide-free cut surface, being highly reactive, forms an alkoxide film with continuous exposure to the IPA. Now performing a second cutting pass over this newly created surface on the same workpiece (identical $h_0, V_0$) amounts to cutting a workpiece with a thin alkoxide film on its free surface. Since the residual strain on the workpiece surface after IPA cutting was small, $< 0.4$ as estimated by PIV, the flow in the alkoxide cutting was found to be negligibly influenced by this residual strain. This was confirmed in multiple experiments. A discussion of residual strain effects on the cutting flow mode can be found in Ref. [11].

4. IPA + Alkoxide cutting, Fig. 3(d): A fourth series of cutting experiments was performed wherein an alkoxide film was present on both the initial workpiece free surface as well as the chip under surface. For this purpose, the cutting was done as in the alkoxide cutting case, but with the tool-workpiece region flooded with IPA.

4. Results

The high-speed, in situ observations have captured flow modes in three different chemical environments, that highlight the influence of chemical media on stability of surface plastic
Figure 3: Description of four different chemical ambient conditions used in cutting experiments with annealed Al. (a) Dry cutting: Cutting of annealed Al without use of any medium. (b) IPA-cutting: Annealed Al is cut in a bath of IPA. As a consequence, the chip under-surface and newly generated workpiece surface in wake of the wedge tool are both directly exposed to the IPA soon after these surfaces are created. Alkoxide layer is formed on both the chip under-surface and the residual (cut) surface in wake of the wedge. This provides a means of probing plastic flow modes and flow stability by action of IPA only along the chip under-surface. (c) Alkoxide cutting: Annealed Al, with alkoxide layer on its free surface, is cut without use of any medium. This condition provides a means of probing flow stability when only the initial workpiece surface is coated with an alkoxide layer. (d) IPA + Alkoxide cutting: Cutting with alkoxide layer formed on both the free surface as well as on the chip under-surface. This condition provides a means of probing flow stability when there is an alkoxide layer on both surfaces.
flow. The results from these direct observations were complemented/reinforced by concurrent measurements of force, energy and cut-surface quality.

4.1. Dry cutting

In the absence of any chemical (IPA), annealed Al deforms via sinuous flow under the chosen conditions; a typical chip is shown in Fig. 4. The chip is extremely thick, with the ratio $h_C/h_0 \simeq 19$; indicative of large underlying strains. Sinuous flow, a non-laminar flow mode, is characterized by large amplitude folding in the material, as revealed by the streaklines overlaid in Fig. 4(a). This type of flow is quite common in cutting of annealed and/or highly strain-hardening metals [10, 11, 33]. Figure 4(b) shows the effective (von Mises) strain in the chip, obtained from PIV. The chip strain distribution is quite non-homogeneous, reflecting the repeated folding, and alternates between high ($\approx 6$) and low ($< 3$) values. The folding also causes the free surface of the chip to have an irregular morphology with mushroom-like structures (Fig. 4). This morphology is typical of sinuous flow, as seen in other metals like Cu and Fe.

Sinuous flow is initiated by plastic buckling of a thin surface layer ahead of the tool. Details of this flow development and its microstructure origins have been discussed in prior
Figure 5: Velocity distribution in vertical direction ($V_Z$) in dry cutting. Bump formation is confirmed on the free surface by the sharp contrast between $V_Z$ in bump relative to surrounding material.

Figure 6: Development of sinuous flow in dry cutting as captured by three frames from a high-speed sequence. (a) A bump is formed due to a plastic buckling instability between pinning points $P_1$ and $P_2$, ahead of the chip. The arrows track the positions of these pinning points in the frames. (b), (c) The bump grows in size (amplitude) and evolves into a fold, resulting in the wavy streaklines.
work \cite{10, 11, 33}, and may be summarized as follows. During sinuous flow, the material demonstrates repeated large-amplitude folding. Each folding event is initiated by the formation of a protuberance or a bump on the free surface, resulting from plastic buckling. This bump formation is shown in Fig. 5 using the $z-$component of the material velocity ($V_z$), derived from PIV. $V_z$ in the chip (0.8 mm/s) is naturally greater than that in the workpiece (0 mm/s, $V_0$ horizontal). The zone where the bump forms has a pronounced $V_z$ in contrast to the surrounding material. The subsequent evolution of this bump into a fold is shown in the image sequence of Fig. 6. The initial bump is constrained between two material points (termed pinning points $P_1$ and $P_2$, see at arrows) of minimal local curvature (frame 1). As the tool advances, these pinning points approach each other (frame 2) and the bump grows, evolving into a large-amplitude fold (frame 3). This process then repeats with the folds stacking up closely on top of one another to form the thick chip ($\lambda = 19$). Each of the folds appears like a mushroom-shaped feature on the chip free surface \cite{50} and the region between adjacent folds resembles a notch \cite{28}.

