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No Infinite Tail Beats Optimal Spatial Search

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Farhi and Gutmann (*Physical Review A*, **57**(4):2403, 1998) proved that a continuous-time analogue of Grover search (also called spatial search) is optimal on the complete graphs. We extend this result by showing that spatial search remains optimal in a complete graph even in the presence of an infinitely long path (or tail). If we view the latter as an external quantum system that has a limited but nontrivial interaction with our finite quantum system, this suggests that spatial search is robust against a coherent infinite one-dimensional probe. Moreover, we show that the search algorithm is *oblivious* in that it does not need to know whether the tail is present or not, and if so, where it is attached to.

I. INTRODUCTION

The celebrated quantum search algorithm of Grover [12] provides a provable quadratic speedup over any classical algorithm. Shortly thereafter, Farhi and Gutmann proposed an analogue analog of Grover's algorithm [8]. They defined the Grover search algorithm via a continuous-time quantum walk on a complete graph where the oracle or target vertex is marked by a suitably weighted self-loop. Remarkably, the Farhi-Gutmann algorithm achieved perfect fidelity on complete graphs of any size. In contrast, this property does not hold for Grover search (viewed as a discrete-time quantum walk) as it is inherently a bounded-error probabilistic algorithm.

This continuous-time search problem was later generalized by Childs and Goldstone [6] to arbitrary finite graphs where it is known as the *spatial search* problem. A collection of different families of finite graphs had been studied in this context; for example, see [4, 6, 9, 13, 19, 21]. But, to date, spatial search has not been studied on *infinite* graphs as it seems that the quantum walk will escape or diffuse to infinity before having a chance to localize on the marked vertex (or oracle). The goal of this work is to disabuse ourselves of this highly plausible intuition.

We consider infinite graphs which are obtained by attaching an infinite path (or tail) to a finite graph. This family of graphs with tails was explored by Golinskii [11]. In this work, we view the finite graph as our operational quantum system for performing quantum search and the tail as an external (possibly, adversarial) infinitedimensional quantum system which interacts with our finite system in a coherent manner.

The main question we explore in this work is: *can spatial search still be performed optimally in the presence of an infinite-dimensional probe?* We provide a positive answer to this question for complete graphs. This extends the result of Farhi-Gutmann [8] to the infinite setting. Moreover, the quantum search algorithm is *oblivious* as it does not need to know whether the infinite-dimensional probe is present (or not) and where it is attached to (if present). Since we give our adversary the benefit of an infinite-dimensional quantum system, this serves only to strengthen the result.

Our technique relies on the theory of Jacobi operators (see [7, 11]). The main idea is to decompose the adjacency operator A of our infinite graph using two pairwise orthogonal invariant subspaces (see Golinskii [11], Theorem 1.2) where the first one is finite-dimensional while the second one is infinite-dimensional. The next crucial observation is that spatial search takes place in the infinite-dimensional invariant subspace of A. Moreover, the action of A in this infinite-dimensional invariant subspace is given by a finite rank Jacobi matrix J. Finally, we show that the initial and target states of the spatial search are nearly confined in a two-dimensional subspace spanned by two *bound* states of J. This yields the claimed spatial search result. To the best of our knowledge, this is the first result which explores optimal spatial search on infinite graphs.

As outlined above, our argument is the standard argument for showing optimal spatial search in the finite setting (see [3–5]). Namely, we show that the initial and target states are spanned by two distinct eigenvectors of the perturbed adjacency matrix. A contribution of this work is to show that this argument holds in the infinite setting via bound states of the reduced adjacency operator. We believe that this argument might be useful in other settings.

Following a brief discussion of basic notation and terminology in Section II, we prove our main results in Sections III and IV. Then, we justify the optimality of our search algorithm in Section V. Finally, we conclude with some open questions in Section VI.