4.2. IPA cutting

The large-amplitude folding and sinuous flow that accompany dry cutting result in very high cutting forces and a very thick chip. In sharp contrast, the chip formed in IPA cutting (cf. Fig. 3) was significantly thinner ($\lambda = h_C/h_0 \approx 4.8$) than with dry cutting ($\lambda = 19$). Most strikingly, as seen in Fig. 7, the flow was homogeneous and laminar, as revealed by the smooth streaklines (see Movie S1). No folding is observable on the macroscale, and the mushroom-like morphology (cf. Fig. 4) is also absent on the chip free surface. Additionally, the strain-field in IPA cutting is homogenous throughout the chip (Fig. 7(b)), with much smaller maximum strain ($\sim 3$). The strain increases in a narrow region between the workpiece and chip, indicative of intense shear within a narrow zone (‘a shear plane’), similar to the chip in Fig. 1(b). This laminar flow mode is what is usually seen in many large-strain, shear deformation conditions with moderately pre-strained metals \cite{34, 51, 52}.

This transition in the flow from sinuous to laminar, with the same material and deformation geometry, is due to the lack of any buckling on the free surface in the IPA cutting. Many alcohols, including IPA, are known to be effective lubricants for aluminum under conditions when a stable alkoxide layer is established on the Al surface \cite{44}.
Movie S1: Comparison of dry cutting and IPA cutting. Dry cutting of annealed Al (left) results in sinuous flow, thick chip and a large cutting force. IPA cutting (right), on the other hand, results in a relatively smooth laminar flow, thin chip and a much smaller cutting force.

In the present experiments, existence of the alkoxide layer, on both the free surface and chip under-surface, was detected using Fourier transform infra-red spectroscopy (FTIR). Specifically, absorbance peaks were detected in the $2840 - 3000 \text{ cm}^{-1}$ and the $1720 - 1740 \text{ cm}^{-1}$ ranges, indicating the presence of $C - H$ and $C = O$ bonds in the layer. It is expected that the thickness of the alkoxide layer so formed is $\sim 15 \text{ nm}$ [49]. In contrast, no alkoxide film was detected on the uncut workpiece free surface ahead of the tool due to the presence of the natural oxide layer on the Al. Thus, the IPA cutting condition is ideal for examining the effect of a lubricant film (here alkoxide) on the plastic flow modes.

The importance of this alkoxide layer in lowering tool-chip friction and cutting forces, thereby reducing the propensity for surface buckling and folding, is discussed in Sec. 4.5.

4.3. Alkoxide cutting

When compared to the dry cutting, the alkoxide-cutting (see Fig. 3(c)) also produced a much thinner chip ($\lambda = 6.7$, Fig. 8); this chip is only slightly thicker than in the IPA-cutting ($\lambda = 4.8$). Surprisingly, however, the flow mode by which this thin chip formed was fundamentally different from the laminar flow of IPA cutting and, of course, also from the sinuous flow of dry cutting. Figure 8(a) shows the streakline pattern and characteristic attributes of this flow mode—segmented flow—derived from the high-speed imaging, while
Figure 7: Flow pattern and deformation in IPA-cutting. (a) Image from a high-speed sequence with superimposed streaklines. The relatively smooth streaklines are indicative of laminar flow. (b) The strain distribution is now homogeneous. \( \lambda = h_C/h_0 \) is equal to 4.8, much smaller than in the sinuous flow case. \( V_0 = 5 \text{ mm/s} \) and \( h_0 = 49 \mu m \).

Figure 8: Flow pattern and deformation in alkoxide cutting. (a) Image from a high-speed sequence with superimposed streaklines showing segmented flow. The alkoxide layer on free surface of chip/workpiece changes the flow mode from sinuous to segmented. Cracks nucleate periodically on chip free surface and propagate toward the tool tip, giving rise to the segmented flow topology. (b) The (von Mises) strain is once again inhomogeneous reflecting the nature of the deformation. \( V_0 = 5 \text{ mm/s} \) and \( h_0 = 53 \mu m \).
Figure 9: Development of segmented flow in alkoxide cutting as captured by three frames from a high-speed sequence. (a) A bump is formed on the free surface as in dry cutting. $P_3$ and $P_4$ show two neighboring (pinning) points in the bump region. (b) In contrast to dry cutting, the bump does not develop into a fold. Instead, a crack nucleates between the points $P_3$ and $P_4$ shown at arrows. (c) The crack propagates towards the tool tip as indicated by the increasing distance between these points.

**Fig. 8(b)** shows the corresponding strain field. The streaklines indicate the highly unsteady nature of the deformation, but their pattern is quite different from that in the sinuous flow (cf. Fig. 6 and Movie S2). The chip strain distribution is highly non-homogeneous (Fig. 8(b)), with a strain of $\sim 2$ for the most part of the chip, interspersed with much higher strain regions (strain 7–8) of narrow width near the cracks. Segmented flow has in the past been observed in cutting of metals of limited ductility like $\beta$-brass, hard steels and highly pre-strained metals [13]. The manifestation of this flow mode in annealed Al, which is at the other extreme of the ductility spectrum, is therefore a strong indication that its surface has been ‘embrittled’ by chemical reaction with the IPA. This is most likely because of alkoxide formation on the workpiece surface facilitated by the specific conditions of the alkoxide cutting experiment (Fig. 3(c)).

The embrittling effect of the alkoxide on the free surface is evident in the periodic cracks that initiate on the free surface leading to individual segments. This process can be described using the three frames from a high-speed sequence shown in **Fig. 9**. A protuberance or bump, resembling the one initiating sinuous flow (Fig. 6), is formed, again by plastic buckling, see frame 1. Two neighboring material points in the bump region are highlighted in this frame (black and red dots). The evolution of a single segment can be inferred from the motion of these points, which eventually end up on opposite sides of a cracked surface. As the workpiece moves against the tool, the size of the bump does not increase to form a fold as in
Movie S2: Comparison of dry cutting and Alkoxide cutting. Dry cutting of annealed Al (left) results in sinuous flow, thick chip and a large cutting force. Alkoxide cutting (right), albeit still unlubricated, results in a segmentation-type ow, with cracks forming periodically and a much reduced cutting force.

sinuous flow. Instead, a crack initiates at one of the pinning points and propagates from the workpiece surface (or free surface of the incipient chip) towards the tool tip. The propagation of this crack is reflected in the increased distance between the marked points in frame 2. The crack propagates to varying distances, depending on the cutting conditions \( (h_0, \alpha, V_0) \), before it is arrested (frame 3). Subsequently, another plastic buckling event occurs leading to a protuberance and cracking at a pinning point, and the process repeats. In other words, sinuous flow is disrupted in the incipient folding stage itself by recurring crack formation leading to segmented flow.

These in situ observations of the transition from sinuous flow to segmented flow (cf. Fig. 1) show that the presence of the alkoxide on the free surface of the chip increases the propensity for a crack to nucleate and propagate. The incipient folds, caused by the surface buckling, provide precursor defects like notches, wherein the chemical action causes local crack nucleation via changes to the metal’s surface energy. Thus, it is only when the free surface of the metal is chemically altered that the sinuous flow transitions to segmented flow. This 'mechanochemical' action of the IPA via the alkoxide surface layer thus appears to be strongly coupled to the prevailing flow mode: incipient sinuous flow favors this action with segmentation ensuing, while laminar flow does not. This type of effect wherein the chemical
Figure 10: Specific force ($\bar{F} = F/h_0$) in shear deformation under various cutting conditions (dry, IPA and alkoxide). (a) Specific cutting force ($\bar{F}_c$) and (b) specific thrust force ($\bar{F}_t$). $\bar{F}_c$ and $\bar{F}_t$ in IPA-cutting are smaller by an order of magnitude compared to dry cutting, whereas the specific forces in alkoxide cutting are smaller by a factor of 6 relative to dry cutting. The specific forces in that case of IPA+Alkoxide cutting is identical with IPA cutting.

action of the medium is coupled to the flow mode is quite different from previously reported mechanochemical effects in surface plasticity [19, 20, 39].

Given that the alkoxide layer can induce two different plastic flow modes depending on which surface it is present on, a natural question is the following: what would be the flow mode when an alkoxide layer is present on both the free surface as well as on the chip under-surface? The answer to this question was obtained from the IPA+Alokixide cutting experiment (Fig. 3(d)). In this experiment, the flow was laminar and the chip strain was homogenous, with $\lambda = 4.9$. In fact, this flow was essentially indistinguishable from the flow in the IPA cutting in every respect. Hence, it is clear that whenever an alkoxide lubricant film is present at the tool-chip interface, laminar flow will always be the dominant flow mode. This is irrespective of whether an alkoxide layer is present on the chip free surface. Further implications of this result are discussed in Sec. 5.

4.4. Forces and energy consumption

Measured force components under all three chemical conditions are shown in Fig. 10. $F_c$ (Fig. 10(a)) and $F_t$ (Fig. 10(b)) represent the cutting (parallel to $V_0$) and thrust forces (normal to $V_0$) respectively, while $\bar{F}_c$ and $\bar{F}_t$ represent the forces normalized with respect to the actual undeformed chip thickness. In dry cutting, both components show a gradual increase to steady state, at which stage $\bar{F}_c \approx 12N/\mu m$. This force value is quite high even though the material being cut is soft Al (23 HV)—a consequence of the large thickness change and
deformation occurring in the workpiece material as it is converted into the chip, see Fig. 4 (λ = 19, strain 5 − 7). It is also worth noting that the friction force (component along the tool face) $F_f$ is 1.6 times $F_n$. If we define a friction coefficient ($\mu$) for the tool-chip contact as the ratio of $F_f/F_n$, then $\mu = 1.6$. In cutting of metals, this $\mu$ can assume values greater than unity \[13\]. It must be cautioned however that $\mu$ is more like a pseudo friction coefficient; for in cutting its value is influenced also by the tool rake angle, rather than being determined completely by the chip and tool materials in contact, and the lubrication condition.