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II. PRELIMINARIES

We introduce the basic notation and terminology that we will use throughout. The set of all positive integers is denoted \mathbb{Z}^+ and the set of all complex numbers with unit modulus is denoted U(1). For vectors x, y where $x = \zeta y$, for some $\zeta \in U(1)$, we write $x \equiv y$. We adopt standard asymptotic notation: $o(f_n)$ denotes any function g_n so that $g_n/f_n \to 0$, $\mathcal{O}(f_n)$ denotes functions g_n for which g_n/f_n is bounded from above by a constant, and $\Omega(f_n)$ denotes functions g_n where g_n/f_n is bounded from below by a constant, where in each case $n \to \infty$; see [20]. In our case, the asymptotic parameter n corresponds to the size of a finite graph.

a. Graphs and operators. We study undirected and connected graphs G = (V, E) with vertex set V and edge set E, respectively. The adjacency matrix A of G is a symmetric matrix whose (i, j) entry is 1 if $(i, j) \in E$ and 0 otherwise. For a vertex u, let $N(u) = \{v \in V : (u, v) \in E\}$ denote the set of neighbors of u. The degree of vertex u, denoted deg(u), is the cardinality of N(u). The complete graph (or clique) on n vertices is denoted K_n . A rooted graph (G, r) is a graph G with a distinguished vertex r which we call the root. See [10] for further background on algebraic graph theory.

We allow countably infinite graphs, in which case, $V = \mathbb{Z}^+$ (see [16]). For example, the infinite path P_{∞} has edges which are consecutive positive integers; its adjacency matrix is known as the free Jacobi matrix (see [11]). Related to these graphs, we associate a complex separable Hilbert space $\mathcal{H} = \ell^2(V)$ equipped with the inner product $\langle x, y \rangle = \sum_{u \in V} \overline{x_u} y_u$, for vectors $x, y \in \mathcal{H}$. For $\ell^2(V)$, a standard basis is $\{e_u : u \in V\}$, where e_u is the unit vector corresponding to vertex u. An infinite graph \mathcal{G} is *locally finite* if deg $(u) < \infty$ for all $u \in V$. For such a graph \mathcal{G} , the adjacency operator A is a linear operator that maps the standard basis vector e_v to the vector associated with the neighboring vertices N(v); that is, $Ae_v = \sum_{u \in N(v)} a_{u,v} e_u$, or simply $a_{u,v} = \langle e_u, Ae_v \rangle$. Let $\deg(\mathcal{G}) = \sup\{\deg(u) : u \in V\}.$ If $\deg(\mathcal{G}) < \infty$, then the adjacency operator A is a bounded self-adjoint operator (see [15]).

The spectrum of a linear operator A is the set $\sigma(A)$ of all complex numbers λ where $\lambda I - A$ is not invertible. For a bounded and self-adjoint operator A, its spectrum can be classified further into the *point* spectrum $\sigma_p(A)$ and the *continuous* spectrum $\sigma_c(A)$. The point spectrum consists of all eigenvalues $\lambda \in \mathbb{C}$ of A such that $Ax = \lambda x$ for some nonzero $x \in \ell^2(V)$. On the contrary, the values in $\sigma_c(A)$ are not eigenvalues of A and have no corresponding eigenvectors in $\ell^2(V)$.

The spectral theorem (see [1, 17]) states that for a bounded self-adjoint operator A on a complex Hilbert space \mathcal{H} , there exists a unique resolution of the identity Eon the Borel subsets of $\sigma(A)$ so that $A = \int_{\sigma(A)} \lambda \ dE(\lambda)$. Moreover, if f is a bounded Borel function on $\sigma(A)$, then $f(A) = \int_{\sigma(A)} f(\lambda) \ dE(\lambda)$. We also use a decomposition induced by invariant subspaces (see [1], Theorem 3, section 40) which states that if W_k $(k = 1, 2, \dots, m)$ are pairwise orthogonal invariant subspaces of A, that is, $\mathcal{H} = \bigoplus_{k=1}^m W_k$ and $AW_k \subset W_k$, for each k, then $A = \sum_{k=1}^m A_k P_k$, where P_k is the projection on W_k and A_k is the restriction of A to W_k .