In the laminar IPA cutting, both $\bar{F}_c$ and $\bar{F}_t$ were around 1.2 N/µm, an order of magnitude smaller than those of the sinuous flow mode of dry cutting (Fig. 10). Using $F_c$, the specific energy (energy per unit volume of material removed) can be calculated as,

$$U = \frac{F_c V_0}{V_0 bh_0} = \frac{F_c}{bh_0} \quad (1)$$

where $b$ is the width of cut. Since $F_c$ is a direct measure of the specific energy in cutting, the IPA cutting occurs with much smaller energy consumption ($U_{IPA} \sim 0.53$ J/mm$^3$) compared to the dry cutting case ($U_{dry} \sim 4.65$ J/mm$^3$). This is undoubtedly a consequence of the much smaller deformation imposed. Furthermore, unlike with the sinuous flow, $F_c$ and $F_t$ reached their steady values much more quickly for the laminar flow mode. The tangential force, $F_t$, along the tool face in the IPA cutting was also an order of magnitude smaller than in dry cutting case. Since this force is a measure of the frictional drag at the tool-chip contact, it shows that the IPA action at this contact has also reduced the frictional energy dissipation (secondary deformation) considerably. The change in friction can be inferred from the value of $\mu = 0.9$, significantly different from the dry cutting ($\mu = 1.6$).

The IPA+Alkoxide cutting case was indistinguishable from the IPA cutting case, not just from the flow mode but even from the specific forces. Even the value of $\mu = 0.8$ is very close to the IPA cutting case. The observations strongly suggest that the friction force reduction in IPA cutting as well as the IPA + Alkoxide cutting has stabilized the laminar flow mode vis-à-vis sinuous flow, by inhibiting the surface buckling.

In the case of alkoxide cutting, the forces and specific energy are again much smaller ($\bar{F}_c \sim 2$ N/µm, $U_{alkoxide} \sim 0.87$ J/mm$^3$) than in the sinuous flow case, an almost 80%
Figure 11: Specific cutting force in annealed Cu for dry and IPA cutting ($\alpha = 0^\circ$, $h_0 = 50 \mu m$, $V_0 = 5$ mm/sec). In contrast to the Al cutting, IPA has no effect on cutting force in the Cu. This strongly suggests that lubrication in the Al is not because of the alcohol itself but due to the formation of an alkoxide layer along the chip under-surface.

decrease, see Fig. 10. This large decrease is, at first sight, surprising since both conditions are essentially unlubricated, i.e., without any IPA access to the tool-chip interface. The unlubricated condition can be inferred from the value of $\mu = 1.5$, close to the dry-cutting case. However, the flow modes in these two cases are very different—segmented (alkoxide) versus sinuous (dry). The force reduction is due to the alkoxide layer on the initial workpiece surface triggering repeated fracture and segmented flow. The force decrease is, however, not as great as in the IPA cutting case; likewise the chip is also not as thin as in the laminar flow case, compare Figs. 7, 8. Furthermore, segmented flow cannot be inferred from the force trace alone, since this trace (Fig. 10) does not show any oscillations that might correspond to the periodic cracks in the chip.

4.5. Uniqueness of the Al-IPA system

The Al-IPA system is unique in that it can produce three of the four primary surface flow modes in the same configuration, merely by varying the chemical environment. The underlying reason for this is the reactivity of an oxide-free Al surface with alcohols as well as the lubrication properties of the resulting alkoxide layer. In order to better demonstrate the uniqueness of this configuration, two additional, secondary experiments were carried out.
4.5.1. Lubrication due to alkoxide film

To emphasize the important role of the alkoxide film in effecting lubrication of the chip-tool interface, annealed Cu was cut under identical conditions to those described in Sec. 3 for Al. It has been shown previously that the cutting characteristics of annealed Cu in dry cutting are very similar to those of Al under similar conditions: a sinuous flow mode prevails with very thick chip and large cutting force [10, 11].

Importantly, there is no report of any alkoxide-type layer occurring on freshly generated Cu surfaces. So any change in $F_c$ with Cu, if observed, can only be attributed to presence of an IPA liquid film, devoid of alkoxide, in the tool-chip contact. Figure 11 shows the variation of $F_c$ in dry and IPA cutting of annealed Cu. The force is essentially the same in both cases indicating that the lubricating effect of the IPA, sans the alkoxide layer at the tool-chip interface, is negligible. Furthermore, it unambiguously points to the alkoxide layer as the cause for the large reduction in friction observed in the aluminum IPA cutting (Sec. 4.4).

Taken together, these results establish the key role of the alkoxide in reducing the friction force (drag) at the tool-chip contact when cutting Al. Equally importantly, this drag reduction alters the flow mode in the primary deformation zone: the sinuous flow of dry cutting is replaced by a laminar flow mode in IPA cutting, with much smaller forces and energy consumption, and deformation strains. These latter attributes are also much desirable in practice.

4.5.2. Importance of the initial oxide layer

The alkoxide cutting experiments established that the deformation can be influenced not just by alkoxide being present at the tool-chip interface, as in the IPA-cutting experiments, but also when it is present at the chip free surface. This result leads to a new hypothesis about the influence of the free surface in the IPA cutting experiment. Since the experiment is conducted in a medium of IPA, it is present at both the chip free surface and tool-chip interface and possibly influences the deformation from both surfaces. In order to exclude this possibility, the following secondary experiment was performed. An annealed Al work-piece, with natural surface oxide layer present, was immersed in IPA for 10 minutes at room temperature.
temperature and then allowed to air-dry completely by evaporation. Any possible reaction with the workpiece free surface should have occurred at this time and so influence subsequent deformation. This Al workpiece was then cut in the dry condition without application of IPA. Sinuous flow with a thick chip resulted, with an $F_c \approx 450$N; indistinguishable from the previous Al dry-cutting (see Fig. 10). This shows that the initial IPA application did not result in any alkoxide formation on the workpiece. This is as expected, since the inherent oxide layer on the Al surface would prevent any chemical reaction with the alcohol. Therefore, in the case of IPA cutting, the formation of the alkoxide is solely restricted to the tool-chip interface and the new created (cut) workpiece surface; the free surface of the chip is chemically unaltered. Furthermore, the alkoxide is formed only when fresh Al is exposed to the alcohol by the cutting. This result validates the hypothesis that the results of the IPA-cutting experiment are purely due to lubrication at the tool-chip interface due to the presence of the alkoxide.

4.6. Surface quality

The three flow modes—sinuous, laminar and segmentation—observed in the dry, IPA and alkoxide cutting experiments, respectively, also showed characteristic features on the macroscale. The most notable of these signatures were the forces and energy dissipation, just discussed, and quality of the final cut surface.

The quality of the cut surface is of interest from an applications standpoint, as it determines component performance. The requirements on this surface usually include minimal density of defects such as cracks and tears, and small values of roughness. The three ambient conditions, with distinct flow modes and force levels, gave rise to surfaces with distinctly different properties.

The sinuous flow with folding, typical of dry cutting, resulted in a surface of poor quality (Fig. 12(a)). Optical profilometry of the cut surface for this flow condition revealed large tears/cracks; an example of such a tear is shown in Fig. 12(a). Each of these tears often spanned the entire width of the cut. By examining large regions of the cut surface, the tears were estimated to occur at an average frequency of 0.3/mm. This spacing is consistent with the oscillation frequency of the forces in dry cutting (see Fig. 10). The average depth of the tears (peak to valley distance) was $\sim 430 \mu$m, which is much greater than $h_0$. While
Figure 12: 3-D optical profilometer images of cut surface of Al showing topography and defect features. (a) Dry cutting—A surface defect in form of a tear is seen. (b), (c) In the case of IPA and alkoxide cutting, the quality of the cut surface is seen to be much better, with relatively smooth surface topography and absence of defects like the tears.
the mechanism of formation of these tears has not yet been resolved, it has been shown in a related sliding configuration [27] that the folds arising in sinuous flow nucleate defects by various types of fold-splitting in the wake of the tool/die. We envisage a similar mechanism herein, accentuated also by high $F_f$, in the sinuous flow mode, which inhibits easy flow of the chip against the tool face. No dead-metal or stagnation zones were observed on the tool rake face, thereby ruling them out as potential causes for the tears and cracks.

In sharp contrast to the dry cutting, both IPA cutting with laminar flow and alkoxide cutting with segmented flow resulted in much smoother cut surfaces; see Figs. 12(b),(c). Firstly, there were very few, if any, tears and cracks on the surface. Secondly, the surface roughness, $R_a$, was 1.75 µm and 1.80 µm for the IPA and alkoxide cutting, respectively. The peak-to-valley distance was measured to be 8.1 µm and 6.0 µm respectively. The improvement in the finish, when compared to the dry-cutting, is more than an order of magnitude, even simply by comparing the peak-to-valley distance. This significant improvement in quality is undoubtedly a consequence of the corresponding flow modes, with resulting (much) smaller forces (Fig. 10).

5. Discussion

The high-speed in situ measurements in large-strain deformation of Al in the presence of isopropyl alcohol (IPA) have revealed an intricate link between surface plastic flow modes and the surrounding chemical environment. Based on the conditions (dry/IPA/alkoxide cutting), three distinct flow modes were produced in the same system without changing the workpiece material or deformation geometry. Transitions between the flow modes occurred purely due to a change in the chemical environment. These flow transitions were accompanied by large scale changes in the cutting forces, energy and deformation strain, as well as quantifiable changes in the properties of the cut surface. The occurrence of different flow modes was principally determined by the specific manner in which the IPA reacted with the Al surface—formation of an alkoxide film on the tool-chip interface vis-à-vis the workpiece free surface resulted in two completely different flow modes. In this context, the present mechanochemical effect is distinct from our recent report of a material-independent mechanochemical effect in metals [28]. In the latter case, a single flow transition—from sinuous to segmented—was observed.
with a range of chemical media and with three different metal systems, the prerequisite being
strong adhesion of the chemical medium to the metal surface [28]. The present results from
the Al-IPA system highlight a mechanochemical effect that is material and chemical medium
specific. The effect demonstrates a wider range of flow transitions, therefore, enabling one to
more fundamentally probe the stability of plastic flow in large strain deformation as discussed
below.