b. Spatial Search. A continuous-time quantum walk on an infinite graph \mathcal{G} with bounded self-adjoint adjacency operator A is given by the unitary operator e^{-itA} (acting on the Hilbert space $\ell^2(V)$). Our focus is on infinite graphs obtained from a finite connected rooted graph (G, r) by attaching an infinite path P_{∞} at the root vertex r; denote the resulting infinite graph as $\mathcal{G} = G(r, P_{\infty})$. As we use $\{1, 2, \ldots, n\}$ to label the vertices of a finite rooted graph of order n, we take the liberty to designate the last vertex n as the root (without loss of generality). These are the graphs with tails studied by Golinskii [11].

We say the infinite graph $\mathcal{G} = G_n(P_\infty)$ has optimal spatial search (adopting [4]) if there is a real $\gamma > 0$ so that for each vertex w of G_n , a continuous-time quantum walk on \mathcal{G} with a self-loop on w of weight γ will unitarily map the principal eigenvector z_1 of G_n to the unit vector e_w with constant fidelity in time $t = \mathcal{O}(1/\epsilon_1)$, where $\epsilon_1 = |\langle e_w, z_1 \rangle|$. That is,

$$\left| \langle e_w, e^{-it(A+\gamma P_w)} z_1 \rangle \right| = \Omega(1),$$

where A is the adjacency operator of \mathcal{G} and P_w is the projection onto the subspace spanned by e_w . It is customary to assume $\epsilon_1 = o(1)$ as otherwise we already have a constant overlap between the target state e_w and the initial state z_1 .

III. INFINITE LOLLIPOP IS OPTIMAL

For $n \geq 2$, consider the infinite *lollipop* graph $\mathcal{L}_n = K_n(P_\infty)$. The vertices of the infinite path P_∞ are labelled with $n+1, n+2, \ldots$ To this lollipop graph \mathcal{L}_n , we place a self-loop of weight γ at vertex 1 (the oracle or target vertex) and denote the resulting infinite graph as $\mathcal{L}_n(\gamma)$. Please see Figure 1.

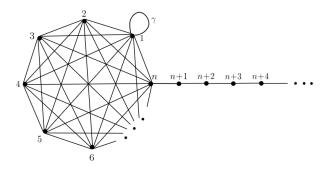


FIG. 1. Optimal spatial search on the infinite lollipop with the oracle hiding at vertex 1.

The adjacency operator H of $\mathcal{L}_n(\gamma)$ is obviously a bounded self-adjoint linear operator on $l^2(\mathbb{Z}^+)$. It can

be written as an infinite dimensional matrix under the standard basis $\{e_j\}_{j=1}^{\infty}$ as

$$H = \begin{pmatrix} \gamma & 1 & \cdots & 1 & & & \\ 1 & 0 & \cdots & 1 & & & \\ \vdots & \vdots & \ddots & \vdots & & & \\ 1 & 1 & \cdots & 0 & 1 & & \\ & & 1 & 0 & 1 & & \\ & & & & \ddots & \ddots & \ddots \end{pmatrix}.$$

Our goal is to prove the following infinite analogue of the Farhi-Gutmann result.

Theorem 1. For
$$\gamma = n + O(1)$$
, we have
 $|\langle e_1, e^{-itH} z_1 \rangle| = \Omega(1),$

for $t = \pi/2\sqrt{n}$, where $z_1 = n^{-1/2} \sum_{j=1}^n e_j$.