5.1. Flow stability, plastic buckling and fracture

The role of stability in determining the deformation mode is clearly exemplified in the
case of sinuous flow. As shown in Sec. 4.1, this flow is initiated by a plastic buckling event on
the workpiece surface just ahead of the tool/chip, leading to material folding. The buckling
instability can be understood using a simplified model of a beam on a foundation representing
the undeformed chip material ahead of the tool [11, 33]. Consequently, by considering the
competition between material removal by homogeneous laminar flow and plastic deformation
via buckling, the onset of sinuous flow can be predicted as a function of $\alpha$ and initial material
pre-strain $\epsilon_{\text{pre}}$. When buckling occurs, laminar flow becomes unstable and sinuous flow
results.

Sinuous flow itself can become unstable in the presence of certain adsorptive chemicals
at the free surface of the chip. In the case of alkoxide cutting, the presence of alkoxide on
the uncut Al workpiece surface (Fig. 3) alters the flow from sinuous to segmented (Sec. 4.3).
Segmentation is characterized by periodic and repeated cracks propagating from the chip
free surface towards the tool tip (Fig. 9). Usually, segmentation is observed in metals which
are relatively less ductile, when the plastic strain at the chip free surface reaches a critical
value [38]. However, when segmentation is observed in annealed Al, it being a prototypical
example of a highly ductile metal, there is a need for an alternative explanation.

The sudden transition from ductile to brittle behavior is reminiscent of stress-corrosion
cracking and hydrogen embrittlement that is reported in structural metals, usually with
disastrous consequences ensuing [16–18]. In the alkoxide cutting, it is likely that the chemi-
cally adsorbed alkoxide layer effectively decreases the surface energy of the workpiece; such
a decrease can lead to local embrittlement of the metal, in line with theoretical predictions
[21, 53].
In addition to the surface energy reduction, the presence of notch-like features at the surface can create an environment conducive for crack propagation. Figure 6 shows how the development of the initial buckle between two pinning points in sinuous flow leads to the formation of such features. In the presence of the alkoxide layer, a notch tip corresponding to one pinning point, becomes unstable to crack growth as opposed to continued plastic deformation. Consequently, the propagation of cracks from the pinning points makes sinuous flow an unstable flow mode and leads, instead, to segmented flow, as seen in Fig. 9. This type of transition is also a signature of a material-independent mechanochemical effect, wherein surface energy reduction via physical adsorption, coupled with pre-existing notch-like features on the surface, can drive crack growth [28].

On the other hand, the IPA cutting experiment (Sec. 4.2) provides evidence for an alternate route to alter stability of sinuous flow—if the forces at the tool-chip interface are reduced by the use of a suitable lubricating film, the compressive loading imposed on the plastic zone ahead of the chip also reduces. This indeed occurs with the IPA cutting, wherein the cutting and thrust forces are both reduced by an order of magnitude (Fig. 10). As a result, the buckling threshold force is shifted (increased) so that laminar flow becomes the more stable mode. Consequently, the metal demonstrates homogeneous laminar flow (Fig. 7). Here, the alkoxide layer at the tool-chip interface plays the role of the lubricating film.

In summary, sinuous flow transitions into laminar flow when the tool-chip interface is lubricated, and to segmented flow when a suitable chemical is adsorbed on the chip free surface. Both of these flow modes are characterized by much smaller forces and energy dissipation vis-à-vis the sinuous flow. Furthermore, in the presence of both these conditions, i.e., tool-chip interface lubrication and an adsorbed layer on then free surface, the development of plastic buckling with folding is again prevented. Consequently, the notches necessary for a crack to propagate do not develop. Therefore, although the metal free surface energy might be altered due to the alkoxide, the absence of notch-like features on the surface preclude the possibility of crack propagation and segmented flow. This was confirmed experimentally by performing the alkoxide cutting in the presence of IPA, so that the alkoxide is present on both the free surface as well as the tool-chip interface. The resulting flow was laminar with no signs of any crack growth events.
5.2. *A phase diagram for stability of surface plastic flow*

The observations can now be presented in the form of a stability diagram for surface plastic flow modes, see Fig. 13(a). Here the vertical axis is the initial pre-strain ($\epsilon_{\text{pre}}$) in the workpiece and the horizontal axis is the deformation geometry (rake angle $\alpha$). This figure represents a ‘phase diagram’ in that each point in the $\epsilon_{\text{pre}} - \alpha$ plane corresponds to one particular experimental condition, i.e., specific pre-strain and geometry. In the absence of any plastic instabilities, the default flow mode, for any $\epsilon_{\text{pre}}, \alpha$ is one of homogeneous strain, i.e., laminar flow (black circle). This figure also includes negative values for $\alpha$, with very large negative values corresponding to sliding without any chip formation.

The plastic buckling instability, leading to sinuous flow, can be incorporated into this diagram by using a simple model [33]. As a result, a critical $\epsilon_{\text{pre}}(\alpha)$ relation is obtained—red dashed curve in Fig. 13(a). For $\epsilon_{\text{pre}}$ values that lie below this curve, the material buckles prior to laminar flow so that folding with sinuous flow ensues. This region of the $\epsilon_{\text{pre}} - \alpha$ diagram corresponds to situations where sinuous flow is the stable flow mode. Similarly, for $\alpha$ values above this curve, the cutting forces are sufficiently small that plastic buckling no longer occurs. In this region, laminar flow predominates, as is well known [13, 33].

On the other hand, segmented flow can be incorporated into the phase diagram by considering the threshold for crack nucleation from the chip free surface. This curve (cyan in Fig. 13(a)) has the following characteristics, as derived from prior work [38]. Crack initiation is usually favored in regions of high accumulated plastic strain. However, for large positive $\alpha$, the amount of pre-strain required for crack initiation is quite large, and under these conditions, only laminar flow occurs. For less-positive $\alpha$, the $\epsilon_{\text{pre}}$ required for crack initiation is smaller implying increased propensity for segmented flow. Consequently, the area of the phase diagram above the cyan curve corresponds to segmented flow—the experimental points (cyan circles) support this observation.

Finally, for completeness, the condition for shear band flow is also depicted (blue circle). Shear banding is a mode of flow localization, and is typical at very high $\epsilon_{\text{pre}} (> 4.5)$. The mechanics of shear band formation is, however, outside the scope of the present study and is discussed elsewhere [12, 54].

The stability phase diagram provides a basis for explaining the observed flow transitions.
Figure 13: Phase diagram showing domains of stability of different plastic flow modes. A point in this diagram corresponds to a single experiment specified by deformation geometry (rake angle $\alpha$) and initial deformation state (pre-strain, $\epsilon_{pre}$) of the workpiece surface. (a) Phase diagram for dry cutting (no chemical environment) showing points with sinuous flow (red), laminar flow (black), segmented flow (cyan) and shear banding (blue). The buckling (red) and crack initiation (cyan) curves are also shown. (b) During IPA cutting, the buckling curve shifts downward due to lubrication by the alkoxide layer. This causes a flow transition from sinuous to laminar. (c) In the case of alkoxide cutting, the crack initiation curve shifts downward, resulting in a transition from sinuous to segmented flow.
• **IPA cutting:** Under these conditions, a lubricating film is present at the tool-chip interface. This film significantly reduces the propensity for plastic buckling, resulting in a transition from sinuous to laminar flow. Consequently, in Fig. [13](#) the buckling curve is shifted downward (red dashed line), see Fig. [13](#)b. Now, points which initially resulted in sinuous flow (red circles) switch stability to laminar flow (black circles).

• **Alkoxide cutting:** In the presence of an alkoxide surface film, the workpiece surface energy is lowered. Correspondingly in Fig. [13](#)c, the crack nucleation threshold curve (cyan) is shifted downward. In this case, even though plastic buckling is more stable than laminar flow, crack nucleation at pinning points represents an alternative stable mode. As a result, cracks now grow from the pinning points towards the tool tip leading to periodic segmentation (Fig. [9](#)). Consequently, points that otherwise showed sinuous flow (red circles, part (a)) now demonstrate segmented flow (cyan circles) under identical $\epsilon_{pre} - \alpha$ conditions.

The schematic diagram qualitatively explains the observations for a given initial starting condition. The same starting conditions in Fig. [13](#)a switch stability in parts (b) and (c) due to changes in the buckling or crack initiation thresholds. However, additional experimental validation is necessary to establish the plastic buckling (red) and crack initiation (cyan) curves more quantitatively. This will involve further probing of the $\epsilon_{pre} - \alpha$ space by performing a series of experiments with varying initial conditions. Furthermore, the diagram is likely to change depending on the material chosen (Al vs. Cu, for instance) and will have to be recomputed accordingly. However, this process can be accelerated by noting that *ex situ* or macroscale observations such as forces can distinguish certain flow modes, see Fig. [10](#) precluding the need for detailed *in situ* flow mapping.