By a theorem of Golinskii ([11], Theorem 1.2), using a change of basis, H can be written in a block diagonal form. This new basis $\{\tilde{e}_k\}_{k=1}^{\infty}$ is defined as follows. Let

$$\tilde{e}_k = e_k, \quad k = n, n+1, \cdots \tag{1}$$

and

$$\tilde{e}_{n-1} = \frac{1}{\sqrt{n-1}} \sum_{j=1}^{n-1} e_j.$$
 (2)

The next orthogonal basis vector is then given by

$$\tilde{e}'_{n-2} = H\tilde{e}_{n-1} - \langle \tilde{e}_{n-1}, H\tilde{e}_{n-1} \rangle \tilde{e}_{n-1} - \langle \tilde{e}_n, H\tilde{e}_{n-1} \rangle \tilde{e}_n.$$

which, after normalization, yields

$$\tilde{e}_{n-2} = \frac{1}{\sqrt{(n-2)(n-1)}} ((n-1)e_1 - \tilde{e}_{n-1}).$$
 (3)

We take the remaining basis vectors to be the nonprincipal columns of the Fourier matrix of order n-2. In particular, the basis vector \tilde{e}_k is defined as

$$\tilde{e}_k = \frac{1}{\sqrt{n-2}} \sum_{j=1}^{n-2} e^{\frac{2\pi i (j-1)k}{(n-2)}} e_j \quad (k = 1, \dots, n-3).$$

Since $H\tilde{e}_{n-2} = \left(\gamma \frac{n-2}{n-1} - 1\right)\tilde{e}_{n-2} + \gamma \frac{\sqrt{n-2}}{n-1}\tilde{e}_{n-1}$, the subspace $S = \operatorname{span}\{\tilde{e}_{n-2}, \tilde{e}_{n-1}, \cdots\}$ is *H*-invariant. Under the new basis, the adjacency operator *H* becomes

$$H = \begin{pmatrix} -I_{n-2} & O \\ O & \widehat{H} \end{pmatrix}$$

As will be clear soon, it suffices for us to restrict our focus on the operator \hat{H} , which is the operator H restricted to the subspace $S = \text{span}\{\tilde{e}_{n-2}, \tilde{e}_{n-1}, \cdots\}$. This is because the initial state z_1 and the target state e_1 of our spatial search problem both have non-negligible overlap with S.

It follows from the preceding analysis that the operator H under the basis $\{\tilde{e}_{n-2}, \tilde{e}_{n-1}, \ldots\}$ is given by

$$\widehat{H} = \begin{bmatrix} \widetilde{e}_{n-2} \\ \widetilde{e}_{n-1} \\ \widetilde{e}_{n-1} \\ \widetilde{e}_{n+1} \\ \vdots \\ \vdots \\ \begin{pmatrix} \gamma \frac{n-2}{n-1} - 1 & \gamma \frac{\sqrt{n-2}}{n-1} & & \\ \gamma \frac{\sqrt{n-2}}{n-1} & n-2 + \frac{\gamma}{n-1} & \sqrt{n-1} & & \\ \gamma \frac{\sqrt{n-1}}{n-1} & 0 & 1 & & \\ & & 1 & 0 & 1 & \\ & & & \ddots & \ddots & \ddots \end{pmatrix}.$$
(4)

This symmetric tridiagonal matrix is an eventually-free or finite rank Jacobi matrix (see [11]) whose full spectrum can be computed via the so-called Jost solution (see [7], Appendix). The Jost solution is a vector y(x) = $(y_1(x), y_2(x), \cdots)^T$ that satisfies the eigen-equation of \hat{H} with eigenvalue of the form $x + \frac{1}{x}$, namely,

$$\widehat{H}y(x) = \left(x + \frac{1}{x}\right)y(x),\tag{5}$$

and also the degree condition

$$\lim_{k \to \infty} x^{-k} y_k(x) = 1.$$

Given the special form of \widehat{H} , we can set

$$y_k(x) = x^k, \quad k = 3, 4, \cdots,$$
 (6)

and use (5), to get the Jost polynomial

$$y_0(x) = \frac{1}{\gamma} \sqrt{\frac{n-1}{n-2}} \cdot \left[(2-n)x^4 + \left[(n-3)\gamma + 4 - 2n \right] \right] x^3 + \left[(n-3)\gamma + 5 - 2n \right] x^2 + \left[3 - n - \gamma \right] x + 1 \right].$$
(7)

In order to compute the eigenvalues of \hat{H} , we need the following spectral theorem for finite rank Jacobi operators. We will only need information about the point spectrum as will be clear soon.

Theorem 2. ([11], p8) Let J be an eventually-free Jacobi matrix and $y_0(x)$ be its Jost function. Then all roots of $y_0(x)$ in the complex unit disk are real and simple, $y_0(0) \neq 0$. A real number λ_j is an eigenvalue of J if and only if

$$\lambda_j = x_j + \frac{1}{x_j}, \quad x_j \in (-1, 1), \quad y_0(x_j) = 0.$$

By choosing $\gamma = n + \mathcal{O}(1)$, the roots of $y_0(x)$ in the complex unit disk can be approximated consecutively. First note that there are four real roots for $y_0(x)$ and two of them lie in the unit disk as indicated by the following table:

Denote the two roots within the unit disk as $x_{\pm} = \frac{1}{n} + \delta_{\pm}$. Hence,

$$0 = \gamma \sqrt{\frac{n-2}{n-1}} \cdot y_0(x_{\pm}) = -\frac{1}{n} + n^2 \delta_{\pm}^2 + o\left(\frac{1}{n}\right) + o(n^2 \delta_{\pm}^2).$$

TABLE I. For $\gamma = n + \mathcal{O}(1)$ and sufficiently large n, there are 4 sign changes of $y_0(x)$.

In order for the left-hand side to attain 0 exactly, for all n, at least the two highest order terms on the right-hand side should cancel perfectly; that is, $o(\frac{1}{n}) = -\frac{1}{n} + n^2 \delta_{\pm}^2$ which implies

$$x_{\pm} = \frac{1}{n} \pm \frac{1}{n^{3/2}} + o\left(\frac{1}{n^{3/2}}\right).$$
 (8)

Therefore, the two distinct eigenvalues of \widehat{H} are given by

$$\lambda_{\pm} = n \pm \sqrt{n} + \mathcal{O}(1). \tag{9}$$

The corresponding eigenvectors (or bound states) are given by $y_{\pm} = (y_1(x_{\mp}), y_2(x_{\mp}), \ldots)^T$ where the entries are defined by the Jost polynomials

$$y_1(x_{\mp}) = \pm \frac{1}{\gamma} \sqrt{\frac{n-1}{n-2}} \cdot \frac{1}{n^{3/2}} + \mathcal{O}\left(\frac{1}{n^3}\right), \tag{10}$$
$$y_2(x_{\mp}) = \frac{1}{\sqrt{n-1}} \cdot \frac{1}{n^2} \mp \frac{1}{\sqrt{n-1}} \frac{2}{n^{5/2}} + \mathcal{O}\left(\frac{1}{n^{7/2}}\right),$$

$$\sqrt{n-1} \quad n \quad \sqrt{n-1} \quad (n \neq j) \tag{11}$$

$$y_k(x_{\mp}) = \frac{1}{n^k} \mp \frac{\kappa}{n^{(2k+1)/2}} + \mathcal{O}\left(\frac{1}{n^{k+1}}\right), \quad k = 3, 4, \cdots$$
(12)

Now, we are ready to prove Theorem 1.

First, note that both $e_1 = \sqrt{\frac{1}{n-1}}\tilde{e}_{n-2} + \sqrt{\frac{n-2}{n-1}}\tilde{e}_{n-1}$ and $z_1 = \tilde{e}_{n-1}$ are completely in the invariant subspace S. Thus, we can restrict our unitary evolution to S. Moreover, as e_1 overlaps almost completely with \tilde{e}_{n-1} , it suffices to consider \tilde{e}_{n-1} as the target state. Hence, the fidelity can be further approximated as

$$\left|\langle e_1, e^{-itH} z_1 \rangle\right| \ge \sqrt{\frac{n-2}{n-1}} \left|\langle \overline{e}_1, e^{-it\widehat{H}} \overline{e}_2 \rangle\right| + \mathcal{O}\left(\frac{1}{n^{1/2}}\right),$$

where \overline{e}_k is a unit vector which is the k-th basis vector for the invariant subspace $S = \text{span}\{\tilde{e}_{n-2}, \tilde{e}_{n-1}, \cdots\}$.