### 5.3. Implications for processing applications

Fundamentally, the results show that surface plastic flow in large-strain, shear deformation can be varied by suitable modification of the chemical environment, suggesting routes for improving performance of machining and surface deformation processes. In particular, the observations strongly suggest that the chemical ambient environment in the deformation zone can be a useful variable for process control, over and beyond the usual process variables.
such as deformation geometry and workpiece initial deformation state. From a technological standpoint, the results have two immediate implications. Firstly, the machining of many soft metals and/or highly strain-hardening metals (e.g., Al, Cu, Fe, Ni, Ta, stainless steels), notoriously referred to as being gummy and difficult to cut, could potentially be improved many-fold by use of a suitable chemical (or corrosive) effect either at the chip under-surface or at the workpiece free surface. For this purpose, the medium must be designed or tailored to effect a chemical reaction at one or more of these surfaces and interfaces. The process performance improvement is reflected in significantly reduced forces and energy dissipation (cf. Fig. 10), and improved surface quality (cf. Fig. 12). The reduced specific energy will also result in lower temperatures in the deformation zone, with additional benefits to workpiece surface quality and tool wear. Secondly, the chemical medium can be tailored to the metal, via its effect on the initial workpiece surface, as has been demonstrated in the alkoxide cutting. In many machining, surface generation and forming processes, the workpiece free surfaces are quite readily accessed by chemical media; whereas lubrication of the tool/die-workpiece contact is much more difficult due to limits imposed by the intimate and severe nature of this contact, a consequence of large contact pressures and elevated temperatures imposed by the tool. In fact, such surface phenomena are already beginning to find use for improved efficiency in material processing [55]. Thus attractive possibilities exist for a new class of mechanochemically-assisted cutting and deformation processes for metals, akin to those developed for non-metals, that exploit surface chemistry principles.

The results also have scientific implications. Firstly, the use of chemical media may provide a route for studying surface plastic flow modes and stability of this plastic flow systematically. Secondly, it points to critical areas where current modeling of large strain deformation in metal cutting and deformation processes needs improvement. One of these is the friction boundary condition at the tool-chip contact in lubricated cutting. The IPA cutting results conclusively show that this boundary condition cannot just be described via use of a Coulomb-type friction coefficient, with a smaller value than in dry cutting, as is often done. The other critical area pertains to incorporating flow stability criteria (e.g., buckling, segmentation) and microstructure in continuum models of metal cutting. For this is necessary to predict unsteady flow modes like sinuous and segmented flows, and the flow
transitions that have been demonstrated. Lastly, the mechanochemical effect highlighted herein is intriguing in that its manifestation is coupled to the occurrence of unsteady flow modes like sinuous flow in metals. We plan to elaborate on some of these topics and questions in future work.

6. Conclusions

A study has been made of the development of surface plastic flow in large-strain deformation of metals in the presence of a chemically active medium. Using high-speed, in situ imaging observations of simple shear deformation in a model system—plane-strain cutting of soft annealed aluminum in an isopropyl alcohol (IPA) environment—the occurrence of three distinct plastic flow modes is demonstrated. All of these flow modes are manifest in the same material depending on details of IPA application, under otherwise identical conditions of deformation geometry and initial workpiece state (annealed). Transitions between these modes are effected by the nature of the chemical environment—a mechanochemical effect.

In dry cutting, absent the chemical medium, the flow mode is (non-laminar) sinuous flow characterized by surface plastic buckling and large-amplitude folding. The corresponding strain field is highly non-homogeneous with large deformation strains and very high forces, even though the material being sheared is quite soft. However, when the shear deformation is imposed in the presence of the IPA, two fundamentally distinct plastic flow modes are seen—segmented flow distinguished by crack propagation from the free surface of the metal (chip free surface) and non-homogeneous straining; and laminar flow with a smooth homogeneous strain field. Both of these flow modes are characterized by small deformation (cutting) forces and specific energy—almost an order of magnitude smaller than with the sinuous flow—effected by reduced straining. The change in flow mode in the presence of the IPA is shown to result from the reaction between the IPA and freshly generated Al surfaces, the latter a product of the deformation. When the IPA application is tailored to create an alkoxide layer on the workpiece free surface ahead of the tool, the ductility of the surface layer is lowered—local embrittlement—with periodic crack nucleation and propagation from this surface resulting in the segmented flow. In contrast, when the IPA action is tailored to create a highly effective lubricant film (most likely an alkoxide layer) on the chip under-surface in
the tool-chip contact region, the resulting lowering of the imposed forces suppresses plastic
buckling and sinuous flow. Instead laminar flow, with much smaller deformation strains,
results. The mechanochemical effect highlighted herein is shown to be strongly coupled to
the nucleation of the sinuous flow, distinguishing it from other flow and fracture phenomena
in surface plasticity such as liquid metal embrittlement and stress corrosion cracking.

The occurrence of different flow modes and flow transitions, and the coupling between
the mechanochemical effect and sinuous flow, are explained in the framework of plastic flow
stability. In this framework, the stability boundaries are altered by the action of the chemical
medium on the metal surface thereby creating conditions for crack nucleation or establishing
laminar flow. The work suggests interesting opportunities, exploiting the mechanochemical
effect, for much improved cutting of soft and highly strain-hardening metals like copper, iron,
nickel and stainless steels— materials often termed ‘gummy’ because of the difficulty involved
in their cutting.

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