Notice that

$$\lim_{n \to \infty} \frac{\langle \overline{e}_k, y_+ \rangle \langle y_+, \overline{e}_k \rangle}{\langle y_+, y_+ \rangle} + \frac{\langle \overline{e}_k, y_- \rangle \langle y_-, \overline{e}_k \rangle}{\langle y_-, y_- \rangle} = 1, \quad k = 1, 2,$$

that is, both the initial and the target states lie in the two-dimensional invariant subspace spanned by the eigenvectors y_+ and y_- . Thus, it again suffices to consider the fidelity in this subspace.

Straightforward calculation shows that when $\gamma = n + \mathcal{O}(1)$, the fidelity satisfies $|\langle e_1, e^{-itH}z_1\rangle| = 1 + o(1)$ for time $t = \frac{\pi}{2\sqrt{n}}$. If we normalize the adjacency matrix of K_n , we obtain $\mathcal{O}(\sqrt{n})$ time (matching Grover search).

IV. ORACLE AT THE EDGE OF INFINITY

In this section, we show that even when the oracle is placed at the attachment vertex of the infinite path, spatial search remains optimal on \mathcal{L}_n . See Figure 2.

Together with Section III, this will show that the search algorithm is *oblivious* as it does not need to know if the external probe (tail) is present or not. This is because the two cases surprisingly require the same asymptotic time for optimal spatial search. The claim follows from a similar analysis as before.

The adjacency operator of $\mathcal{L}_n(\gamma)$ is given as

$$H = \begin{pmatrix} 0 & 1 & \cdots & 1 & & & \\ 1 & 0 & \cdots & 1 & & & \\ \vdots & \vdots & \ddots & \vdots & & & \\ 1 & 1 & \cdots & \gamma & 1 & & \\ & & 1 & 0 & 1 & & \\ & & & 1 & 0 & 1 & \\ & & & & \ddots & \ddots & \ddots \end{pmatrix}.$$

First, we restrict our focus to the invariant subspace $S = \operatorname{span}\{\tilde{e}_{n-1}, \tilde{e}_n, \cdots\}$ since $e_n = \tilde{e}_n \in S$ and $z_1 = \sqrt{\frac{n-1}{n}}\tilde{e}_{n-1} + \sqrt{\frac{1}{n}}\tilde{e}_n \in S$, where $\tilde{e}_{n-1} = \frac{1}{\sqrt{n-1}}\sum_{j=1}^{n-1}e_j$ and $\tilde{e}_k = e_k, k \ge n$. Under the new basis that spans S, the operator H is a rank-2 Jacobi matrix

$$\widehat{H} = \frac{\widetilde{e}_{n-1}}{\widetilde{e}_n} \begin{pmatrix} n-2 & \sqrt{n-1} & & \\ \sqrt{n-1} & \gamma & 1 & & \\ & 1 & 0 & 1 & \\ & & \ddots & \ddots & \ddots \end{pmatrix}.$$
(13)

Hence, the following Jost polynomials are obtained:

$$y_0(x) = \frac{1}{\sqrt{n-1}} \cdot [-\gamma x^3 + (n-2)(\gamma - 1)x^2 + (2-n-\gamma)x + 1], \quad (14)$$

$$y_1(x) = \frac{1}{\sqrt{n-1}} \cdot (x - \gamma x^2),$$
 (15)

$$y_k(x) = x^k, \quad k = 2, 3, \cdots.$$
 (16)

By choosing $\gamma = n + \mathcal{O}(1)$, we can compute the two distinct roots for y_0 that is within the interval [-1, 1]

$$x_{\pm} = \frac{1}{n} \pm \frac{1}{n^{3/2}} + o\left(\frac{1}{n^{3/2}}\right),\tag{17}$$

which yields the corresponding eigenvalues for H

$$\lambda_{\pm} = n \pm \sqrt{n} + \mathcal{O}(1). \tag{18}$$

As shown previously, the corresponding eigenvectors are

defined by the values of Jost polynomials:

$$y_1(x_{\mp}) = \pm \frac{1}{\sqrt{n-1}} \cdot \frac{1}{n^{3/2}} + \mathcal{O}\left(\frac{1}{n^{5/2}}\right) \tag{19}$$

$$y_2(x_{\mp}) = \frac{1}{n^2} \mp \frac{2}{n^{5/2}} + \mathcal{O}\left(\frac{1}{n^3}\right)$$
 (20)

$$y_k(x_{\mp}) = \frac{1}{n^k} \mp \frac{k}{n^{(2k+1)/2}} + \mathcal{O}\left(\frac{1}{n^{k+1}}\right), \quad k = 3, 4, \cdots$$
(21)

Following the same argument, we can see that for time $t = \frac{\pi}{2\sqrt{n}}$, the fidelity satisfies $|\langle e_n, e^{-itH}z_1 \rangle| = 1 + o(1)$.

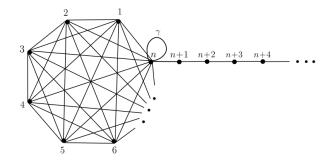


FIG. 2. Optimal spatial search still occurs on the infinite lollipop even if the oracle sits at gateway vertex n.

V. OPTIMALITY

We show that the time bound obtained in Theorem 1 (and in Section IV) is optimal. To this end, we generalize an argument of Farhi and Gutmann [8] to a class of infinite graphs with tails.

For a finite graph G_n on n vertices, take the cone $\widehat{G}_n = K_1 + G_n$ which is obtained by adding a new vertex (called the conical vertex) and connecting it to all vertices of G_n . Then, attach a tail to the conical vertex and denote this infinite graph as $\widehat{G}_n(P_\infty)$. Notice that we recover the infinite lollipop when G_n is a clique.

Theorem 3. Let G_n be a (n,d)-regular graph, where $d = \omega(\sqrt{n})$ for some $\delta > 0$, and let \mathcal{H}_0 be the adjacency operator of $\widehat{G}_n(P_\infty)$. Let $z_1 \in \ell^2$ being natural embedding of the principal eigenvector of G_n . Suppose there is a time t_0 so that for some $\gamma \in \mathbb{R}$ and $\zeta \in U(1)$, and for a vertex w of G_n , we have

$$\left\| e^{-it_0(\mathcal{H}_0 + \gamma P_w)} z_1 - \zeta e_w \right\|^2 = o(1).$$

Then, $\gamma t_0 = \Omega(1/\epsilon_1)$, where $\epsilon_1 = |\langle e_w, z_1 \rangle|$, provided $1/\gamma \epsilon_1 \in o(1)$.

The largest eigenvalue in $\sigma_p(\mathcal{H}_0)$ has a unique bound eigenstate β_1 which satisfies $\|\beta_1 - z_1\| = o(1)$. This can be shown using similar techniques as in previous sections. We call a time-dependent state $\psi(t) \in \ell^2(\mathbb{Z}^+)$ exponentially decaying if there is a positive integer M so that for all $m \geq M$ we have $|\langle e_m, \psi(t) \rangle| = \mathcal{O}(\kappa^m)$, for some $\kappa < 1$, for all t.

Proof. (of Theorem 3) Let $\mathcal{H}_w = \mathcal{H}_0 + \gamma P_w$. It suffices to show the claim under the assumption $\|e^{-it\mathcal{H}_w}\beta_1 - \zeta e_w\|^2 = o(1)$, since $\|\beta_1 - z_1\| = o(1)$ and by using the triangle inequality for squared norm (see [18], eq. 18.5).

Following [8], we compare two Schrödinger evolutions given by

$$\begin{aligned} \psi'_w(t) &= -i\mathcal{H}_w\psi_w(t), \qquad \psi_w(0) = \beta_1, \\ \psi'_0(t) &= -i\mathcal{H}_0\psi_0(t), \qquad \psi_0(0) = \beta_1. \end{aligned}$$

Note $\psi_0(t) \equiv \beta_1$, for all t, as β_1 is an eigenstate of \mathcal{H}_0 .

For simplicity, we assume that spatial search achieves perfect fidelity, namely, $\psi_w(t_0) \equiv e_w$. The general case is handled using triangle inequality for squared norm.

The key quantity is $M(t) := \|\psi_w(t) - \psi_0(t)\|^2$. First, notice that

$$M(t_0) = 2(1 - \operatorname{Re}\langle e_w, \beta_1 \rangle) \ge 2(1 - \epsilon_1).$$
 (22)

Furthermore, we have $M'(t) = -2 \operatorname{Re} \langle \psi_w(t), \psi_0(t) \rangle'$. Given that the inner product is an infinite series, the existence of its derivative requires uniform convergence. As $\psi_0(t) \equiv \beta_1$ is exponentially decaying (by virtue of being a Jost solution), we have $|\overline{(\psi_w(t))_m}(\beta_1)_m| \leq |(\beta_1)_m|$ and

$$\sum_{m=1}^{\infty} |(\beta_1)_m| \le C_M + \sum_{m \ge M} \kappa^m = C_M + \frac{\kappa^M}{1-\kappa} < \infty$$

for a constant C_M . Thus, $\langle \psi_w(t), \beta_1 \rangle$ is uniformly convergent (see Titchmarsh [20], 1.11).

Since \mathcal{H}_w is a finite-rank Jacobi matrix and $\psi'_w(t) = -i\mathcal{H}_w\psi_w(t)$, we see that $\langle \psi'_w(t), \psi_0(t) \rangle$ is also uniformly convergent. This allows us to take the derivative of $\langle \psi_w(t), \psi_0(t) \rangle$ by termwise differentiation (see Titchmarsh [20], 1.72), *i.e.*,

$$\begin{aligned} \langle \psi_w(t), \psi_0(t) \rangle' &= \langle \psi_w(t), \psi'_0(t) \rangle + \langle \psi'_w(t), \psi_0(t) \rangle \\ &= -i \langle \psi_w(t), \mathcal{H}_0 \psi_0(t) \rangle + i \langle \mathcal{H}_w \psi_w(t), \psi_0(t) \rangle \end{aligned}$$

So, we obtain

$$M'(t) = 2\gamma \mathrm{Im} \langle P_w \psi_w(t), \psi_0(t) \rangle \le 2\gamma \left\| P_w \psi_0(t) \right\|.$$

Thus, $M'(t) \leq 2\gamma \epsilon_1$, which further implies

$$M(t_0) = \int_0^{t_0} M'(t)dt \le 2\gamma\epsilon_1 t_0.$$

By combining the lower and upper bounds on $M(t_0)$, we get $\gamma t_0 \ge (1 - \epsilon_1)/\epsilon_1 = \Omega(1/\epsilon_1)$ as $\epsilon_1 = o(1)$.

Theorem 3 justifies the optimal time $1/\epsilon_1$ used to define spatial search. For the infinite lollipop, we have $\epsilon_1 = 1/\sqrt{n}$, and thus, $\gamma t_0 = \Omega(\sqrt{n})$. Since the search algorithm uses $\gamma = n + \mathcal{O}(1)$, we get $t_0 = \Omega(1/\sqrt{n})$, which matches the bound achieved by Theorem 1. Hence, the algorithm is optimal.

VI. CONCLUSION

In this work, we proved optimal spatial search occurs on cliques even in the presence of an infinite path. This generalized a known result of Farhi and Gutmann [8] to the infinite setting. We view this as a first step in showing that optimal spatial search is robust against an adversary modeled as an infinite-dimensional external quantum probe. Interesting directions for future work include extending the result to multiple tails or to tails induced by more general Jacobi matrices and strengthening the lower bound to other families of infinite graphs.

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Our work was motivated by a question posed in [2]. We mention that discrete-time quantum walk on graphs with tails was studied in [14].

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